Topos theoretic aspects of semigroup actions Jonathon Funk and Pieter Hofstra October 26, 2009

Abstract

We define the notion of a torsor for an inverse semigroup, which is based on partial actions of a semigroup, and prove that this is precisely the structure classified by the topos associated with an inverse semigroup. Unlike in the group case, not all set-theoretic torsors are isomorphic: we shall give a complete description of the category of torsors. We explain how a semigroup homomorphism gives rise to an adjunction between a restrictions-of-scalars functor and a tensor product functor, which we relate to the theory of covering spaces and E-unitary semigroups. We also interpret for semigroups the Lawvereproduct of a sheaf and distribution, and finally, we indicate how the theory might be extended to general semigroups, by defining a notion of torsor and a classifying topos for those.

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1 Introduction

1.1 Motivation

Lawson [9] explains that one should regard inverse semigroups as describing *partial symmetries* of mathematical structures, in the same way as groups may be used to describe global symmetries of objects. The inverse semigroup of partial isomorphisms of, say, a topological space is more informative than just the automorphism group: two spaces may have the same global automorphisms, but different partial automorphisms.

It has recently become clear that there is an interesting and useful connection between inverse semigroups and topos theory [4, 5, 8]. Explicitly, for each inverse semigroup S there is a topos $\mathscr{B}(S)$, called the *classifying topos* of S, defined as the category of equivariant sheaves on the associated inductive groupoid of S. This topos is equivalent to the category of presheaves on the (total subcategory of) the idempotent splitting of S. It turns out that many results and in semigroup theory have a natural interpretations in topos theoretic terms. For instance, it is known that cohomology of an inverse semigroup (Loganathan-Lausch [11]), Morita equivalence of inverse semigroups, the maximum group image, E-unitary inverse semigroups, and even McAlister's P-theorem have natural and canonical topos interpretations.

The notion of a partial action of a semigroup on an object X (sometimes called a semigroup action, e.g., Exel [3]) goes back at least to the basic representational result in the subject, namely the well-known Wagner-Preston theorem. In fact, there are several related notions, and in this paper, we shall consider a mild, but useful generalization, namely prehomomorphisms $S \longrightarrow I(X)$, where I(X) denotes the symmetric inverse semigroup on X. We shall refer to the case where $S \longrightarrow I(X)$ is a homomorphism, which is the notion featured in the Wagner-Preston theorem, as a strict partial action.

The main question we answer is the following: what does the classifying topos of an inverse semigroup actually classify? Put in different terms: what is an S-torsor? We shall see that it is a non-empty object equipped with a partial action of S that is transitive and locally free. The theory of semigroup torsors generalizes the group case, but as we shall see it is 'finer' than that of group torsors and, even in the set-theoretic setting provides a useful invariant of semigroups.

On a more general level, the paper aims at unifying three viewpoints of partial actions by an inverse semigroup: the aforementioned partial actions, covariant Set-valued functors, and finally, one may consider distributions on the topos $\mathscr{B}(S)$ in Lawvere's sense [2, 10]: thinking of $\mathscr{B}(S)$ as a 'space' associated with S, the distributions may be thought of as measures on this space. Our goal is to give a self-contained exposition of the three perspectives, including how to pass between them and to illustrate this with some key examples.

1.2 Overview

We now describe the contents of the paper. We have tried to make the paper accessible to anyone with a basic familiarity with the language of category theory. At times, some topos-theoretic concepts will be used without definition; in those cases we will provide references. The first section, which describes partial actions and torsors in elementary terms, does not require any knowledge of topos theory.

After quickly reviewing some of the basic theory of inverse semigroups, the goal of § 2 is to give an exposition of the elementary notion of a partial action of an inverse semigroup in a set. In fact, we identify three related notions depending on the strictness of the action, as well as two different notions of morphism, thus giving rise to various categories of representations. We mention a number of key examples, such as the well-known Wagner-Preston and Munn representations. Then we introduce the notion of a torsor as a special kind of representation. We confine ourselves to proving only a couple of elementary facts here, leaving a more conceptual investigation for the next section. Finally, we study partial actions and torsors in categories different from Set, in particular in (pre)sheaf toposes.

§ 3 begins by reviewing the classifying topos $\mathscr{B}(S)$ of an inverse semigroup S. Our main goal is to relate the notions of partial actions by S to certain classes of functors on L(S). In particular, we will obtain an equivalence of categories between the category of S-sets and the category of what we term torsion-free functors on L(S) (valued in Set). This equivalence specializes to one between strict S-sets and pullback-preserving functors, and ultimately between torsors and filtering functors. The latter result gives the desired statement that $\mathscr{B}(S)$ indeed classifies S-torsors in our sense. By general considerations, $\mathscr{B}(S)$ must therefore contain a generic torsor; we shall show that this is none other than the well-known object of Schutzenberger representations. Finally, we give a complete characterization of all set-theoretic torsors. For the group case, this trivializes, since all torsors are isomorphic,

but an inverse semigroup may have non-isomorphic torsors. We give an explicit description of how every S-set, and in particular every torsor, arises as a colimit of *principal torsors*.

In § 4 we explore some aspects of change of base, i.e., how the categories of S-sets and T-sets are related when S and T are connected by a (pre)homomorphism ρ . We first explain how the usual hom-tensor adjunction arises; this essentially follows from the fact that S-sets form a cocomplete category. The only non-evident part here is that, unlike in the group case, coequalizers are not created by the forgetful functor to sets. After that we explicitly calculate the tensor product of torsors; this amounts to unraveling a colimit-extension, but the end result is a bit more complicated than for groups, since the category over which the colimit is taken has more than one object. We apply this to the case of the homomorphism $S \longrightarrow S/\sigma$, the maximum group image of S, and obtain a characterization of E-unitary inverse semigroups: S is E-unitary if and only if its category of torsors is left-cancellative. Finally, we observe that every S-torsor in Sh(B) (which one might call a principal S-bundle) may be completed to a principal S/σ bundle, in the sense that there is a canonical map from the bundle to its completion, which is injective when S is E-unitary.

§ 5 is concerned with the third perspective on partial actions, namely as distributions on the topos $\mathscr{B}(S)$. We recall the definition of distribution, establish a few elementary but useful facts, and establish correspondences between S-sets and torsion-free distributions, and between strict S-sets and what we coin S-distributions. Of course, torsors correspond to left exact distributions, which are the points of $\mathscr{B}(S)$. We explicitly describe some of the leading examples of S-sets in terms of distributions, and also interpret the so-called Lawvere action of $\mathscr{B}(S)$ in its category of distributions.

Finally, § 6 sketches an approach to a generalization of the subject matter. For a general semigroup T, the topos of presheaves on a category L(T) is not necessarily appropriate as its classifying topos mainly because of fact that general semigroups need not have enough idempotents, or indeed any idempotents at all. Instead, we propose a classifying topos for a general semigroup which plays the same topos-theoretic role as $\mathscr{B}(S)$ does in the inverse case: it classifies torsors. The definition of a semigroup-torsor is straightforward, and for semigroup-torsor pairs it is geometric. The classifying topos for T is obtained by pulling back the topos classifier of semigroup-torsor pairs along the point of the semigroup classifier corresponding to T.

2 Partial actions: basic theory

In this section we introduce our basic objects of study, namely partial actions by an inverse semigroup and torsors. We review some basic inverse semigroup theory in order to establish some terminology and notation, recall the definition of a partial action by an inverse semigroup, and give some examples. We also discuss strict and non-strict morphisms between such objects and establish some elementary results. We define torsors for an inverse semigroup, give some examples, and make some basic observations about maps between torsors. Finally, we show how the notion of torsor makes sense in an arbitrary topos.

2.1 Background on inverse semigroups

A semigroup S is said to be *inverse* when for every $x \in S$ there exists a unique x^* for which $xx^*x = x$ and $x^*xx^* = x^*$. A canonical example is the inverse semigroup I(X) of partial injective functions from a set X to itself (this is in fact an inverse monoid). More generally, for many mathematical structures it makes sense to consider all partial isomorphisms from that structure to itself, and the collection of those will form an inverse semigroup.

Elements of the form x^*x and of the form xx^* are evidently idempotent; in fact, all idempotents are of this form. (It is helpful to think of x^*x as the domain of x, and of xx^* as the range.) The subset of S on the idempotents will be denoted by E(S), or simply by E, when S is understood. The set E is in fact endowed with a partial order and binary meets, given by multiplication. In general, it has neither a largest nor a smallest element. In the example S = I(X), the lattice of idempotents is simply the powerset of Xwith its usual lattice structure.

The well-known partial order in S, which contains E as a subordering, is given by $x \leq y$ iff $x = yx^*x$.

We shall consider two notions of morphism between inverse semigroups, homomorphism and prehomomorphism. The weaker notion *prehomomorphism* is a function $\rho : S \longrightarrow T$ between inverse semigroups which satisfies $\rho(xy) \leq \rho(x)\rho(y)$. If for all elements x, y we actually have equality, then ρ is a *homomorphism*. It is well-known that a (pre)homomorphism automatically preserves the involution, i.e. that $\rho(x^*) = \rho(x)^*$. Moreover, any (pre)homomorphism preserves the natural ordering, and sends idempotents to idempotents. For more information and explanation concerning these basic concepts, we refer the reader to Lawson's textbook [9].

2.2 Actions of inverse semigroups

We now turn to partial actions by an inverse semigroup.

Definition 2.1 An *S*-set is a set *X* and a prehomomorphism $S \xrightarrow{\mu} I(X)$, sometimes written (X, μ) . For any $s \in S$ and $x \in X$, we write $s \cdot x$, or sometimes just sx, to mean $\mu(s)(x)$ when defined. Then $\mu(st) \leq \mu(s)\mu(t)$ reads (st)x = s(tx) for all x, which means that if (st)x is defined then so are tx and s(tx) and the given equality holds. An *S*-set (X, μ) is said to be strict when μ is a homomorphism.

For any $e \in E$, $\mu(e)$ is an idempotent of I(X), which amounts to a subset of X that we denote eX. The expression " $x \in eX$ " simply means that exis defined (and ex = x). With this notation we may write the partial map $\mu(s): X \to X$ as



where $e = s^*s$.

Let us consider some examples of S-sets.

Example 2.2 A canonical example of an S-set is the Munn representation [9] of an inverse semigroup S. This is a well-supported S-set $S \longrightarrow I(E)$ such that $s \cdot e$ is defined iff $e \leq s^*s$, in which case $s \cdot e = ses^*$. For any e, we have $eE = \{d \mid d \leq e\}$. The Munn representation is closely related to the Wagner-Preston representation. This is the S-set $S \longrightarrow I(S)$ such that $s \cdot t$ is defined iff $t = s^*st$, in which case $s \cdot t = st$. For any idempotent e, we have $eS = \{t \mid t = et\}$. The Munn and Wagner-Preston S-sets are strict S-sets in the sense of Def. 2.1.

Example 2.3 A prehomomorphism of inverse semigroups $S \xrightarrow{\rho} T$ may be construed as an S-set, not strict in general, by restricting the Wagner-Preston T-set to S. Let T_{ρ} denote this S-set: $s \cdot t$ is defined iff $t = \rho(s^*s)t$, in which case $s \cdot t = \rho(s)t$.

Example 2.4 Of course, every inverse semigroup S acts in itself by multiplication; this action is total and as such is an example of a strict S-set. However, it turns out that when we view this as a right action, it is naturally related to the so-called Schutzenberger object (1). We shall return to this in § 3.1.

In general, there may of course be several different actions of S in a given set X; we may say, for two such actions μ, ν , that ν extends μ whenever $\mu(s) \leq \nu(s)$ for all $s \in S$. When $X = \{x\}$ is a singleton, then it is easily seen that an action μ of S in X is determined by specifying an ideal $I \subseteq E$, namely $I = \{e \in E \mid ex = x\}$. The terminal S-set is then the singleton set in which S acts totally.

Definition 2.5 A morphism of S-sets $(X, \mu) \longrightarrow (Z, \sigma)$ is a map $\psi : X \longrightarrow Y$ such that for all s and x, if sx is defined, then so is $s\psi(x)$ and $\psi(sx) = s\psi(x)$ holds. Of course, it may happen that $s\psi(x)$ is defined when sx is not. If indeed this does not occur, then we say that ψ is a strict morphism.

Example 2.6 The Wagner-Preston and Munn representations (Eg. 2.2) are related by the range map $S \longrightarrow E$, $s \mapsto ss^*$, which is a strict morphism of *S*-sets.

An S-set (X, μ) may also be regarded as a partial map

$$\mu: S \times X \twoheadrightarrow X$$

in which case a morphism of S-sets (i.e., an equivariant map) is a map ψ : $X \longrightarrow Y$ such that the square

of partial maps commutes on the nose when ψ is strict, and commutes up to inequality $\psi \mu \leq \sigma(S \times \psi)$ otherwise.

When X is an S-set, then we say that an element $x \in X$ is supported by an idempotent $e \in S$, or that e is in the support of x, when $x \in eX$. Since mostly we are not interested in unsupported elements of an S-set, we introduce the following terminology. **Definition 2.7** An S-set (X, μ) is well-supported if $X = \bigcup_E eX$.

In any case, if an S-set X is not well-supported, then we can replace it with the well-supported S-set $\bigcup_{e \in E} eX$.

Let S-Set denote the category of well-supported S-sets and their morphisms. Of course this includes, but is not limited to, the strict morphisms. The full subcategory of S-Set on the strict, well-supported S-sets is denoted $\underline{S-Set}$.

2.3 Torsors

Having defined strict and general S-sets, we now turn to torsors. Recall that for a group G, a G-torsor X (in Set) is a non-empty G-set for which the action is free and transitive. We will generalize this in the appropriate way to the case of an inverse semigroup, and then explore some examples.

Definition 2.8 A well-supported S-set (X, μ) is an S-torsor if:

- 1. X is non-empty;
- 2. μ is transitive for any $x, y \in X$, there are $s, t \in S$ and $z \in X$ such that sz = x and tz = y;
- 3. μ is locally free for any x and s, t such that sx = tx, there is $r \in S$ and $y \in X$ such that ry = x and sr = tr.

We denote the full subcategory of S-Set on the torsors by TOR(S).

- 1. In the inverse case, transitive is equivalent to the following: for any $x, y \in X$, there is $s \in S$ such that sx = y.
- 2. In the inverse case, locally free is equivalent to the following: for any x and s, t such that sx = tx, there is an idempotent d such that $x \in dX$ and sd = td.

Moreover, without loss of generality it can be assumed in the locally free requirement that $d \leq s^*s, t^*t$ because otherwise replace d by $e = ds^*st^*t$, noting $eX = dX \cap s^*sX \cap t^*tX$.

In the case of a group G, every set-theoretic torsor is isomorphic to the group G itself. In the inverse semigroup case, this is no longer true, as illustrated by the following example.

Example 2.9 If X is a non-empty set, then X is an I(X)-torsor (where of course I(X) acts in X via $f \cdot x = f(x)$). It is clear that this action is transitive; but it is also locally free since if $f \cdot x = g \cdot x$ then f and g agree on the domain $\{x\}$.

At the other end of the spectrum we have the case of meet-semilattices:

Example 2.10 We determine the torsors on an \wedge -semilattice D when regarded as an inverse semigroup such that $ab = a \wedge b$ and $a^* = a$. A strict S-set $D \longrightarrow I(X)$ amounts to an action of D in X by partial identities, and such that $aX \cap bX = abX$. If such an action is a torsor, then by transitivity, and since $X \neq \emptyset$, X must be a one-element set. On the other hand, an S-set $D \longrightarrow \{0 \leq 1\} = I(1)$ is necessarily a torsor. In turn, these correspond to ideals of D (up-closed and closed under binary \wedge), and whence to points of the presheaf topos PSh(D). Thus, D-torsors in the sense of Def. 2.8 coincide with the usual meaning of torsor on an \wedge -semilattice (filtering functor on D) [6].

As a final example, here is a torsor for which the action is total:

Example 2.11 Let S/σ be the maximum group of S. Then S acts in S/σ via left multiplication. This action is transitive and free, so S/σ is a torsor. In fact, one may show that if X is an S-torsor for a total action, then $X \cong S/\sigma$.

The last example makes precise the sense in which torsors are a more general invariant of S than the maximum group. We will give a structure theorem for general torsors in § 3.4. For now we note a result that is a straightforward generalization of the group case, namely that morphisms of torsors are necessarily isomorphisms:

Proposition 2.12

- 1. An isomorphism of S-sets is strict.
- 2. A strict morphism of S-torsors is an isomorphism.
- 3. Any map of torsors is an epimorphism in S-Set.

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Proof. 1. Suppose that $X \xrightarrow{\alpha} Y$ is an isomorphism of S-sets with inverse β . If $s\alpha(x)$ is defined, then so is $\beta(s\alpha(x))$. Hence $s\beta\alpha(x) = sx$ is defined, so α is strict.

2. Suppose that X and Y are torsors, and that α is strict. To see that α is surjective, let $y \in Y$. Choose any $x_0 \in X$, which is possible since torsors are non-empty. By transitivity of Y, there is $s \in S$ such that $s\alpha(x_0) = y$. By strictness, sx_0 is defined, and $\alpha(sx_0) = y$. To see that α is injective, suppose that $\alpha(x) = \alpha(z), x, z \in X$. By transitivity of X, there is s such that sx = z. Hence, $s\alpha(x) = \alpha(sx) = \alpha(z) = \alpha(x) = s^*s\alpha(x)$. By the freeness of Y, there is an idempotent $e \leq s^*s$ such that $se = s^*se = e$, and $\alpha(x) \in eX$. By the strictness of $\alpha, x \in eX$, and hence z = sx = sex = ex = x.

3. It is easily verified that if two maps $\alpha, \beta : X \longrightarrow Y$ of S-sets, where X is transitive, agree on an element of X, then $\alpha = \beta$. The result follows immediately.

Corollary 2.13 TOR(S) is an essentially small right-cancellative category.

Proof. $\operatorname{TOR}(S)$ is essentially small because every torsor X admits a surjection $S \longrightarrow X$, $s \mapsto sx$, where x is a fixed element of X. $\operatorname{TOR}(S)$ is right-cancellative by 2.12, 3.

2.4 Internal partial actions

So far we have been working in the category of sets. But as we know from the group case, the theory of torsors becomes much more potent and applicable when we consider it in other categories, such as categories of sheaves. In this section we briefly indicate how to define torsors diagrammatically, and give some examples of torsors in categories other than *Set*.

First of all, it is clear that the notion of a partial action makes sense in any category with finite limits. Then the definition of an internal torsor is easily obtained:

Definition 2.14 If S is a semigroup in a topos \mathscr{E} , then a well-supported (meaning p below is an epimorphism) S-set (X, μ) in \mathscr{E}



is an S-torsor if:

- 1. $X \longrightarrow 1$ is an epimorphism;
- 2. μ is transitive consider the kernel pair of p (pullback).



Then μ is transitive if the map $\langle \mu \pi_1, \mu \pi_2 \rangle : H \longrightarrow X \times X$ is an epimorphism;

3. μ is locally free - consider the following two pullbacks and equalizer.



In the equalizer, (k, u) is an element of M. Then by definition μ is locally free if the restriction of g(k, u) = k to the equalizer N is an epimorphism.

If S is a semigroup in the topos $\mathscr{E} = Set$, then Defs. 2.8 and 2.14 are equivalent. For instance, when interpreted as a sentence in first order logic, the locally free requirement in Def. 2.14 states

$$\forall s, t \in S, x \in X \ (sx = tx) \Rightarrow (\exists r \in S, y \in X(ry = x \land sr = tr)).$$

This is precisely the locally free axiom as stated in Def. 2.8. Moreover, this axiom is *geometric* in the sense of geometric logic ([12], page 537).

Because the notion of torsor is geometric, it is evident that inverse image functors of geometric morphisms preserve torsors.

We will be mostly concerned with the case where \mathscr{E} is a Grothendieck topos; in that case we can consider any set-theoretic inverse semigroup S as an internal inverse semigroup ΔS , where $\Delta : Set \longrightarrow \mathscr{E}$ is the constant objects functor.

For example, when $\mathscr{E} = PSh(\mathbb{C})$, the category of presheaves on a small category \mathbb{C} , ΔS -torsors are characterized as follows:

Proposition 2.15 Let S be a semigroup in Set, and \mathbb{C} a small category. Suppose that a presheaf X is a ΔS -set in $PSh(\mathbb{C})$. Then X is a ΔS -torsor iff for every object c of \mathbb{C} , X(c) is an S-torsor.

Proof. Suppose that X is a ΔS -torsor. The inverse image functor c^* of the point $Set \xrightarrow{c} PSh(\mathbb{C})$ associated with an object c satisfies $c^*(X) = X(c)$. Now use the fact that c^* preserves torsors.

On the other hand, if every X(c) is an S-torsor, then the torsor conditions are satisfied for X in $PSh(\mathbb{C})$ because finite limits and epimorphisms are determined pointwise in $PSh(\mathbb{C})$.

When $\mathscr{E} = Sh(B)$, where B is a space, then a ΔS -set in Sh(B) is an étale space $X \xrightarrow{p} B$ and a continuous associative partial action

$$\mu: S \times X \twoheadrightarrow X$$

over B: p(sx) = p(x), where $\mu(s, x) = sx$. The domain of definition of μ is an open subset of $S \times X$, which simply means that for any $s \in S$, $\{x \mid sx \text{ is defined}\}$ is an open subset of X.

The torsor requirements interpreted in Sh(B) are as follows:

- 1. $X \xrightarrow{p} B$ is onto;
- 2. the partial action is fiberwise transitive for any $x, y \in X$ such that p(x) = p(y) there are $s, t \in S$ and $u \in X$ such that su = x and tu = y. Note that p(u) = p(su) = p(x) = p(y), i.e., u necessarily lies in the fiber of b = p(x) = p(y).
- 3. the action is locally free for any $s, t \in S$ and $x \in X$ such that sx = tx, there are $r \in S$ and $u \in X$ such that ru = x and sr = tr. Again, u necessarily lies in the fiber of x since p(u) = p(ru) = p(x).

We may call such an étale space a principal S-bundle. We will briefly return to these structures and their connections with principal G-bundles in § 4.4.

3 Torsors and the classifying topos

We have given an elementary definition of S-torsor, but have not motivated this definition, aside from the observation that it indeed generalizes both the group case and the meet-semilattice case. One of the purposes of this section is to show that the classifying topos of S does indeed classifies S-torsors, thus justifying the notion at least from the topos point of view. We shall also interpret the notions of strict, and well-supported S-sets in more categorical terms, namely as certain functors. Finally, we shall prove a structural result which characterizes all set-theoretic torsors.

3.1 The classifying topos of an inverse semigroup

As mentioned in the Introduction the classifying topos of an inverse semigroup S, denoted $\mathscr{B}(S)$, is defined as the category of equivariant sheaves on the inductive groupoid of S. This formulation simplifies to the following: the objects of $\mathscr{B}(S)$ are sets X equipped with a total action by S, which we write on the right, together with a map $X \xrightarrow{p} E$ to the idempotent subset E of S satisfying xp(x) = x and $p(xs) = s^*xs$. Morphisms are S-equivariant maps between such sets over E.

One may think loosely of $\mathscr{B}(S)$ as the 'space' associated with S; technically, the topos $\mathscr{B}(S)$ is an étendue [7].

Let L(S) denote the category whose object set is E, the collection of idempotents of S, and whose morphisms $d \xrightarrow{s} e$ are pairs $(s, e) \in S \times E$ such that $d = s^*s$ and s = es. We may think of L(S) as the total map category of the idempotent splitting of S. From another point of view, L(S)is the result of amalgamating the horizontal and vertical compositions of the inductive groupoid of S, regarding it as a double category. It is easily proved that L(S) is left-cancellative in the sense that its morphisms are monomorphisms. Moreover, L(S) has pullbacks: in fact any pullback is built from the following three basic kinds: an isomorphism square, a restriction square, and an inequality square.

$$e \longrightarrow s^*s \hspace{0.1cm} \downarrow \hspace{0.1cm} \downarrow$$

The first two are pullbacks iff they commute, and they are preserved by any functor.

The following result is due to Lawson and Steinberg [8].

Proposition 3.1 $\mathscr{B}(S)$ is equivalent to the category of presheaves on L(S) by an equivalence that associates with a representable presheaf of an idempotent e the étale map $eS \longrightarrow E$, $t \mapsto t^*t$.

The assignments $S \mapsto L(S) \mapsto \mathscr{B}(S)$ are functorial: a prehomomorphism morphism $\rho: S \longrightarrow T$ defines a functor

$$\rho: L(S) \longrightarrow L(T).$$

whence an (essential) geometric morphism

$$\rho_! \dashv \rho^* \dashv \rho_* : \mathscr{B}(S) \longrightarrow \mathscr{B}(T)$$

of classifying toposes.

The topos $\mathscr{B}(S)$ has a canonical "torsion-free generator" **S**, called the *Schutzenberger object*. As a presheaf on L(S), **S** is given as follows:

$$\mathbf{S}(e) = \{t \mid t^*t = e\} \qquad \mathbf{S}(s)(t) = ts , \qquad (1)$$

where $s: d \longrightarrow e$ is a morphism of L(S).

Thus the presheaf action of **S** is given by precomposition. In terms of étale maps over E, the Schutzenberger object is simply the domain map $S \longrightarrow E$, which sends s to s * s. On this object, S acts totally on the right by multiplication.

However, **S** carries more structure: the operation of postcomposition gives a partial action of S, defined pointwise by

$$S \times \mathbf{S}(e) \twoheadrightarrow \mathbf{S}(e)$$
; $(r,t) \mapsto \begin{cases} rt & \text{if } t = r^*rt \\ \text{undefined} & \text{otherwise.} \end{cases}$

This agrees with the restriction maps, so that **S** is an internal ΔS -action in $\mathscr{B}(S)$. Even better, it is a torsor:

Proposition 3.2 S together with its canonical ΔS -action is a torsor.

Proof. We may, by Proposition 2.15, test this pointwise. Clearly each $\mathbf{S}(e)$ is non-empty, as $e \in \mathbf{S}(e)$. Moreover, given $s, t \in \mathbf{S}(e)$, we have $(ts^*)s = t(s^*s) = te = t$, so that the action is transitive. Finally, if st = st' for $t, t' \in \mathbf{S}(e)$, then t = t' follows because L(S) is left-cancellative.

We shall later see that the internal partial action \mathbf{S} is the *generic torsor*. Unlike in the group case, the generic torsor \mathbf{S} may not be a representable presheaf. In fact, it is representable iff S is an inverse monoid.

3.2 Partial actions as functors

We relate S-sets, strict S-sets, and S-torsors to three classes of functors on L(S). It should be emphasized that these functors are covariant, whereas the objects of $\mathscr{B}(S)$ are contravariant functors on L(S).

The passage from S-sets to functors is given as follows. Given an S-set (X, μ) , define a functor

$$\Phi_{\mu}: L(S) \longrightarrow Set$$

such that

$$\Phi_{\mu}(e) = eX = \{x \in X | ex = x\}; \ \Phi_{\mu}(s)(x) = sx \text{ for } e \xrightarrow{s} d \text{ in } L(S) .$$
(2)

The action of Φ_{μ} on morphisms is well-defined: the map $s : e \longrightarrow d$ satisfies $s^*s = e$ and s = ds. Thus for $x \in X$ with ex = x we have that s^*sx is defined, whence sx is defined, so that $ss^*(sx) = sx$ and also d(sx) = sx.

The assignment $(X, \mu) \mapsto \Phi_{\mu}$ is the object part of a functor

$$\Phi: S - Set \longrightarrow \operatorname{Func}[L(S), Set]$$

Explicitly, a morphism of S-sets $\rho : (X, \mu) \longrightarrow (Y, \nu)$ gives a natural transformation $\Phi_{\rho} : \Phi_{\mu} \longrightarrow \Phi_{\nu}$, whose component at e is the function

$$\rho_e : eX \longrightarrow eY; \qquad ex = x \mapsto e\rho(x) = \rho(ex) = \rho(x)$$

Now we consider a construction in the other direction. Start with a functor $F: L(S) \longrightarrow Set$, and define

$$\Psi(F) = \lim_{\longrightarrow} E \longrightarrow L(S) \xrightarrow{F} Set = \prod_{E} F(e) / \sim$$
(3)

where the equivalence relation is generated by $(e, x) \sim (e', F(e \le e')(x))$.

The set $\Psi(F)$ is in general not an S-set, but the following is a necessary and sufficient condition.

Definition 3.3 A functor $F : L(S) \longrightarrow Set$ is *torsion-free* if for every idempotent $e, F(e) \longrightarrow \Psi(F)$ is injective. TF(L(S), Set) denotes the category of all such torsion-free functors.

One may regard torsion-freeness of F as expressing that all transition morphisms F(s) are monic (recall that all maps in L(S) are monic): **Proposition 3.4** A torsion-free functor $L(S) \longrightarrow$ Set has the property that its transition maps are injective (said to be transition-injective). The converse holds if S is an inverse monoid.

Proof. If F is torsion-free, then clearly for any idempotents $d, e, F(d \le e)$ is injective. It follows that F is transition-injective because every map in L(S) is the composite of an isomorphism and an inequality. For the converse, if S has a global idempotent 1, then $\Psi(F) \cong F(1)$ identifying the map $F(e) \longrightarrow \Psi(F)$ with $F(e \le 1)$, which is injective if F is transition-injective.

We may now prove that any torsion-free functor F gives rise to an S-set structure on $\Psi(F)$:

Proposition 3.5 The assignment $F \mapsto \Psi(F)$ restricts to form the object part of a functor $\Psi : TF(L(S), Set) \longrightarrow S-Set$.

Proof. The partial action by S in $\Psi(F)$ is defined as follows. If $s \in S$ and $\alpha \in \Psi(F)$, then

$$s\alpha = \begin{cases} [ses^*, F(se)(x)] & \text{if } \exists (e, x) \in \alpha, \ e \le s^*s \\ \text{undefined} & \text{otherwise.} \end{cases}$$

This action is well-defined because the maps $F(e) \longrightarrow \Psi(F)$ are injective. The action of Ψ on morphisms is also straightforward and left to the reader. \Box

Moreover, it is easily verified that all functors of the form Φ_{μ} are torsionfree: given any idempotent e, the map $eX \longrightarrow \Psi(\Phi_{\mu})$ is injective because the cocone of subsets $eX \subseteq X$ induces a map $\Psi(\Phi_{\mu}) \longrightarrow X$. We may now prove:

Proposition 3.6 The functor Ψ : $\text{TF}[L(S), \text{Set}] \longrightarrow S$ -Set is left adjoint to $\Phi : S$ -Set \longrightarrow TF[L(S), Set]. Moreover, for any torsion-free F, $\Psi(F)$ is well-supported, and the unit

$$F \longrightarrow \Phi \Psi(F)$$

is an isomorphism. For any well-supported S-set (X, μ) , the counit

$$\Psi\Phi(X,\mu) \longrightarrow (X,\mu)$$

is an isomorphism. Thus, Φ and Ψ establish an equivalence

$$S-Set \simeq TF(L(S), Set)$$
.

Proof. For any idempotent e, the map

$$F(e) \longrightarrow eX, \ x \mapsto [e, x],$$

is an isomorphism, for $X = \Psi(F)$. Indeed, if $(e, x) \sim (e, y)$, then clearly x = y, so the map is injective. It is onto because if $e\alpha$ is defined, then by definition there are $d \leq e$ and $y \in F(d)$ such that $\alpha = [d, y]$. But then $\alpha = [e, F_{d \leq e}(y)]$. This isomorphism of sets is natural so that $F \cong \Phi \Psi(F)$. On the other hand, it is not hard to see that a well-supported S-set (X, μ) is recovered from its functor Φ_{μ} as the colimit $\Psi(\Phi_{\mu})$. We omit further details.

3.3 $\mathscr{B}(S)$ classifies torsors

We will now specialize the correspondence between S-sets and torsion-free functors to strict S-sets and torsors, respectively.

Recall that an S-set (X, μ) is called *strict* when μ is in fact a homomorphism (rather than a prehomomorphism). For the proof of the following, recall from § 3.1 that L(S) has pullbacks, and that a functor $L(S) \longrightarrow Set$ preserves all pullbacks if and only if it preserves inequality pullbacks.

Proposition 3.7 An S-set (X, μ) is strict iff Φ_{μ} preserves pullbacks.

Proof. It is readily checked that the functor Φ_{μ} preserves the inequality pullbacks iff μ is a homomorphism.

Let $PB(\mathbb{C}, Set)$ denote the category of functors on a small category \mathbb{C} that preserve any existing pullbacks. The proof of the following is now evident:

Proposition 3.8 The equivalence of Prop. 3.6 restricts to one

 $S-Set \simeq PB(L(S), Set)$.

In order to describe torsors as functors we shall say that $F : L(S) \longrightarrow Set$ is *filtering* if its category of elements is a filtered category [12]. The following proposition is then a straightforward generalization of the group case:

Proposition 3.9 TOR(S) is equivalent to the category Filt(L(S), Set) of filtering functors on L(S), which is equivalent to the category of finite limit preserving distributions on $\mathscr{B}(S)$ (these are the inverse image functors of the points of $\mathscr{B}(S)$).

Proof. It is relatively straightforward to verify that an S-set (X, μ) satisfies the torsor conditions iff the functor Φ_{μ} is filtering.

Note that a torsor is necessarily a strict S-set because a filtering functor must preserve pullbacks.

In the above result one may replace the category of sets by an arbitrary topos \mathscr{E} . In § 3.1 we already showed that the Schutzenberger object **S** is a torsor in $\mathscr{B}(S)$. By the above result, it corresponds to a filtering functor $L(S) \longrightarrow \mathscr{B}(S)$, which is easily seen to be the Yoneda embedding. Because of the well-known correspondence between filtering functors $L(S) \longrightarrow \mathscr{E}$ and geometric morphisms $\mathscr{E} \longrightarrow \mathscr{B}(S)$, this proves:

Theorem 3.10 The functor that associates with a point $\operatorname{Set} \xrightarrow{p} \mathscr{B}(S)$ the torsor p^*S is an equivalence

$$Top(Set, \mathscr{B}(S)) \simeq TOR(S)$$
.

Thus $\mathscr{B}(S)$ classifies S-torsors in the sense that for any Grothendieck topos \mathscr{E} , we have

$$Top(\mathscr{E}, \mathscr{B}(S)) \simeq TOR(\mathscr{E}; \Delta S)$$
.

Another way to interpret the above equivalence of torsors with geometric morphisms is as follows. If X is an S-torsor (in Set) with corresponding point p, then we have the following topos pullback.

$$\begin{array}{c|c} \operatorname{Set}/X & \longrightarrow & \operatorname{Set} \\ & & & & & \\ & & & & & \\ & & & & \\ \mathscr{B}(S)/\mathbf{S} & \longrightarrow & \mathscr{B}(S) \end{array}$$
(4)

The geometric morphism δ is the support of X, described as a locale morphism in § 3.4.

The covariant representables correspond to torsors (in *Set*) that we call principal.

Example 3.11 *Principal torsors.* The covariant representable functor

$$\overline{e}: L(S) \longrightarrow Set; \ \overline{e}(d) = L(S)(e,d) = \{s \mid s^*s = e, \ s = ds\} = d\mathbf{S}(e)$$

associated with an idempotent e is filtering. The usual colimit extension $e^* : \mathscr{B}(S) \longrightarrow Set$ of \overline{e} is a finite limit-preserving distribution such that $e^*(P) = P(e)$. As such e^* is the inverse image functor of a point of $\mathscr{B}(S)$. The torsor associated with this point is easily seen to be is $e^*(\mathbf{S}) = \mathbf{S}(e)$. The Yoneda lemma asserts in this case that for any S-set X, S-set maps $\mathbf{S}(e) \longrightarrow X$ are in bijective correspondence with the set eX. We thus have a full and faithful functor

$$L(S)^{\mathrm{op}} \longrightarrow \mathrm{TOR}(S) ; e \mapsto \mathbf{S}(e) .$$

A torsor that is isomorphic to $\mathbf{S}(e)$, for some e, is said to be a principal torsor. Incidentally, $L(S)^{\text{op}}$ is isomorphic to the category R(S), whose object set is E, and a morphism $d \xrightarrow{s} e$ is an $s \in S$ such that $ss^* = e$ and s = sd. Thus, the full subcategory of TOR(S) on the principal torsors is equivalent to R(S).

We summarize the correspondences explained so far in the following diagram (we treat distributions in \S 5):

3.4 The structure of torsors

We now return to set-theoretic torsors and their structure. From what we have shown so far, we may conclude the following:

Proposition 3.12 Any S-set, and in particular any S-torsor, is a colimit of principal S-torsors.

Proof. A (filtering) functor $L(S) \longrightarrow Set$ is a colimit of representable functors.

3 TORSORS AND THE CLASSIFYING TOPOS

Although we cannot expect that an arbitrary colimit of (principal) torsors is a torsor, a filtered colimit of torsors is a torsor. We turn now to a closer examination of this aspect, and a more informative version of Prop. 3.12.

An ideal of a meet-semilattice is an upclosed subset that is closed under binary meets.

Proposition 3.13 Let $J \subseteq E$ be an ideal. Then the colimit of the functor

 $J^{\mathrm{op}} \subseteq E^{\mathrm{op}} \longrightarrow L(S)^{\mathrm{op}} \longrightarrow Set^{L(S)} \; ; \; d \mapsto \overline{d} \; ,$

is a filtering functor. In particular, the colimit preserves pullbacks, and its corresponding S-set, which we denote $\mathbf{S}(J)$, is a torsor.

Proof. A filtered colimit of filtering functors is filtering. J^{op} is filtered since J is an ideal, and any representable \overline{d} is filtering.

The torsor associated with an ideal $J \subseteq E$ given by Prop. 3.13 is

$$\mathbf{S}(J) = \coprod_{d \in J} \mathbf{S}(d) / \sim \,,$$

where the equivalence relation is defined as follows: $s \sim t$ if there is $f \in J$ such that sf = tf (without loss of generality we can assume $f \leq s^*s, t^*t$). The partial action of S in $\mathbf{S}(J)$ is given as follows:

 $s \cdot [t] = \begin{cases} [st] & \text{if there is } r \sim t \text{ such that } r^*r \in J \text{ and } r = s^*sr \\ \text{undefined} & \text{otherwise.} \end{cases}$

Clearly, this is well-defined. Note: if say rd = td, $d \in J$, $d \leq r^*r$, t^*t , then the domain of std = srd is d. We have $std \leq st$, so $d \leq (st)^*st$, whence $(st)^*st \in J$ since J is upclosed.

Thus, $\mathbf{S}(J)$ is a colimit of a diagram of principal torsors $\mathbf{S}(d)$, where d ranges over J and the morphisms are the ones coming from the inequalities $d \leq e$. In general, the maps $\mathbf{S}(d) \longrightarrow \mathbf{S}(J)$ are not strict, and are neither injective nor surjective.

Lemma 3.14 Suppose that $t^*t \in J$. Then for any $s \in S$, s[t] is defined and equals [st] iff $(st)^*st \in J$.

Proof. We have already seen above that if s[t] is defined, then $(st)^*st \in J$. For the converse, we must produce an $r \sim t$ such that $r^*r \in J$ and $r = s^*sr$. Let $r = s^*st$. Then $r^*r = (st)^*st \in J$ and $r = s^*sr$. Also note

$$r(r^*r) = r = s^*st = s^*stt^*t = tt^*s^*st = t(st)^*st = t(r^*r) ,$$

so that $r \sim t$.

Example 3.15 We have the following examples of S(J).

- 1. J = E: $\mathbf{S}(J) = S/\sigma$, where σ is the minimum group congruence on S.
- 2. J = the principal ideal on $e = \{d \in E \mid e \leq d\}$: $\mathbf{S}(J) = \mathbf{S}(e)$.
- 3. If S has a zero element 0 (s0 = 0s = 0), then 1 is a torsor. In this case, $\mathbf{S}(0) = \mathbf{S}(E) = S/\sigma = 1.$

In the case of a group G, it is well-known that every G-set decomposes uniquely as a disjoint sum of transitive G-sets, each of which is in turn a quotient of the representable G-set. We now explain how this statement generalizes to the case of an inverse semigroup.

Let X be a non-empty strict S-set, and let $x \in X$ be an arbitrary element. We may consider the set

$$\operatorname{Supp}(x) = \{ e \in E \mid ex = x \} ,$$

called the *support* of x. Supp(x) is easily seen to be an ideal of the meetsemilattice of idempotents E. (The strictness of X is needed for closure under binary infima.) If X is a torsor, then there is a locale morphism $\delta : X \longrightarrow E$, occurring in the topos pullback (4), such that if x is regarded as a point $1 \xrightarrow{x} X$ of the discrete locale X, then the point $\delta \cdot x : 1 \longrightarrow X \longrightarrow E$ of the locale E corresponds to the support ideal Supp(x). Indeed, the frame morphism $\mathscr{O}(E) \xrightarrow{\delta^*} 2^X$ associated with δ is given by $\delta^*(e) = eX$. Thus, δ is the support of the torsor X.

Returning to the case of an arbitrary strict S-set X, and $x \in X$, define the S-torsor

$$T_x = \mathbf{S}(\operatorname{Supp}(x)) = \lim_{\operatorname{Supp}(x)} \mathbf{S}(e) .$$

A typical element of T_x is an equivalence class of elements t such that $t^*t \in \text{Supp}(x)$, where two such s and t are equivalent when there exists an $f \in$

 $\operatorname{Supp}(x)$ for which sf = tf. As before, [t] denotes an equivalence class of such t. The partial action of S in T_x is defined by

$$s \cdot [t] = \begin{cases} [st] & \text{if } (st)^* st \in \text{Supp}(x) \text{ (Lemma 3.14)} \\ \text{undefined} & \text{otherwise.} \end{cases}$$

There is a canonical map $\nu_x : T_x \longrightarrow X$: $\nu_x[t] = tx$. Note that tx is defined since $(t^*t)x = x$ is, and that this is independent of the choice of representative. ν_x is the map from the colimit induced by the cocone of maps $\mathbf{S}(e) \xrightarrow{x} X$, where $e \in \text{Supp}(x)$ (corresponding by Yoneda to $x \in eX$).

Lemma 3.16 For any strict S-set X, ν_x is a strict map of S-sets.

Proof. Let $s \in S$, and $[t] \in T_x$. If s[t] = [st] is defined, then

$$\nu_x(s[t]) = \nu_x[st] = (st)x$$

is defined. Therefore, tx and $s(tx) = s\nu_x[t]$ are defined, and the latter equals the above. On the other hand, if $s\nu_x[t] = s(tx)$ is defined, then since X is strict $(st)x = \nu_x[st]$ is also defined. But this says that $(st)^*st \in \text{Supp}(x)$, so that by Lemma 3.14 s[t] is defined and equals [st].

By the *orbit* of x we mean the S-set

$$O_x = \{ y \in X \mid \exists s \in S, sx = y \} .$$

Lemma 3.17 The image of $\nu_x : T_x \longrightarrow X$ is precisely the orbit O_x . The map ν_x is surjective precisely when the action of S in X is transitive.

Proof. If $y = sx \in O_x$, then $s^*s \in \text{Supp}(x)$, and $\nu_x[s] = sx = y$. Conversely, elements of the image are clearly in the orbit. For the other statement note that the action is transitive iff there is precisely one orbit, which equals the whole of X.

Any strict S-set X can be written as the coproduct (disjoint sum) of its orbits. (If X is not strict, then the orbits may not be disjoint.) Let I be an indexing set for this decomposition, so that we have

$$X \cong \coprod_{i \in I} O_{x_i} \; .$$

4 CHANGE OF BASE

Then the maps $\nu_{x_i}: T_{x_i} \longrightarrow O_{x_i}$ assemble to form a covering of X:

$$\coprod_{i\in I} T_{x_i} \twoheadrightarrow \coprod_{i\in I} O_{x_i} \cong X$$

In particular, this shows how X is canonically a colimit of S-torsors, and ultimately a colimit of principal S-torsors.

Corollary 3.18 If x is an element of an S-torsor X, then the map $T_x \xrightarrow{\nu_x} X$ is an isomorphism of S-sets. I.e., $T_x \cong O_x = X$ in this case.

Proof. ν_x is strict (Lemma 3.16), whence an isomorphism (Prop. 2.12).

The above results were stated for strict S-sets, but it is equally true that an arbitrary S-set admits a decomposition as a colimit of principal torsors (Prop. 3.12). We do not give an explicit description, which would be more involved since in general Supp(x) may not be an ideal.

4 Change of base

So far we have been working with a fixed inverse semigroup S; in this section we examine what happens when we vary S. We begin by showing that a prehomomorphism $S \longrightarrow T$ induces an adjunction between the categories S-Setand T-Set; the right adjoint is restriction of scalars, and the left adjoint is a tensor product with T. In general, the right adjoint does not restrict to the subcategories of torsors (just as in the group case), but when X is an S-torsor, then $T \otimes_S X$ is a T-torsor, and thus TOR(-) is a covariant functor. We give an explicit description of the tensor product $T \otimes_S X$, which is more involved than for groups. We apply this to the homomorphism $S \longrightarrow S/\sigma$, obtaining a torsor characterization of E-unitary semigroups. Finally, we relate principal S-bundles on a space to principal bundles for the maximum group of S.

4.1 The hom-tensor adjunction

We fix a prehomomorphism $\rho: S \longrightarrow T$. If $T \longrightarrow I(Z)$ is a T-set, then the composite prehomomorphism

$$S \xrightarrow{\rho} T \longrightarrow I(Z)$$

is an S-set (with the same underlying set Z) that we denote Z_{ρ} . This gives a functor

 $T-Set \longrightarrow S-Set \qquad Z \mapsto Z_{\rho}$,

which we call restriction of scalars.

Clearly, if we wish to restrict this functor to a functor from strict S-sets to strict T-sets, we need to require that ρ is in fact a homomorphism.

Restriction of scalars has a left adjoint because categories of the form S-Set are cocomplete. We first prove this fact:

Lemma 4.1 The category S-Set is cocomplete.

Proof. Coproducts of S-sets are set-theoretic. Concretely, for a family (X_i, μ_i) of S-sets, form the set $\prod_i X_i$, and define a partial action via

$$s \cdot (x, i) = (sx, i)$$

where this is defined if and only if sx is defined. It is readily checked that this has the correct property. This same construction is valid for strict S-sets.

Coequalizers are not set-theoretic. Consider two maps $\alpha, \beta : X \longrightarrow Y$ of S-sets (where α, β need not be strict). Define an equivalence relation \sim on Y generated by the following two clauses:

$$y \sim y'$$
 if $\exists x \in X$. $\alpha(x) = y$ and $\beta(x) = y'$
 $sy \sim sy'$ if $y \sim y'$ (and sy , sy' are defined).

Now define an action in Y/\sim by putting

t[y] = [ty'] for some $y' \sim y$ with ty' defined.

This is well-defined on representatives, and gives a partial action of S in Y/\sim . Clearly the quotient function $Y \longrightarrow Y/\sim$ is equivariant. The verification of the coequalizer property is left to the reader.

Proposition 4.2 The restriction-of-scalars functor T-Set $\longrightarrow S$ -Set along a prehomomorphism $\rho: S \longrightarrow T$ has a left adjoint.

Proof. We have proved in § 3.4 that every S-set is canonically a colimit of principal torsors (where the diagram generally contains non-strict maps). Since S-torsors are the same as points of the topos $\mathscr{B}(S)$, it is easy to see

how to pass forward an S-torsor X along a prehomomorphism $S \xrightarrow{p} T$: if p is the point of $\mathscr{B}(S)$ corresponding to X, then the composite geometric morphism

$$Set \xrightarrow{p} \mathscr{B}(S) \xrightarrow{\rho} \mathscr{B}(T)$$

is a point of $\mathscr{B}(T)$ whose corresponding *T*-torsor we denote $T \otimes_S X$. In the special case of a principal torsor $X = \mathbf{S}(e)$, one easily verifies that $T \otimes_S \mathbf{S}(e) \cong \mathbf{T}(\rho(e))$, where **T** is the Schutzenberger object of *T*. Putting this together, the left adjoint to $(-)_{\rho}$ may be taken to be the following: if $X \cong \varinjlim_{e} \mathbf{S}(e)$,

then

$$T \otimes_S X \cong T \otimes_S (\underset{e}{\underset{e}{\lim}} \mathbf{S}(e)) \cong \underset{e}{\underset{e}{\lim}} (T \otimes_S \mathbf{S}(e)) \cong \underset{e}{\underset{e}{\lim}} \mathbf{T}(\rho(e)) .$$

The last colimit is taken in T-Set.

4.2 Tensor product of torsors

We have described the functor $X \mapsto T \otimes_S X$ in an abstract way. In this section we calculate an explicit description for the case where X is a torsor.

Consider the subset of

$$L(T) \times E(S) \times X$$

consisting of those 4-tuples (t, d, e, x) such that t = dt, $t^*t = \rho(e)$, and $x \in eX$. In other words, $\rho(e) \xrightarrow{t} d$ is a morphism of L(T), and x is an element of eX. Let $T \otimes_S X$ denote the quotient of this subset given by the equivalence relation generated by equating

$$(t, c, e, x) \sim (t, d, e, x)$$

whenever $c \leq d$, and

$$(t\rho(s), d, f, x) \sim (t, d, e, sx)$$

whenever $f \xrightarrow{s} e$ is a morphism of L(S). Let [t, d, e, x] denote the equivalence class of an element (t, d, e, x). A partial action by T is defined in $T \otimes_S X$ as follows: if $r \in T$ and $\alpha \in T \otimes_S X$, then

$$r\alpha = \begin{cases} [rt, rr^*, e, x] & \exists (t, d, e, x) \in \alpha \text{ such that } d \leq r^*r \\ \text{undefined} & \text{otherwise.} \end{cases}$$

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From yet another point of view, if X is an S-torsor, with corresponding point p, we may regard $T \otimes_S X$ and the connecting map $X \longrightarrow T \otimes_S X$ as arising from the following diagram of topos pullbacks.

The Schutzenberger object **T** is the generic ΔT -torsor in $\mathscr{B}(T)$. The connecting map commutes with support.



4.3 *E*-unitary semigroups

We now apply some of the topos machinery to characterize some well-known concepts from semigroup theory.

First recall that a prehomomorphism of inverse semigroups is said to be *idempotent-pure* if it reflects idempotents [9].

Proposition 4.3 If ρ is idempotent-pure, then for any S-torsor X, the connecting map $X \longrightarrow T \otimes_S X$ is a monomorphism.

Proof. A semigroup prehomomorphism ρ is idempotent-pure iff the connecting map of generic torsors $\mathbf{S} \longrightarrow \rho^* \mathbf{T}$ is a monomorphism.

As previously mentioned, if ρ is a homomorphism, then restriction of scalars $T-Set \longrightarrow S-Set$ preserves strictness. For example, the map

$$S \longrightarrow S/\sigma = G$$

to the maximum group is a homomorphism.

Corollary 4.4 If S is E-unitary with maximum group image G (so that the homomorphism $S \longrightarrow G$ is idempotent-pure), then every S-torsor is isomorphic to an S-subset of the S-torsor G.

Proof. If X is an S-torsor, then $G \otimes_S X$ is a G-torsor, whence isomorphic to G. Therefore, by Prop. 4.3, X is isomorphic to an S-subset of G regarded as an S-set.

Example 4.5 In the *E*-unitary case a principal torsor $\mathbf{S}(e)$ is isomorphic to the *S*-subset $\{\overline{s} \mid s^*s = e\}$ of *G*, where the partial action by *S* is given by:

$$t\overline{s} = \begin{cases} \overline{ts} & \text{if } s = t^*ts \\ \text{undefined} & \text{otherwise.} \end{cases}$$

Generally, if $J \subseteq E$ is an ideal, then the S-subset $\{\overline{s} \mid s^*s \in J\}$ of G is a torsor, where the partial action by S is given in just the same way. This describes, in the E-unitary case, every torsor up to isomorphism. It simultaneously generalizes the \wedge -semilattice (Eg. 2.10) and group cases.

Corollary 4.6 The following are equivalent for an inverse semigroup S:

- 1. S is E-unitary;
- 2. for every Grothendieck topos \mathscr{E} , $\operatorname{TOR}(\mathscr{E}; \Delta S)$ is left-cancellative and the forgetful functor

$$\operatorname{TOR}(\mathscr{E};\Delta S) \longrightarrow \mathscr{E}$$

preserves monomorphisms;

3. $\operatorname{TOR}(S)$ is left-cancellative and the forgetful functor

$$\operatorname{TOR}(S) \longrightarrow \operatorname{Set}$$

preserves monomorphisms.

Proof. $1 \Rightarrow 2$. A map $X \xrightarrow{m} Y$ of torsors in \mathscr{E} corresponds to a natural transformation $\tau : p^* \longrightarrow q^*$ of their classifying points $p, q : \mathscr{E} \longrightarrow \mathscr{B}(S)$. If $\eta : \mathbf{S} \longrightarrow \overline{\mathbf{S}}$ is the canonical morphism in $\mathscr{B}(S)$ (as in § 4.4), then the following square in \mathscr{E} commutes.

If S is E-unitary, then η is a monomorphism, whence so are $p^*\eta$ and $q^*\eta$. $\tau_{\overline{\mathbf{S}}}$ is an isomorphism because it is a map of ΔG -torsors, $G = S/\sigma$. Therefore, m is a monomorphism in \mathscr{E} .

 $2 \Rightarrow 3$. This is trivial.

 $3 \Rightarrow 1$. If $\operatorname{TOR}(S)$ is left-cancellative, then in particular for any idempotent e, the map of torsors $\mathbf{S}(e) \longrightarrow G$ is a monomorphism in $\operatorname{TOR}(S)$. If $\operatorname{TOR}(S) \longrightarrow Set$ preserves monomorphisms, then this map is injective, which says that S is E-unitary.

4.4 Principal Bundles

We return to the topos Sh(B) of sheaves on a space B. We regard sheaves as étale spaces over B; as explained in § 2.4, an étale space $X \longrightarrow B$ equipped with a partial action of ΔS is a torsor when (i) every fibre is nonempty, (ii) the action is fibrewise transitive and (iii) the action is fibrewise locally free.

Let $S \longrightarrow G = S/\sigma$ denote again the maximum group image of S, and consider a ΔS -torsor $X \xrightarrow{\psi} B$ over B. We may now use the tensor product to form a ΔG -torsor $G \otimes_S X = Y \xrightarrow{\varphi} B$, which is a locally constant covering of B. It may be interesting to examine the connecting map $X \longrightarrow G \otimes_S X$ over B. To this end, let $p : Sh(B) \longrightarrow \mathscr{B}(S)$ denote the geometric morphism associated with a ΔS -torsor $X \xrightarrow{\psi} B$, so that $p^*(\mathbf{S}) = \psi$.

We will need the (essentially unique) connected universal locally constant object $\overline{\mathbf{S}}$ of $\mathscr{B}(S)$ - universal in the sense that it splits all locally constant objects [5]. (The notation is meant to suggest that this object is a kind of closure of \mathbf{S} , which we do not need to discuss here.) Explicitly, the presheaf $\overline{\mathbf{S}}$ may be given as $\overline{\mathbf{S}}(e) = G$, and transition along a morphism $d \xrightarrow{s} e$ of L(S)is given by $g \mapsto g\overline{s}$. There is a canonical natural transformation $\eta : \mathbf{S} \longrightarrow \overline{\mathbf{S}}$. The geometric morphism $\mathscr{B}(S)/\overline{\mathbf{S}} \longrightarrow \mathscr{B}(S)$ is the universal locally constant covering of $\mathscr{B}(S)$.

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Now consider the following diagram of topos pullbacks.



Then $Y \xrightarrow{\varphi} B$ is a ΔG -torsor. It is also a locally constant covering because it is a pullback of the universal covering γ (which is the unique point of $\mathscr{B}(G)$). Thus, $G \otimes_S$ maps the category of ΔS -torsors over B to the category of ΔG -torsors over B, which in turn maps to the category of locally constant coverings of B. Moreover, the two torsors are related by a map over B.



For example, if S is E-unitary, which is characterized by the condition that η is a monomorphism, then the connecting map $X \longrightarrow Y$ is an (open) inclusion.

5 Distributions

We now complete the picture of S-sets and S-torsors by introducing the third viewpoint, namely as distributions on the topos $\mathscr{B}(S)$.

5.1 Distributions on a topos

We rehearse some standard definitions concerning topos distributions [2], and characterize the category of pullback-preserving functors on \mathbb{C} in these terms. This in turn yields a description of the category of strict *S*-sets in terms of distributions (Prop. 5.7).

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Definition 5.1 (Lawvere) A distribution on a Grothendieck topos \mathscr{E} (with values in Set) is a colimit-preserving functor $\mathscr{E} \longrightarrow Set$. If \mathbb{C} is a small category and $PSh(\mathbb{C})$ denotes the category of presheaves on \mathbb{C} , then we shall refer to a distribution on $PSh(\mathbb{C})$ simply as a distribution on \mathbb{C} .

The inverse image functor of a point of \mathscr{E} , i.e. of a geometric morphism $Set \longrightarrow \mathscr{E}$, is a distribution. A distribution has a right adjoint, but in general it need not be the inverse image functor of a point of the topos since it need not preserve finite limits. Thus, we may think of distributions as generalized points.

It is well-known that the category of distributions on \mathbb{C} (with natural transformations) is equivalent to the category of (covariant) functors $\mathbb{C} \longrightarrow Set$. The equivalence is given on the one hand by composing with the Yoneda functor $\mathbb{C} \longrightarrow PSh(\mathbb{C})$, and on the other by a colimit extension formula along the same Yoneda functor: if F is a functor on \mathbb{C} , then

$$\lambda(P) = \lim_{K \to \infty} \mathbb{P} \longrightarrow \mathbb{C} \xrightarrow{F} Set$$

is a distribution, where $\mathbb{P} \longrightarrow \mathbb{C}$ is the discrete fibration corresponding to a presheaf P. For any object c of \mathbb{C} , we have $\lambda(c) = F(c)$, where typically we use the same symbol c to denote an object of \mathbb{C} and the corresponding representable presheaf.

The following probably well-known fact will help us in our study of S-sets. PB(\mathbb{C} , Set) denotes the category of pullback-preserving functors on \mathbb{C} .

Proposition 5.2 If \mathbb{C} has pullbacks, then $PB(\mathbb{C}, Set)$ is equivalent to the full subcategory of distributions on \mathbb{C} that preserve pullbacks of the form

$$\begin{array}{c} P \longrightarrow Q \\ \downarrow & \downarrow \\ c \longrightarrow d \end{array}$$

in $PSh(\mathbb{C})$, where m is a morphism of \mathbb{C} .

Proof. Let λ denote the colimit extension of a functor $F : \mathbb{C} \longrightarrow Set$. We have two functors:

$$PSh(\mathbb{C}/d) \simeq PSh(\mathbb{C})/d \longrightarrow Set/F(c)$$
.

One functor carries $Q \longrightarrow d$ first to its pullback $P \longrightarrow c$ along m and then to $\lambda(P) \longrightarrow F(c)$, and the other carries $Q \longrightarrow d$ first to $\lambda(Q) \longrightarrow F(d)$ and then to the pullback along F(m). Since F preserves pullbacks (by assumption), we see that the two functors are isomorphic when composed with Yoneda $\mathbb{C}/d \longrightarrow PSh(\mathbb{C}/d)$. But both functors preserve colimits, so they must be isomorphic, which says that λ preserves pullbacks of the specified form. \Box

5.2 Torsion-free distributions

We wish to interpret general S-sets as distributions on $\mathscr{B}(S)$. According to Def. 5.1 and Prop. 3.1, this is equivalent to what we call a distribution on L(S), but in some cases (such as the Wagner-Preston and Munn) it is beneficial to regard $\mathscr{B}(S)$ as the category of étale maps $X \longrightarrow E$.

Definition 5.3 A distribution $\lambda : \mathscr{B}(S) \longrightarrow Set$ is *torsion-free* if for every $s \in \mathbf{S}(e), \lambda(s) : \lambda(e) \longrightarrow \lambda(\mathbf{S})$ is injective.

This definition is in agreement with Def. 3.3 in the following sense.

Proposition 5.4 A functor $L(S) \longrightarrow$ Set is torsion-free iff its colimit extension $\mathscr{B}(S) \longrightarrow$ Set is torsion-free.

Proof. A distribution λ on $\mathscr{B}(S)$ is torsion-free iff for every idempotent e, the map $\lambda(e) : \lambda(e) \longrightarrow \lambda(\mathbf{S})$ is injective because an arbitrary element $e \xrightarrow{s} \mathbf{S}$ factors as $e \xrightarrow{s} ss^* \longrightarrow \mathbf{S}$, where $e \xrightarrow{s} ss^*$ is an isomorphism. If $\lambda = F$ on L(S), then $\lambda(e)$ is the canonical map $F(e) \longrightarrow \Psi(F)$. Note that $\lambda(\mathbf{S})$ is isomorphic to

$$\varinjlim \mathbb{S} \longrightarrow L(S) \xrightarrow{F} Set ,$$

where $\mathbb{S} \longrightarrow L(S)$ is the discrete fibration corresponding to **S**. This discrete fibration is equivalent to $E \longrightarrow L(S)$ [4], so the above colimit is isomorphic to $\Psi(F)$.

Prop. 5.5, which is a distribution version of Prop. 3.6, requires what we call the generic singleton of a set. Let X be a set and consider I(X), the symmetric inverse semigroup on X. Write L(X) for L(I(X)); explicitly, the objects of this category are the subsets of X and the morphisms are the

injective maps between them. Also, let $\mathscr{B}(X)$ denote $\mathscr{B}(I(X))$. Consider the functor

$$x^* : L(X) \longrightarrow Set ; x^*(A) = A$$
.

If X is non-empty, then x^* is filtering, so that it corresponds to a geometric morphism

$$x: Set \longrightarrow \mathscr{B}(X)$$
,

which we call the generic singleton of X. If an element $a \in X$ is regarded as a singleton subset $\{a\} \subseteq X$, whence an object of L(X), then its corresponding (representable) point of $\mathscr{B}(X)$ is isomorphic to the generic singleton x, by a unique isomorphism. If $X = \emptyset$, then $\mathscr{B}(X) = Set$ and $x^* : Set \longrightarrow Set$ is the 0-distribution: $x^*(A) = \emptyset$. In this case, x^* is not (the inverse image functor of) a point.

For any S-set (X, μ) , the composite functor

$$L(S) \longrightarrow \mathscr{B}(S) \xrightarrow{\mu_!} \mathscr{B}(X) \xrightarrow{x^*} Set$$

is precisely Φ_{μ} , where x is the generic singleton of X.

Proposition 5.5 For any S-set (X, μ) , the distribution $x^* \cdot \mu_!$ is torsion-free (by Props. 3.6 and 5.4, or by Prop. 5.6). The category S-Set is equivalent to the full subcategory of torsion-free distributions on $\mathscr{B}(S)$. The equivalence associates with an S-set (X, μ) the torsion-free distribution $x^* \cdot \mu_!$, and with a torsion-free distribution λ the S-set $\lambda(\mathbf{S})$.

The restriction-of-scalars functor has a distribution interpretation because if a *T*-set *Z* corresponds to torsion-free distribution λ , then Z_{ρ} corresponds to $\lambda \cdot \rho_{!}$. Thus, $\lambda \cdot \rho_{!}$ is torsion-free. A direct proof of this fact is probably noteworthy.

Proposition 5.6 If $\lambda : \mathscr{B}(T) \longrightarrow$ Set is a torsion-free distribution, then so is

$$\mathscr{B}(S) \xrightarrow{\rho_!} \mathscr{B}(T) \xrightarrow{\lambda} Set$$
.

Proof. $\rho_!(e \longrightarrow \mathbf{S})$ equals $\rho(e) \longrightarrow \rho_!(\mathbf{S})$. But the composite of this with the transpose $\rho_!(\mathbf{S}) \longrightarrow \mathbf{T}$ of $\mathbf{S} \longrightarrow \rho^*(\mathbf{T})$ is the monomorphism $\rho(e) \longrightarrow \mathbf{T}$, which is taken by λ to an injective map, where \mathbf{T} denotes the Schutzenberger object of $\mathscr{B}(T)$. Therefore, λ carries $\rho(e) \longrightarrow \rho_!(\mathbf{S})$ to an injective map. Hence, $\lambda \cdot \rho_!$ is torsion-free.

We should point out that the left adjoint to restriction-of-scalars (as described in § 4.1) is in general not obtained by taking a colimit in the category of distributions on $\mathscr{B}(T)$: if X is an S-set with associated (torsion-free) distribution λ , then the distribution associated with $T \otimes_S X$ is different from $\lambda \cdot \rho^*$.

5.3 S-distributions

We may apply Prop. 5.2 to the category L(S). <u>S-Set</u> denotes the category of strict, well-supported S-sets and equivariant maps.

Proposition 5.7 <u>S-Set</u> is equivalent to the full subcategory of distributions $\mathscr{B}(S) \longrightarrow$ Set (which we shall call S-distributions) that preserve pullbacks of the form



where $d \leq e$ in E, and $P(c) = \{x \in Q(c) \mid dm_c(x) = m_c(x)\}$. The equivalence associates with an S-set (X, μ) the distribution $x^* \cdot \mu_1$, which is an S-distribution, and with an S-distribution λ the S-set $\lambda(\mathbf{S})$.

Proof. Prop. 5.2 says that the statement holds for pullbacks of the form



where $d \xrightarrow{s} e$ is a morphism of L(S). But the isomorphism factor $d \xrightarrow{s} ss^*$ of this morphism is irrelevant.

5.4 Examples

We give explicit descriptions of the distributions associated with some of the key examples of S-sets.

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Example 5.8 Consider the terminal S-set 1, where every $s \in S$ acts as the unique total function $1 \longrightarrow 1$. The pullback-preserving functor $L(S) \longrightarrow Set$ associated with this S-set is identically 1. Its S-distribution is the connected components functor $\pi_0 : \mathscr{B}(S) \longrightarrow Set$. Incidentally, π_0 is terminal amongst all distributions on $\mathscr{B}(S)$, not just the S-distributions.

Example 5.9 The Wagner-Preston distribution. Consider again the Wagner-Preston representation of S (Eg. 2.2): the corresponding pullback-preserving functor on L(S) is

$$W(e) = eS = \{t \mid t = et\}$$
.

Transition in W along $e \xrightarrow{s} f$ is given by $t \mapsto st$. The S-distribution associated with the Wagner-Preston S-set is

$$W(X \longrightarrow E) = X ,$$

where $X \longrightarrow E$ is an étale right S-set. For instance, if $\mathbb{G} = (G_0, G_1) = (S, E)$ is the inductive groupoid associated with S, then $W(E \xrightarrow{1} E) = E = G_0$, the set of objects of \mathbb{G} .

Example 5.10 The Munn distribution. The pullback-preserving functor on L(S) associated with the Munn S-set is

$$M(e) = eE = \{d \mid d \le e\}$$
.

Transition in M along a morphism $e \xrightarrow{s} f$ of L(S) sends $d \leq e$ to $sds^* \leq ss^* \leq f$. Its S-distribution sends an étale right S-set $p: X \longrightarrow E$ to its set of 'Munn-orbits:'

$$M(p) = O_M(X) = X/\sim,$$

where \sim is the equivalence relation generated by relating $x \sim xs$ whenever $p(x) \leq ss^*$ (without loss of generality, by replacing s with p(x)s we can insist that $p(x) = ss^*$, for then xs = xp(x)s and $p(x) = p(x)s(p(x)s)^*$). Note that $p(xs) = s^*p(x)s \leq s^*ss^*s = s^*s$ (with equality if $p(x) = ss^*$). One easily sees that $M(E \xrightarrow{1} E) = \pi_0(\mathbb{G})$, the set of connected components of \mathbb{G} .

5.5 $\mathscr{B}(S)$ acts in S-Set

Lawvere observes that a topos ${\mathscr E}$ acts in its category of distributions by the formula:

$$P \cdot \lambda(E) = \lambda(P \times E)$$
, or $\int E d(P \cdot \lambda) = \int P \cdot E d\lambda$,

where P and E are objects of \mathscr{E} , and λ is a distribution on \mathscr{E} . The presheaf case $\mathscr{E} = PSh(\mathbb{C})$ of this formula yields

$$P \cdot F(c) = \underset{\longrightarrow}{\lim} \mathbb{X}(c) \longrightarrow \mathbb{C} \xrightarrow{F} Set ,$$

where



is a pullback of discrete fibrations.

Proposition 5.11 Suppose that \mathbb{C} has pullbacks. If a functor F on \mathbb{C} preserves pullbacks, then for any presheaf P on \mathbb{C} , $P \cdot F$ also preserves pullbacks.

Proof. We must show that the distribution corresponding to F preserves pullbacks of the following form.

This is a consequence of Prop. 5.2.

Corollary 5.12 If λ is an S-distribution, then so is $P \cdot \lambda$, for any object P of $\mathscr{B}(S)$.

Consequently, $\mathscr{B}(S)$ acts in <u>S-Set</u>. If a strict S-set X corresponds to S-distribution λ , then let us write $P \otimes X$ for the strict S-set corresponding to the S-distribution $P \cdot \lambda$: we have

$$P \otimes X \cong P \cdot \lambda(\mathbf{S}) = \lambda(P \times \mathbf{S})$$
.

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Furthermore, if P is interpreted as an étale map $F \xrightarrow{p} E$, then

$$P \otimes X \cong \lambda(P \times \mathbf{S}) = \lambda(S \times_E F \longrightarrow E) , \qquad (5)$$

where



is a pullback of étale maps.

A description of the S-set $P \otimes X$ may be given that is similar to the one given for the tensor product $T \otimes_S X$. Again regarding P as an étale map $Y \xrightarrow{p} E$, we may construct $P \otimes X$ as a quotient of the following subset of $Y \times L(S) \times X$:

$$A = \{(y, t, d, x) \mid p(y) \xrightarrow{t} d \text{ and } tx \text{ is defined } \}.$$

Any two 4-tuples in A

$$(ys, ts, d, x) \sim (y, t, d, sx)$$

are identified whenever $s = t^*ts$, and sx is defined. Note: if $(y, t, d, sx) \in A$, then $(ys, ts, d, x) \in A$ because we have $p(ys) = s^*p(y)s = s^*t^*ts = (ts)^*ts$ (which equals s^*s), and implicitly (ts)x = t(sx) is defined. In addition, two 4-tuples

$$(y,t,c,x) \sim (y,t,d,x)$$

are identified whenever $c \leq d$. Then $P \otimes X$ is isomorphic to the set of equivalence classes so obtained.

Example 5.13 Let 1 denote the terminal S-set, which corresponds to the S-distribution π_0 . Then by (5) we have

$$\mathbf{S} \otimes 1 \cong \pi_0(\mathbf{S} \times \mathbf{S}) = \pi_0(S \times_E S \longrightarrow E) \cong S/\sigma$$
.

In other words, the S-sets $\mathbf{S} \otimes 1$ and S/σ are isomorphic.

Example 5.14 Consider again the S-sets S and E, the Wagner-Preston and Munn representations (Eg. 2.2). By (5)

$$\mathbf{S} \otimes S \cong W(\mathbf{S} \times \mathbf{S}) = W(S \times_E S \longrightarrow E) \cong S \times_E S ,$$

and

$$\mathbf{S} \otimes E \cong M(\mathbf{S} \times \mathbf{S}) = M(S \times_E S \longrightarrow E) \cong O_M(S \times_E S) .$$

A Munn-orbit of $S \times_E S$ is given by relating a pair (r, t), such that $r^*r = t^*t$, with (r, t)s = (rs, ts) whenever $ss^* = r^*r$ $(= t^*t)$. Let [r, t] denote the Munn-orbit of (r, t). We have the following commutative triangle of S-set morphisms.



The morphism $(r,t) \mapsto tr^*$ factors through the S-set of Munn-orbits by a (well-defined) isomorphism of S-sets. This shows that the 'Lawvere-product' of the Schutzenberger object and the Munn S-set equals the Wagner-Preston S-set: $\mathbf{S} \otimes E \cong S$. The same equation in terms of S-distributions,

$$\mathbf{S} \cdot M \cong W \; ,$$

or even its 'integral' form

$$\int \mathbf{S} \times P \, dM = \int P \, dW \, ,$$

may appeal to the reader.

6 Classifying topos of an arbitrary semigroup

In this section, we define a topos $\mathscr{B}(T)$ associated with an arbitrary semigroup T. We make no assumptions on T, although if T is inverse, then the topos $\mathscr{B}(T)$ obtained is equivalent to the usual one. Instead of defining first a category L(T) and then taking for $\mathscr{B}(T)$ the category of presheaves on that category, what seems like a reasonable and viable alternative is to define $\mathscr{B}(T)$ as the topos classifier of T-torsors. In any case, while it is unclear to us that the "presheaves on L(T)" approach does not degenerate (because a general semigroup may not have 'enough' idempotents), or that $\mathscr{B}(T)$ should even be a presheaf topos in general, we also cannot be sure that reasonable and viable generalizations of L(T), or of the inductive groupoid, do not exist.

6.1 Semigroup torsors

Let M(X) denote the set of partial maps $X \to X$. M(X) is an ordered semigroup (not inverse). More generally, if X is an object of a topos, then let $M(X) = \widetilde{X}^X$, where \widetilde{X} denotes the classifier of partial maps into X.

In the case of a general semigroup, we must upgrade Def. 2.1 by replacing the inverse semigroup I(X) with the ordered semigroup M(X): a *T*-set (X, μ) of *T* is thus a semigroup prehomomorphism

$$\mu: T \longrightarrow M(X) ; \ \mu(s)(x) = sx$$
.

If T is inverse, then a T-set $T \longrightarrow M(X)$ necessarily factors through $I(X) \subseteq M(X)$.

We may now observe that Defs. 2.8 and 2.14 make sense for an arbitrary semigroup, not just inverse ones. This gives us a category TOR(T) of torsors and equivariant maps for T.

6.2 Construction of $\mathscr{B}(T)$

The well-known topos classifier of semigroups, which we shall denote \mathscr{S} , can be constructed as the topos of functors on the category of finitely presented semigroups. The generic semigroup in \mathscr{S} is the underlying set functor, which we denote **R**. A sketch approach for semigroups is also known [1].

We next construct the topos classifier \mathscr{T} of pairs (S, X), where S is a semigroup and X is an S-torsor, using the syntactic site associated with a geometric theory. This theory has two sorts X and S, a binary associative operation symbol on S, and also a relation symbol

$$R \subseteq S \times X \times X$$

that is functional (but not total) in the first two arguments:

$$\forall s, x, y, z; R(s, x, y) \land R(s, x, z) \Rightarrow y = z ,$$

and well-supported

$$\forall x; \exists s, y, R(s, x, y) .$$

We require that R is (strictly) associative:

$$\forall s, t, x, y; R(st, x, y) \Longrightarrow \exists z, R(t, x, z) \land R(s, z, y) ,$$

$$\forall s, t, x, y; \exists z, R(t, x, z) \land R(s, z, y) \Rightarrow R(st, x, y) .$$

We require that X is non-empty:

$$\exists x, x = x$$
,

that the partial action is transitive:

$$\forall x, y; \exists s, t, z, R(s, z, x) \land R(t, z, y) ,$$

and locally free:

$$\forall s, t, x, y; \exists y, R(s, x, y) \land R(t, x, y) \Longrightarrow \exists r, y(R(r, y, x) \land sr = tr) .$$

If (\mathbf{S}, \mathbf{X}) denotes the generic semigroup-torsor pair of \mathscr{T} , then since \mathscr{S} (together with \mathbf{R}) classifies semigroups there is a geometric morphism $\gamma : \mathscr{T} \longrightarrow \mathscr{S}$ corresponding to \mathbf{S} , where $\gamma^*(\mathbf{R}) = \mathbf{S}$. If T is a semigroup in Set, with corresponding point $Set \xrightarrow{p} \mathscr{S}$, so that $p^*(\mathbf{R}) = T$, then the topos pullback of γ and p classifies T-torsors.



Moreover, we have

$$\rho^*(\mathbf{S}) = \rho^* \gamma^*(\mathbf{R}) \cong \Delta p^*(\mathbf{R}) = \Delta T,$$

and the generic ΔT -torsor in $\mathscr{B}(T)$ is $\rho^*(\mathbf{X})$. We call $\mathscr{B}(T)$ the classifying topos of T, just as in the inverse case. We have thus proved the following.

Theorem 6.1 An arbitrary semigroup T has a topos, denoted $\mathscr{B}(T)$, which classifies T-torsors. If T is inverse, then $\mathscr{B}(T)$ is equivalent to the usual classifying topos of T.

We must admit that outside the inverse case we know very little about $\mathscr{B}(T)$. A closer examination of γ may be revealing.

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