

1. (2 points) Suppose a directed graph has adjacency matrix

$$A = \begin{bmatrix} 1 & 0 & 1 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 1 & 0 & 1 \\ 1 & 0 & 0 & 0 \end{bmatrix}.$$

How many paths of length 2 are there from vertex 4 to vertex 2?

My answer: _____

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My answer: _____

Answer: By Theorem 5 in section 1.4, the number of paths of length 2 from vertex i to vertex j is the (i, j) -entry of A^2 , that is the dot product $R_i \cdot C_j$, where R_i is the i -th row and C_j is the j -th column of the adjacency matrix A of the graph. Thus, for the first question we have to calculate

$$R_4 \cdot C_2 = [1 \ 0 \ 0 \ 0] \cdot [0 \ 0 \ 1 \ 0] = 0$$

and for the second question we need to calculate

$$R_2 \cdot C_4 = [0 \ 0 \ 1 \ 0] \cdot [0 \ 0 \ 1 \ 0] = 1$$

Hence, the answers are 0 and 1.

2. (2 points) Let $A = \begin{bmatrix} 1 & 2 \\ -3 & 4 \end{bmatrix}$ and $B = \begin{bmatrix} -1 & 1 \\ 2 & 1 \end{bmatrix}$. Find $(AB)^{-1}(BA^T)^T$.

Answer: From the rules of matrix multiplication we get

$$(AB)^{-1}(BA^T)^T = B^{-1}A^{-1}(A^T)^T B^T = B^{-1}A^{-1}AB^T = B^{-1}B^T.$$

Since $\det(B) = -3$, we obtain

$$B^{-1}B^T = -\frac{1}{3} \begin{bmatrix} 1 & -1 \\ -2 & -1 \end{bmatrix} \begin{bmatrix} -1 & 2 \\ 1 & 1 \end{bmatrix} = -\frac{1}{3} \begin{bmatrix} -2 & 1 \\ 1 & -5 \end{bmatrix} = \frac{1}{3} \begin{bmatrix} 2 & -1 \\ -1 & 5 \end{bmatrix}$$

My answer: _____

3. (2 points) Let A , B and C be 3×3 matrices with $\det(A) = 3$, $\det(B) = 5$ and $\det(C) = 6$. Find the determinant of the 3×3 matrix M satisfying $AMB = C$.

Answer: By the product rule for determinants, we have

$$\det(AMB) = \det(A) \det(M) \det(B) = 3 \cdot 5 \det(M) = 15 \det(M).$$

But $AMB = C$, whence $\det(AMB) = \det(C) = 6$. Thus, $15 \det(M) = 6$, and therefore $\det(M) = \frac{6}{15} = \frac{2}{5}$.

My answer: _____

4. (2 points) Find the inverse of

$$A = \begin{bmatrix} 1 & i \\ -i & 2 \end{bmatrix}$$

Answer: The determinant of A is $2 + i^2 = 1$. Hence the inverse of A is

$$A^{-1} = \begin{bmatrix} 2 & -i \\ i & 1 \end{bmatrix}$$

My answer: _____

5. (3 points) The dimension of the subspace of \mathbb{R}^5 spanned by the vectors

$$[1 \ 0 \ 3 \ 1 \ 1]^T, \quad [1 \ -1 \ 7 \ -1 \ 0]^T, \quad [2 \ 1 \ 2 \ 4 \ 3]^T \quad \text{and} \quad [5 \ 1 \ 11 \ 7 \ 6]^T$$

is

Answer: The subspace is the same as the row space of the matrix A below. We can therefore apply Theorem 2 in section 4.4 to find its dimension:

$$A = \begin{bmatrix} 1 & 0 & 3 & 1 & 1 \\ 1 & -1 & 7 & -1 & 0 \\ 2 & 1 & 2 & 4 & 3 \\ 5 & 1 & 11 & 7 & 6 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & 3 & 1 & 1 \\ 0 & -1 & 4 & -2 & -1 \\ 0 & 1 & -4 & 2 & 1 \\ 0 & 1 & -4 & 2 & 1 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & 3 & 1 & 1 \\ 0 & 1 & -4 & 2 & 1 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

Thus, the rank of A is 2, which is then also the dimension of the subspace we are looking for.

My answer: _____

6. (3 points) Suppose that $T: \mathbb{M}_{2,2} \rightarrow \mathbb{P}_2$ is a linear transformation satisfying

$$T\left(\begin{bmatrix} 1 & 1 \\ 0 & 0 \end{bmatrix}\right) = x, \quad T\left(\begin{bmatrix} 0 & 1 \\ 0 & 1 \end{bmatrix}\right) = x^2, \quad T\left(\begin{bmatrix} 0 & 0 \\ 1 & 1 \end{bmatrix}\right) = 1 - x, \quad T\left(\begin{bmatrix} 0 & 0 \\ 0 & -1 \end{bmatrix}\right) = 5 - x^2.$$

Find $T\left(\begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}\right)$.

Answer: We write $\begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}$ as a linear combination of the four matrices, for which we know the value of T :

$$x_1 \begin{bmatrix} 1 & 1 \\ 0 & 0 \end{bmatrix} + x_2 \begin{bmatrix} 0 & 1 \\ 0 & 1 \end{bmatrix} + x_3 \begin{bmatrix} 0 & 0 \\ 1 & 1 \end{bmatrix} + x_4 \begin{bmatrix} 0 & 0 \\ 0 & -1 \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}$$

By comparing coefficients, this yields a linear system

$$x_1 = 1, \quad x_1 + x_2 = 0, \quad x_3 = 0, \quad x_2 + x_3 - x_4 = 0,$$

whose solution is $x_1 = 1$, $x_3 = 0$, $x_2 = -1 = x_4$. Thus,

$$\begin{aligned} T\left(\begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}\right) &= T\left(\begin{bmatrix} 1 & 1 \\ 0 & 0 \end{bmatrix} - \begin{bmatrix} 0 & 1 \\ 0 & 1 \end{bmatrix} - \begin{bmatrix} 0 & 0 \\ 0 & -1 \end{bmatrix}\right) \\ &= T\left(\begin{bmatrix} 1 & 1 \\ 0 & 0 \end{bmatrix}\right) - T\left(\begin{bmatrix} 0 & 1 \\ 0 & 1 \end{bmatrix}\right) - T\left(\begin{bmatrix} 0 & 0 \\ 0 & -1 \end{bmatrix}\right) \\ &= x - x^2 - (5 - x^2) = -5 + x. \end{aligned}$$

My answer: _____

7. (3 points) For an $n \times n$ matrix A answer the questions (ii), (iii) and (iv). As an example, I have given the answer for (i).

(i) State a condition on the columns of A which is equivalent to the condition $\text{rank}(A) < n$.

Answer: The columns of A are linearly dependent

(ii) State a condition on the determinant of A which is equivalent to the condition $\text{rank}(A) < n$.

Answer: $\det(A) = 0$

My answer: _____

(iii) State a condition regarding the homogeneous linear system $AX = 0$ which is equivalent to the condition $\text{rank}(A) < n$.

Answer: The homogeneous linear system $AX = 0$ has a non-trivial solution.

My answer: _____

(iv) State a condition on invertibility of A which is equivalent to the condition $\text{rank}(A) < n$.

Answer: A is not invertible.

My answer: _____

8. (4 points) Complete the formulas below:

(i) If A is an $m \times n$ matrix, then $n - \dim(\text{null}A) - \text{rank}(A) =$

Answer: $= 0$

My answer: _____

(ii) If A is an $m \times n$ matrix, then $\dim(\text{col}A) - \text{rank}(A) =$

Answer: $= 0$.

My answer: _____

(iii) $\dim \mathbb{P}_4 =$

Answer: $= 5$.

My answer: _____

(iv) $\dim \mathbb{M}_{2,4} =$

Answer: $= 8$.

My answer: _____

9. (4 points) Give the general solution of the system of first order differential equations

$$\begin{aligned} 2f_1 + 4f_2 &= f_1' \\ -3f_2 &= f_2' \end{aligned}$$

(Partial marks will be given for diagonalizing the coefficient matrix of the system.)

Answer: The system is equivalent to the system $Af = f'$ for

$$f = \begin{bmatrix} f_1 \\ f_2 \end{bmatrix} \quad \text{and} \quad A = \begin{bmatrix} 2 & 4 \\ 0 & -3 \end{bmatrix}$$

Since A is upper-triangular, the eigenvalues of A are the diagonal elements 2 and -3 . Since A has 2 distinct eigenvalues, it is diagonalizable. We find a basis of eigenvectors:

For $\lambda = 2$ we get

$$2I_2 - A = \begin{bmatrix} 0 & -4 \\ 0 & 5 \end{bmatrix} \sim \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix}.$$

Hence a basic eigenvector for $\lambda = 2$ is

$$X_1 = \begin{bmatrix} 1 \\ 0 \end{bmatrix}.$$

We proceed similarly for $\lambda = -3$:

$$-3I_2 - A = \begin{bmatrix} -5 & -4 \\ 0 & 0 \end{bmatrix} \sim \begin{bmatrix} 5 & 4 \\ 0 & 0 \end{bmatrix}$$

The corresponding equation is $5x_1 + 4x_2 = 0$. Hence

$$X_2 = \begin{bmatrix} 4 \\ -5 \end{bmatrix}$$

is a basic eigenvector for $\lambda = -3$. By Theorem 1 in section 2.8, the general solution of the system is

$$f(x) = c_1 e^{2x} \begin{bmatrix} 1 \\ 0 \end{bmatrix} + c_2 e^{-3x} \begin{bmatrix} 4 \\ -5 \end{bmatrix}$$

where $c_1, c_2 \in \mathbb{R}$ are arbitrary constants.

Marking: 3 points for finding e-values and a basis of e=vectors; 1 point for the general solution

10. (7 points) Determine the values of a for which the linear system

$$\begin{aligned}x + ay &= 1 \\ax + 4y &= 2\end{aligned}$$

has (i) no solution, (ii) a unique solution, (iii) infinitely many solutions. In case (iii) determine all solutions.

Answer: The augmented matrix of the system is

$$\begin{bmatrix} 1 & a & 1 \\ a & 4 & 2 \end{bmatrix} \sim \begin{bmatrix} 1 & a & 1 \\ 0 & 4 - a^2 & 2 - a \end{bmatrix}$$

Since $4 - a^2 = (2 - a)(2 + a)$ we get the following cases:

(i) No solution: This is the case when we have a row of type $[0 \ 0 \ 1]$ in a row-echelon form of the augmented matrix. Hence, this is the case if and only if $4 - a^2 = 0$ and $a \neq 2$, which is equivalent to $a = -2$.

(ii) A unique solution: This is the case when the augmented matrix has rank 2, but we do not have a row of type $[0 \ 0 \ 1]$ in a row-echelon form of A . Hence, this is the case exactly when $4 - a^2 \neq 0$, i.e., $a \neq 2$ and $a \neq -2$.

(iii) Infinitely many solutions: The rank of the augmented matrix is 1, i.e., $2 - a = 0 = 4 - a^2$, which is equivalent to $a = 2$. In this case, a row-echelon form of the augmented matrix is

$$\begin{bmatrix} 1 & 2 & 1 \\ 0 & 0 & 0 \end{bmatrix}$$

Hence the corresponding linear system becomes $x + 2y = 1$, whose solutions are

$$\begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} 1 - 2t \\ t \end{bmatrix}$$

where t is a free parameter.

Marking: 3 points for row-reduction; 1 point each for finding the cases (ii)–(iii); 1 point for solution in case (iii)

11. (6 points) The characteristic polynomial of the matrix

$$A = \begin{bmatrix} 3 & 1 & -1 \\ -1 & 1 & 1 \\ 2 & 2 & 0 \end{bmatrix}$$

is $x(x-2)^2$. (You do not need to show this.)

(a) (4 points) For each eigenvalue of A find a basis of the corresponding eigenspace.

(b) (2 points) Decide if A is diagonalizable or not. If yes, give an invertible matrix P and a diagonal matrix D such that $P^{-1}AP = D$. If no, explain why not.

Answer: Since the eigenvalues are the roots of the characteristic polynomials, A has eigenvalues 2 and 0. For each eigenvalue λ , the corresponding eigenspace is the set of solutions of the homogenous linear system $(\lambda I_3 - A)$.

$\lambda = 2$: We row-reduce

$$2I_3 - A = \begin{bmatrix} -1 & -1 & -1 \\ 1 & 1 & 1 \\ -2 & -2 & -2 \end{bmatrix} \sim \begin{bmatrix} 1 & 1 & 1 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

The corresponding linear system is $x + y - z = 0$ or $x = -y + z$. The general solution is

$$\begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} -s + t \\ s \\ t \end{bmatrix} = s \begin{bmatrix} -1 \\ 1 \\ 0 \end{bmatrix} + t \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}$$

where s and t are free parameters. Hence the eigenspace $E_2(A)$ has

$$\begin{bmatrix} -1 \\ 1 \\ 0 \end{bmatrix}, \quad \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}$$

as a basis, and thus $\dim E_2(A) = 2$.

$\lambda = 0$: We row-reduce

$$\begin{aligned} 0I_3 - A &= \begin{bmatrix} -3 & -1 & 1 \\ 1 & -1 & -1 \\ -2 & -2 & 0 \end{bmatrix} \stackrel{(1)}{\sim} \begin{bmatrix} 1 & -1 & -1 \\ -3 & -1 & 1 \\ -2 & -2 & 0 \end{bmatrix} \stackrel{(2)}{\sim} \begin{bmatrix} 1 & -1 & -1 \\ 0 & -4 & -2 \\ 0 & -4 & -2 \end{bmatrix} \stackrel{(3)}{\sim} \begin{bmatrix} 1 & -1 & -1 \\ 0 & 2 & 1 \\ 0 & 0 & 0 \end{bmatrix} \\ &\stackrel{(4)}{\sim} \begin{bmatrix} 1 & -1 & -1 \\ 0 & 1 & 1/2 \\ 0 & 0 & 0 \end{bmatrix} \stackrel{(5)}{\sim} \begin{bmatrix} 1 & 0 & -1/2 \\ 0 & 1 & 1/2 \\ 0 & 0 & 0 \end{bmatrix} \end{aligned}$$

Explanations: (1): exchange rows 1 and 2; (2): replace row R2 by R2+3R1 and row R3 by R3 +2R1; (3): replace row R3 by R3-R2 etc. Hence the corresponding linear system is $x = (1/2)z$ and $y = -(1/2)z$. Its general solution is

$$\begin{bmatrix} (1/2)s \\ -(1/2)s \\ s \end{bmatrix} = s \begin{bmatrix} 1/2 \\ -1/2 \\ 1 \end{bmatrix}$$

where s is a free parameter. Thus, a basis of the eigenspace $E_0(A)$ is

$$\begin{bmatrix} 1/2 \\ -1/2 \\ 1 \end{bmatrix}$$

(b) Since the dimensions of the eigenspaces add up to 3, the matrix is diagonalizable. Matrixes P and D as required in (b) are

$$P = \begin{bmatrix} -1 & 1 & -1/2 \\ 1 & 0 & 1/2 \\ 0 & 1 & 1 \end{bmatrix} \quad \text{and} \quad D = \begin{bmatrix} 2 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

Note that P and D are not unique.

Marking: Correct calculations, but basis not stated: -1; eigenspace $\{0\}$: -2; in (b) it is sufficient just to give the matrices P and D ;

Wrong answers in (b): A is not diagonalizable since its determinant is 0; A is not diagonalizable since it has only 2 eigenvalues; A is diagonalizable since it has 3 eigenvectors; A is not diagonalizable since the elements of the matrix are linearly independent;

12. (8 points) Let

$$\begin{bmatrix} 2 & 6 & 10 & 4 \\ 1 & 3 & 6 & 1 \\ 3 & 9 & 14 & 7 \end{bmatrix}.$$

- (a) (4 points) Find the reduced row-echelon form of A .
 (b) (1 points) Give a basis of the row space $\text{row}(A)$ of A .
 (c) (1 points) Give a basis of the column space $\text{col}(A)$ of A .
 (d) (2 points) Give a basis of the null space $\text{null}(A)$.

Answer: (a)

$$A \sim \begin{bmatrix} 1 & 3 & 6 & 1 \\ 2 & 6 & 10 & 4 \\ 3 & 9 & 14 & 7 \end{bmatrix} \sim \begin{bmatrix} 1 & 3 & 6 & 1 \\ 0 & 0 & -2 & 2 \\ 0 & 0 & -4 & 4 \end{bmatrix} \sim \begin{bmatrix} 1 & 3 & 0 & 7 \\ 0 & 0 & 1 & -1 \\ 0 & 0 & 0 & 0 \end{bmatrix} = \text{ref}(A).$$

(b) A basis of the row space is given by the non-zero rows of $\text{ref}(A)$ (Thm. 1 in section 4.4):

$$[1 \ 3 \ 0 \ 7], \quad [0 \ 0 \ 1 \ -1].$$

(c) By Theorem 2 in section 4.4, a basis of the column space of A is given by those columns of A corresponding to the columns of $\text{ref}(A)$ with a leading 1. These are the columns 1 and 3. Hence a basis of $\text{col}(A)$ is

$$\begin{bmatrix} 2 \\ 1 \\ 3 \end{bmatrix}, \quad \begin{bmatrix} 10 \\ 6 \\ 14 \end{bmatrix}.$$

(d) The null space of A is the set of solutions of the linear system $AX = 0$, which is equivalent to $\text{ref}(A)X = 0$. The latter system has the form

$$\begin{array}{cccc} x_1 & + & 3x_2 & & + & 7x_4 & = & 0 \\ & & & x_3 & - & x_4 & = & 0 \end{array}$$

We see that x_2 and x_4 are free variables, and that the general solution of this system is

$$\begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} = \begin{bmatrix} -3s - 7t \\ s \\ t \\ t \end{bmatrix} = s \begin{bmatrix} -3 \\ 1 \\ 0 \\ 0 \end{bmatrix} + t \begin{bmatrix} -7 \\ 0 \\ 1 \\ 1 \end{bmatrix}$$

where s and t are free parameters. Hence a basis of $\text{null}(A)$ is

$$\begin{bmatrix} -3 \\ 1 \\ 0 \\ 0 \end{bmatrix}, \quad \begin{bmatrix} -7 \\ 0 \\ 1 \\ 1 \end{bmatrix}.$$

Marking: Basis = spanning set: errors in the ref: -1 or -2, depending on error;

13. (7 points) Let

$$U = \{A \in \mathbb{M}_{3,3} : A + A^T = 0\}.$$

For example, the matrix

$$\begin{bmatrix} 0 & 1 & 2 \\ -1 & 0 & 3 \\ -2 & -3 & 0 \end{bmatrix}$$

lies in U , since if we add the matrix and its transpose we obtain the zero matrix.

(a) (3 points) Show that U is a subspace of $\mathbb{M}_{3,3}$.

(b) (3 points) Find a basis of U .

(c) (1 point) Determine the dimension of U .

Answer: (a) We can apply the subspace test.

(1) The zero matrix satisfies $0^T + 0 = 0 + 0 = 0$ so 0 is in U .

(2) Given A, B in U , we have that $A + A^T = 0$ and $B + B^T = 0$. Thus $(A + B) + (A + B)^T = A + B + A^T + B^T = (A + A^T) + (B + B^T) = 0 + 0 = 0$ so $A + B$ is also in U .

(3) Given A in U and c a scalar, we have $(cA) + (cA)^T = cA + cA^T = c(A + A^T) = c0 = 0$ so cA is in U .

Thus U satisfies all three tests and is a subspace of $\mathbb{M}_{3,3}$.

(b) If

$$A = \begin{bmatrix} a & b & c \\ d & e & f \\ g & h & i \end{bmatrix}$$

then

$$A + A^T = \begin{bmatrix} 2a & b+d & c+g \\ b+d & 2e & f+h \\ c+g & f+h & 2i \end{bmatrix}$$

So we deduce that A is in U if and only if

$$a = e = i = 0, b = -d, c = -g, f = -h$$

so

$$U = \left\{ \begin{bmatrix} 0 & b & c \\ -b & 0 & f \\ -c & -f & 0 \end{bmatrix} : b, c, f \in \mathbb{R} \right\}$$

In particular, this says that any matrix in U has the form

$$b \begin{bmatrix} 0 & 1 & 0 \\ -1 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} + c \begin{bmatrix} 0 & 0 & 1 \\ 0 & 0 & 0 \\ -1 & 0 & 0 \end{bmatrix} + f \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & -1 & 0 \end{bmatrix}$$

so U is the span of the three matrices

$$\begin{bmatrix} 0 & 1 & 0 \\ -1 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 & 1 \\ 0 & 0 & 0 \\ -1 & 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & -1 & 0 \end{bmatrix}.$$

Furthermore, these are linearly independent (since the only linear combination that can make the zero matrix is the trivial one). Hence this is a basis for U .

(c) Since there are 3 vectors in a basis, this is a 3 dimensional subspace of $\mathbb{M}_{3,3}$.

Marking: (b) Just giving a basis: 1/3; proving spanning without verifying linear independence 2/3.

Mistakes: Row-reducing the example matrix to find a basis of U ; calculating the characteristic polynomial of the given example matrix.

Some wrong answers: “ U is a subspace since U must fit within the subspace of $\mathbb{M}_{3,3}$ since otherwise dimensions will be left out.”

14. (7 points) Let U be the span of the following set of vectors in \mathbb{R}^4 :

$$\left\{ \begin{bmatrix} 1 \\ -1 \\ 2 \\ 0 \end{bmatrix}, \begin{bmatrix} 3 \\ 3 \\ 0 \\ 1 \end{bmatrix}, \begin{bmatrix} -1 \\ 1 \\ 1 \\ 0 \end{bmatrix} \right\}$$

- (i) (2 points) Show that these vectors are orthogonal.
 (ii) (1 points) What is $\dim(U)$?
 (iii) (1 points) What is $\dim(U^\perp)$?
 (iv) (3 points) Calculate the orthogonal projection of the vector $v = [1 \ 2 \ 3 \ 1]^T$ onto U .

Answer: (i) We have that

$$[1 \ -1 \ 2 \ 0]^T \cdot [3 \ 3 \ 0 \ 1]^T = 3 - 3 + 0 + 0 = 0$$

$$[1 \ -1 \ 2 \ 0]^T \cdot [-1 \ 1 \ 1 \ 0]^T = -1 - 1 + 2 + 0 = 0$$

and

$$[3 \ 3 \ 0 \ 1]^T \cdot [-1 \ 1 \ 1 \ 0]^T = -3 + 3 + 0 + 0 = 0$$

Since all pairwise dot products are zero, this is an orthogonal set of vectors in \mathbb{R}^4 .

(ii) Since the set is orthogonal, it is linearly independent. Therefore it is a basis for its span U . Hence $\dim(U) = 3$.

(iii) Since $\dim(U) + \dim(U^\perp) = \dim(\mathbb{R}^4)$ and $\dim(U) = 3$ we deduce $\dim(U^\perp) = 4 - 3 = 1$.

(iv) Since we have an orthogonal basis (call it $\{X_1, X_2, X_3\}$), we can apply the projection formula:

$$\text{proj}_U(X) = \frac{X \cdot X_1}{\|X_1\|^2} X_1 + \frac{X \cdot X_2}{\|X_2\|^2} X_2 + \frac{X \cdot X_3}{\|X_3\|^2} X_3$$

Here $X = [1 \ 2 \ 3 \ 1]^T$, so

$$X \cdot X_1 = 5, X \cdot X_2 = 10, X \cdot X_3 = 4$$

and

$$\|X_1\|^2 = 6, \|X_2\|^2 = 19, \|X_3\|^2 = 3.$$

So

$$\begin{aligned} \text{proj}_U(X) &= \frac{5}{6} \begin{bmatrix} 1 \\ -1 \\ 2 \\ 0 \end{bmatrix} + \frac{10}{19} \begin{bmatrix} 3 \\ 3 \\ 0 \\ 1 \end{bmatrix} + \frac{4}{3} \begin{bmatrix} -1 \\ 1 \\ 1 \\ 0 \end{bmatrix} = \frac{95}{114} \begin{bmatrix} 1 \\ -1 \\ 2 \\ 0 \end{bmatrix} + \frac{60}{114} \begin{bmatrix} 3 \\ 3 \\ 0 \\ 1 \end{bmatrix} + \frac{152}{114} \begin{bmatrix} -1 \\ 1 \\ 1 \\ 0 \end{bmatrix} \\ &= \frac{1}{114} \begin{bmatrix} 123 \\ 237 \\ 342 \\ 60 \end{bmatrix} = \frac{1}{38} \begin{bmatrix} 41 \\ 79 \\ 114 \\ 20 \end{bmatrix} \end{aligned}$$

We can check that this is correct by verifying that $X - \text{proj}_U(X) = \frac{1}{114} [-9 \ -9 \ 0 \ 54]^T$ is orthogonal to U .

Another approach to (iv): Let's find a basis for U^\perp , which is one-dimensional. If $U = \text{row}(A)$ then $U^\perp = \text{Null}(A)$ so:

$$\begin{bmatrix} 1 & -1 & 2 & 0 \\ 3 & 3 & 0 & 1 \\ -1 & 1 & 1 & 0 \end{bmatrix} \sim \begin{bmatrix} 1 & -1 & 2 & 0 \\ 0 & 6 & -6 & 1 \\ 0 & 0 & 3 & 0 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & 0 & \frac{1}{6} \\ 0 & 1 & 0 & \frac{1}{6} \\ 0 & 0 & 1 & 0 \end{bmatrix}$$

and so a basis for the nullspace U^\perp is $Y = [-1 \ -1 \ 0 \ 6]^T$. Therefore

$$\text{proj}_{U^\perp} X = \frac{X \cdot Y}{\|Y\|^2} Y = \frac{3}{38} \begin{bmatrix} -1 \\ -1 \\ 0 \\ 6 \end{bmatrix}$$

and so

$$\text{proj}_U(X) = X - \text{proj}_{U^\perp}(X) = \begin{bmatrix} 1 \\ 2 \\ 3 \\ 1 \end{bmatrix} - \frac{3}{38} \begin{bmatrix} -1 \\ -1 \\ 0 \\ 6 \end{bmatrix} = \frac{1}{38} \begin{bmatrix} 41 \\ 79 \\ 114 \\ 20 \end{bmatrix}$$

Marking: (a) -1 if orthogonality only checked for the first vectors; (d) -1 if some calculation error but method correct; full marks if the projection vector was given as the correct linear comb of the orthogonal basis, but was not simplified; formula wrong: $1/3$.

Some mistakes: Calculating the vector approximately, i.e., replacing the fractions by integers!!! Using the formula for the component of X in U^\perp , instead of the projection on U .

Not really a mistake but too complicated: Applying Gram-Schmidt to check orthogonality; determining the dimension of U by row-reducing the matrix whose rows (or columns) are the given three vectors.

15. (2 bonus points). The following statement is a theorem that we have seen in class, except that one of the hypotheses is missing. Write down the missing hypothesis.

Let v_1, \dots, v_n be vectors in a vector space V . Suppose that

If one of the conditions

- (i) $\{v_1, \dots, v_n\}$ is a linearly independent set
 - (ii) $\{v_1, \dots, v_n\}$ is a spanning set for V
- is satisfied, then both of them are satisfied.

Answer: Missing hypothesis: $\dim(V) = n$

Marking: Some wrong answers: V is diagonalizable; V is invertible; the v_i are orthogonal;

16. (2 bonus points) Complete the following definition:

“Vectors v_1, \dots, v_n of a vector space V are called *linearly dependent* if there are real numbers $a_1, \dots, a_n \in \mathbb{R}$ such that

Answer: ... such that $a_1 v_1 + \dots + a_n v_n = 0$ and not all of the a_i are zero.

Marking: Some wrong answers: $a_1 v_1 + \dots + a_n v_n \neq 0$; “all vectors v_1, \dots, v_n can be divided to form a single vector”; giving the definition of linear independence instead of linear dependence (1/2).