

1. Find a basis of the row and column space of  $A$  and determine the rank of  $A$ , where  $A$  is the matrix

$$\begin{bmatrix} 1 & -2 & 3 & 0 & 0 \\ 2 & -5 & 6 & -3 & -2 \\ 0 & 5 & 0 & 15 & 10 \\ 2 & 6 & 6 & 18 & 8 \end{bmatrix}$$

We first find a row-echelon form of  $A$ :

$$\begin{aligned} & \begin{bmatrix} 1 & -2 & 3 & 0 & 0 \\ 2 & -5 & 6 & -3 & -2 \\ 0 & 5 & 0 & 15 & 10 \\ 2 & 6 & 6 & 18 & 8 \end{bmatrix} \sim \begin{bmatrix} 1 & -2 & 3 & 0 & 0 \\ 0 & -1 & 0 & -3 & -2 \\ 0 & 5 & 0 & 15 & 10 \\ 0 & 10 & 0 & 18 & 8 \end{bmatrix} \sim \begin{bmatrix} 1 & -2 & 3 & 0 & 0 \\ 0 & 1 & 0 & 3 & 2 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & -12 & -12 \end{bmatrix} \\ (2) \quad & \sim \begin{bmatrix} \textcircled{1} & -2 & 3 & 0 & 0 \\ 0 & \textcircled{1} & 0 & 3 & 2 \\ 0 & 0 & 0 & \textcircled{1} & 1 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix} = A' \end{aligned}$$

(1) } The non-zero rows of  $A'$  are a basis of the row-space of  $A$ :

$$\{ [1, -2, 3, 0, 0]^T, [0, 1, 0, 3, 2]^T, [0, 0, 0, 1, 1]^T \}$$

(1) } The columns corresponding to the leading 1's of  $A'$  are a basis of the column space of  $A$ :

$$\left\{ \begin{bmatrix} 1 \\ 2 \\ 0 \\ 2 \end{bmatrix}, \begin{bmatrix} -2 \\ -5 \\ 5 \\ 6 \end{bmatrix}, \begin{bmatrix} 3 \\ -3 \\ 15 \\ 18 \end{bmatrix} \right\}$$

(1) }  $A$  has rank 3

2. Use the Gram-Schmidt algorithm to convert the basis

$$[1 \ -1 \ 1]^T, [1 \ 0 \ 1]^T, [1 \ 1 \ 2]^T$$

of  $\mathbb{R}^3$  to an orthogonal basis.

$$(2) \left\{ \begin{aligned} F_1 &= X_1 = [1, -1, 1]^T \\ F_2 &= X_2 - \frac{X_2 \cdot F_1}{F_1 \cdot F_1} F_1 = [1 \ 0 \ 1]^T - \frac{[1 \ 0 \ 1]^T \cdot [1, -1, 1]^T}{1+1+1} [1, -1, 1]^T \\ &= [1 \ 0 \ 1]^T - \frac{2}{3} [1, -1, 1]^T = \left[ \frac{1}{3}, \frac{2}{3}, \frac{1}{3} \right]^T = \frac{1}{3} [1, 2, 1]^T \end{aligned} \right.$$

$$(2) \left\{ \begin{aligned} F_3 &= X_3 - \frac{X_3 \cdot F_2}{F_2 \cdot F_2} F_2 - \frac{X_3 \cdot F_1}{F_1 \cdot F_1} F_1 = \\ &= [1, 1, 2]^T - \frac{[1, 1, 2]^T \cdot [1, 2, 1]^T}{\frac{1}{9}(1+4+1)} \frac{1}{3} [1, 2, 1]^T - \frac{[1, 1, 2]^T \cdot [1, -1, 1]^T}{3} [1, -1, 1]^T \\ &= [1, 1, 2]^T - \frac{5}{6} [1, 2, 1]^T - \frac{2}{3} [1, -1, 1]^T \\ &= \left[ 1 - \frac{5}{6} - \frac{2}{3}, 1 - \frac{5}{2} + \frac{2}{3}, 2 - \frac{5}{6} - \frac{2}{3} \right]^T = \left[ -\frac{1}{2}, 0, \frac{1}{2} \right]^T \\ &= \frac{1}{2} [-1, 0, 1]^T \end{aligned} \right.$$

Hence, the Gram-Schmidt algorithm provides the orthogonal basis

$$\left\{ [1, -1, 1]^T, \frac{1}{3} [1, 2, 1]^T, \frac{1}{2} [-1, 0, 1]^T \right\}$$

Note Since we are only interested in an orthogonal basis, we can multiply any basis vector by a non-zero scalar. This will yield another orthogonal basis. For example,

$$\left\{ [1, -1, 1]^T, [1, 2, 1]^T, [-1, 0, 1]^T \right\}$$

is also an orthogonal basis

3. Write the vector  $X$  as a sum of a vector in  $U$  and in  $U^\perp$ :

$$X = [1 \ 1 \ 1]^T, \quad U = \text{Span}\{[1 \ -1 \ 2]^T, [3 \ -1 \ 4]^T\}.$$

We first find an orthogonal basis of  $U$ , by applying the Gram-Schmidt algorithm:

$$F_1 = X_1 = [1, -1, 2]^T$$

$$\begin{aligned} F_2 &= X_2 - \frac{X_2 \cdot F_1}{F_1 \cdot F_1} F_1 = [3, -1, 4]^T - \frac{[3, -1, 2]^T \cdot [1, -1, 4]^T}{1+1+4} [1, -1, 2]^T \\ &= [3, -1, 4]^T - \frac{3+1+8}{6} [1, -1, 2]^T = [3, -1, 4]^T - 2[1, -1, 2]^T \\ &= [1, 1, 0]^T \end{aligned}$$

Thus,  $\{[1, -1, 2]^T, [1, 1, 0]^T\}$  is an orthogonal basis of  $U$ .

We can now apply the projection formula (lemma 1)

$$\begin{aligned} \text{proj}_U(X) &= \frac{X \cdot F_1}{F_1 \cdot F_1} F_1 + \frac{X \cdot F_2}{F_2 \cdot F_2} F_2 = \frac{[1, 1, 1]^T \cdot [1, -1, 2]^T}{1+1+4} F_1 + \frac{[1, 1, 1]^T \cdot [1, 1, 0]^T}{1+1} F_2 \\ &= \frac{2}{6} [1, -1, 2]^T + \frac{2}{2} [1, 1, 0]^T = \frac{1}{3} [4, 2, 2]^T \end{aligned}$$

We obtain the component of  $X$  in  $U^\perp$  as

$$X - \text{proj}_U(X) = [1, 1, 1]^T - \frac{1}{3} [4, 2, 2]^T = \frac{1}{3} [-1, 1, 1]^T$$

Hence

$$X = \text{proj}_U(X) + (X - \text{proj}_U(X)) = \frac{1}{3} \begin{bmatrix} 4 \\ 2 \\ 2 \end{bmatrix} + \frac{1}{3} \begin{bmatrix} -1 \\ 1 \\ 1 \end{bmatrix}$$

where  $\frac{1}{3} \begin{bmatrix} 4 \\ 2 \\ 2 \end{bmatrix} \in U$  and  $\frac{1}{3} \begin{bmatrix} -1 \\ 1 \\ 1 \end{bmatrix} \in U^\perp$ .

1. Find the best approximation to a solution of the following linear system:

$$\begin{aligned}x - y &= 3 \\2x + y &= -1 \\x + 5y &= -1\end{aligned}$$

The coefficient matrix is  $A = \begin{bmatrix} 1 & -1 \\ 2 & 1 \\ 1 & 5 \end{bmatrix}$ , and  $B = \begin{bmatrix} 3 \\ -1 \\ -1 \end{bmatrix}$ . Hence

$$A^T A = \begin{bmatrix} 1 & 2 & 1 \\ -1 & 1 & 5 \end{bmatrix} \begin{bmatrix} 1 & -1 \\ 2 & 1 \\ 1 & 5 \end{bmatrix} = \begin{bmatrix} 6 & 6 \\ 6 & 27 \end{bmatrix}, \text{ and}$$

$$A^T B = \begin{bmatrix} 1 & 2 & 1 \\ -1 & 1 & 5 \end{bmatrix} \begin{bmatrix} 3 \\ -1 \\ -1 \end{bmatrix} = \begin{bmatrix} -3 \\ -24 \end{bmatrix}. \text{ The normal equation}$$

$$(A^T A)z = A^T B \text{ is therefore } \begin{aligned}6z_1 + 6z_2 &= -3 \\-6z_1 + 27z_2 &= -24\end{aligned}$$

We find the solution using Gaussian elimination:

$$\begin{bmatrix} 6 & 6 & -3 \\ 6 & 27 & -24 \end{bmatrix} \sim \begin{bmatrix} 6 & 6 & -3 \\ 0 & 21 & -21 \end{bmatrix} \sim \begin{bmatrix} 1 & 1 & -1/2 \\ 0 & 1 & -1 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & 1/2 \\ 0 & 1 & -1 \end{bmatrix}$$

Hence there is a unique solution (clear since  $A^T A$  is invertible)

$$z = \begin{bmatrix} 1/2 \\ -1 \end{bmatrix}$$

which is the best approximation to a solution of the given linear system.

$$\text{The vector } Az = \begin{bmatrix} 1 & -1 \\ 2 & 1 \\ 1 & 5 \end{bmatrix} \begin{bmatrix} 1/2 \\ -1 \end{bmatrix} = \begin{bmatrix} 3/2 \\ 0 \\ -9/2 \end{bmatrix} \text{ is as close to}$$

a solution as possible.

5. (3 extra points) (Continuation of question 5 of Assignment 2) Let  $U$  and  $V$  be subspaces of  $\mathbb{R}^n$ . Recall that then  $U \cap V = \{x \in \mathbb{R}^n : x \in U \text{ and } x \in V\}$  and  $U + V = \{x \in \mathbb{R}^n : x = u + v \text{ for some } u \in U \text{ and } v \in V\}$  are subspaces of  $\mathbb{R}^n$ . Show that

$$\dim U + \dim V = \dim(U + V) + \dim(U \cap V).$$

(Hint: If  $U \cap V \neq \{0\}$  let  $B$  be a basis of  $U \cap V$ , otherwise put  $B = \emptyset$ . By Theorem 3 of §4.3, one can extend  $B$  to a basis  $B_U$  of  $U$  and also to a basis  $B_V$  of  $V$ . Show that  $B_U \cup B_V$  is a basis of  $U + V$ .)

We proceed as in the hint, and write

$$B = \{x_1, \dots, x_k\} \quad (k=0 \text{ if } B = \emptyset)$$

$$B_U = \{x_1, \dots, x_k, y_1, \dots, y_l\}$$

$$B_V = \{x_1, \dots, x_k, z_1, \dots, z_m\}, \text{ hence}$$

$$B_U \cup B_V = \{x_1, \dots, x_k, y_1, \dots, y_l, z_1, \dots, z_m\}.$$

We show that

$$\bullet B_U \cup B_V \text{ is lin indep. } 0 = \sum_{a=1}^k s_a x_a + \sum_{b=1}^l r_b y_b + \sum_{c=1}^m p_c z_c$$

Hence

$$\sum_{a=1}^k s_a x_a + \sum_{b=1}^l r_b y_b = \sum_{c=1}^m (-p_c) z_c \in U \cap V$$

This vector is therefore a linear combination of  $x_1, \dots, x_k$ . Since the coefficients are unique, it follows from the expression above that all  $r_b = 0$  and all  $p_c = 0$ . But then  $0 = \sum_{a=1}^k s_a x_a$  forces all  $s_a = 0$ . Thus  $B_U \cup B_V$  is l.i.

$\bullet B_U \cup B_V$  spans  $U + V$ : Indeed, let  $x = u + v$  with  $u \in U$  and  $v \in V$ .

$$\text{We can write } u = \sum_{a=1}^k s_a x_a + \sum_{b=1}^l r_b y_b \text{ and } v = \sum_{a=1}^k s'_a x_a + \sum_{c=1}^m p_c z_c$$

Thus  $x = u + v = \sum_{a=1}^k (s_a + s'_a) x_a + \sum_{b=1}^l r_b y_b + \sum_{c=1}^m p_c z_c$  is a linear combination of  $B_U \cup B_V$ .

We have now shown that  $B_U \cup B_V$  is a basis of  $U + V$ , so  $\dim(U + V) = k + l + m$ , and the claim follows from

$$\begin{aligned} \dim U + \dim V &= (k + l) + (k + m) = (k + l + m) + k \\ &= \dim(U + V) + \dim(U \cap V). \end{aligned}$$