Transformations Groups of the Andersson-Perlman Cone

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Abstract. An Andersson-Perlman cone is a certain subcone $\Omega(\mathcal{K})$ of the symmetric cone Ω of a Euclidean Jordan algebra. We exhibit a subgroup of the automorphism group of Ω which operates transitively on $\Omega(\mathcal{K})$ and show that $\Omega(\mathcal{K})$ is a simply-connected submanifold of Ω .

1. Introduction.

Andersson-Perlman cones in the setting of Euclidean Jordan algebras (henceforth abbreviated as AP cones) were introduced by H. Massam and the author in [MN] as a generalization of certain cones defined by the statisticians S. A. Andersson and M. D. Perlman for real symmetric matrices [AP]. All mathematical results in [AP] were generalized in [MN] to the setting of Euclidean Jordan algebras, except the existence of transitive transformation groups which play a predominant role in the development in [AP]. In fact, the paper [MN] stresses a different, perhaps more direct approach to the description of Andersson-Perlman cones by employing Peirce decompositions and Frobenius transformations.

In this note we show that one can also generalize the results of [AP] on transitive groups to the framework of Andersson-Perlman cones in Euclidean Jordan algebras. Our interest in these groups is explained in the following remarks. An Andersson-Perlman cone is a subcone $\Omega(\mathcal{K})$ of the cone Ω of an Euclidean Jordan algebra V defined in terms of a complete orthogonal system $\mathcal{E} = (e_1, \ldots, e_n)$ of idempotents of V and a ring \mathcal{K} of subsets of $I = \{1, \ldots, n\}$, see 6. If Ω_i denotes the symmetric cone of the Peirce-1-space $V(e_i, 1)$ of e_i then always

$$\Omega_1 \oplus \Omega_2 \oplus \cdots \oplus \Omega_n \subset \Omega(\mathcal{K}) \subset \Omega$$

and both upper and lower bounds can be obtained by varying \mathcal{K} . Thus, one may consider $\Omega(\mathcal{K})$ as an interpolation between Ω and $\Omega_1 \oplus \Omega_2 \oplus \cdots \oplus \Omega_n$. In the

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same spirit, the transitive transformation group T (denoted $T_{\mathcal{E},\preceq}$ in the paper) of $\Omega(\mathcal{K})$ interpolates various well-known subgroups of the automorphism group $G(\Omega) = \{g \in \mathrm{GL}(V); g\Omega = \Omega\}$ of Ω . In general, T is a semidirect product of a unipotent subgroup N of $G(\Omega)$ (denoted $N_{\mathcal{E},\prec}$ in the paper) and the real reductive group

$$M_{\mathcal{E}} = \{ g \in G(\Omega); g\Omega_i = \Omega_i \} = P(\Omega_1 \oplus \Omega_2 \oplus \cdots \oplus \Omega_n) \cdot K_{\mathcal{E}}$$
 (1)

where $K_{\mathcal{E}} = \{ f \in \text{Aut } V; fe_i = e_i \text{ for } 1 \leq i \leq n \}$. Observe that (1) is the Cartan decomposition of $M_{\mathcal{E}}$. We always have

$$M_{\mathcal{E}} \subset T = M_{\mathcal{E}} \cdot N \subset G(\Omega),$$
 (2)

and both bounds are attained. For example, if $\Omega(\mathcal{K}) = \Omega$ and \mathcal{E} is a Jordan frame then N is the so-called strict triangular subgroup [FK], while if $\mathcal{E} = \{e\}(n=1)$ then also $\Omega(\mathcal{K}) = \Omega$, $N = \{\text{Id}\}$ and $M_{\mathcal{E}} = G(\Omega)$. In this case, (1) is just the standard Cartan decomposition of $G(\Omega)$.

2. Notation and review.

Our basic reference for Jordan algebras is [FK]. Some of the results and notations used are summarized below.

Throughout, V denotes a Euclidean Jordan algebra with identity element e, left multiplication L(u) defined by $L(u)v = uv(u, v \in V)$ and quadratic representation P given by $P(u)v = 2u(uv) - u^2v$. The linearization of P is

$$\{u \, v \, w\} := P(u, w)v := P(u + w)v - P(u)v - P(w)v$$

$$= 2u(vw) + 2w(uv) - 2(uw)v$$

for $(u, v, w \in V)$. The Jordan triple system left multiplication L(u, v) (denoted $u \square v$ in [FK]) is given by L(u, v) = 2(L(uv) + [L(u), L(v)]) and hence L(u, v)w = P(u, w)v. For any endomorphism φ of V, φ^* is the adjoint of φ with respect to the positive definite trace form of V.

We will use the term "Lie group" and "Lie subgroup" as defined in [B]. In particular, any Lie subgroup of a Lie group is closed and has the induced topology. Closed subgroups of a Lie group are always Lie subgroups in a unique way.

We denote the symmetric cone of V by $\Omega = \Omega(V)$. This is an open convex cone which is homogeneous with respect to the group $G(\Omega) = \{g \in \operatorname{GL}(V); g\Omega = \Omega\}$, the automorphism group of Ω . The group $G(\Omega)$ is a Lie subgroup of $\operatorname{GL}_{\mathbb{R}}(V)$. Its identity component will be denoted by G. Moreover, $G(\Omega)$ is an open subgroup of the structure group of V, defined as the group of all invertible endomorphisms g of V with the property

$$P(gx) = gP(x)g^* \tag{1}$$

for all $x \in V$, or, equivalently,

$$gL(u,v)g^{-1} = L(gu,g^{*-1}v)$$
 (1')

for all $u, v \in V$ ([FK; III.5 and VIII.2]). The Lie algebra $\mathfrak{g}(V)$ of the structure group of V coincides with the Lie algebra of $G(\Omega)$. It consists of all endomorphisms X of V satisfying for all $u, v \in V$

$$[X, L(u, v)] = L(Xu, v) - L(u, X^*v)$$
(2)

([FK; VIII.2.6]). The group of automorphisms of V will be denoted Aut V. For any $g \in G(\Omega)$ one knows ([FK; III.5] and [FK; VIII.2.4]):

$$ge = e \Leftrightarrow gg^* = Id \Leftrightarrow g \in \operatorname{Aut} V$$
 (3)

In particular, Aut V is a maximal compact subgroup of $G(\Omega)$.

Following [FK] we denote the Peirce spaces of an idempotent $c \in V$ by $V(c,i) = \{v \in V; cv = iv\}, i \in \{0,\frac{1}{2},1\}$. The Peirce decomposition of an arbitrary $y \in V$ is written in the form $y = y_1 + y_{12} + y_0$ where $y_i \in V(c,i)$ for i = 0,1 and $y_{12} \in V(c,\frac{1}{2})$. The symmetric cone of the Euclidean Jordan algebra V(c,1) will be denoted Ω_c . For an idempotent c and $z \in V(c,\frac{1}{2})$ the Frobenius transformation on V is defined as $\tau_c(z) = \exp(L(z,c)) \in G$. It is straightforward to check that $\tau_c : V(c,\frac{1}{2}) \to G$ is a homomorphism, thus $\tau_c(z+z') = \tau_c(z)\tau_c(z')$ and $\tau_c(-z) = \tau_c(z)^{-1}$. If $x = x_1 + x_{12} + x_0$ is the Peirce decomposition of $x \in V$ with respect to c then

$$\tau_c(z)x = x_1 \oplus 2zx_1 + x_{12} \oplus 2(e - c)[z(zx_1) + zx_{12}] + x_0$$

$$= x_1 \oplus 2zx_1 + x_{12} \oplus P(z)x_1 + 2(e - c)(zx_{12}) + x_0.$$
(4)

The adjoint of the Frobenius transformation operates as follows [MN; 2.7]:

$$\tau_c(z)^*x = (x_1 + 2c(zx_{12}) + P(z)x_0) \oplus (x_{12} + 2zx_0) \oplus x_0.$$
 (5)

3. Frobenius transformations with respect to an orthogonal system.

Throughout, we fix a complete orthogonal system $\mathcal{E} = (e_1, \ldots, e_n)$ of (arbitrary) idempotents of V. Thus, $e_i e_j = \delta_{ij} e_i$ and $e_1 + \cdots + e_n = e$. We denote by V_{ij} , $1 \leq i, j \leq n$, the Peirce spaces of \mathcal{E} [FK IV.2] and define, for $1 \leq i < n$, subspaces

$$V^{(i)} := \bigoplus_{k=i+1}^{n} V_{ik} = V(e_i, \frac{1}{2}) \cap V(e_{i+1} + \dots + e_n, \frac{1}{2}).$$

For $x \in V$ we let $x = \sum_{i \leq j} x_{ij}, x_{ij} \in V_{ij}$, be the Peirce decomposition of $x \in V$. We abbreviate $\tau_i = \tau_{e_i}$ and $\Omega_i = \Omega_{e_i} = \Omega(V_{ii}), 1 \leq i \leq n$. By [MN; 2.8] the map

$$F: V^{(1)} \times \cdots \times V^{(n-1)} \times \Omega_1 \times \cdots \times \Omega_n \rightarrow \Omega$$

given by

$$F(z_1, \dots, z_{n-1}, y_1, \dots y_n) := \tau_1(z_1) \dots \tau_{n-1}(z_{n-1})(y_1 \oplus \dots \oplus y_n)$$
$$= \tau_1(z_1)y_1 + \tau_2(z_2)y_2 + \dots + \tau_{n-1}(z_{n-1})y_{n-1} + y_n$$

is a bijection. Even more, we have:

Proposition 3. The map F is a diffeomorphism.

Proof. It follows from the definition of the Frobenius transformation that F is differentiable. Since both manifolds have the same dimension, it suffices to show that the tangent map $T_{\zeta}F$ of F in a point $\zeta=(z_1,\cdots,z_{n-1},y_1,\cdots y_n)\in M:=V^{(1)}\times\cdots\times V^{(n-1)}\times\Omega_1\times\cdots\times\Omega_n$ is injective. For n=2 and $(u_1,v_1,v_2)\in V_{12}\times V_{11}\times V_{22}=T_{\zeta}M$, the tangent space of M at ζ , we have

$$T_{\zeta}F(u_1,v_1,v_2)=v_1\oplus 2(u_1y_1+z_1v_1)\oplus P(z_1)v_1+\{z_1\,y_1\,u_1\}+v_2.$$

Hence, if $T_{\zeta}F(u_1,v_1,v_2)=0$ we obtain $v_1=0$, then $u_1=0$ because $4y_1^{-1}(y_1u_1)=u_1$ by [MN; (2.6.7)] and finally $v_2=0$. In general, if $w=(u_1,\cdots,u_{n-1},v_1,\cdots v_n)\in V^{(1)}\times\cdots\times V^{(n-1)}\times V_{11}\times\cdots\times V_{nn}=T_{\zeta}M$ lies in the kernel of $T_{\zeta}F$ then, since $\tau_2(z_2)y_2+\cdots+\tau_{n-1}(z_{n-1})y_{n-1}+y_n\in V(e_1,0)$, it follows by considering the V_{11} - and $V^{(1)}$ -component of $T_{\zeta}Fw$ that $v_1=0=u_1$, but then w=0 by induction.

Lemma 4. (a) For $z_{ij} \in V_{ij}$, $i \neq j$, and $x_{mn} \in V_{mn}$ the Frobenius transformation $\tau_i(z_{ij})$ operates as follows

$$\tau_{i}(z_{ij})(x_{mn}) \tag{1}$$

$$= x_{mn} + \begin{cases}
2x_{ii}z_{ij} \oplus P(z_{ij})x_{ii} \in V_{ij} \oplus V_{jj} & m = n = i \\
2e_{j}(z_{ij}x_{ij}) \in V_{jj} & \{m, n\} = \{i, j\} \\
2z_{ij}x_{ik} \in V_{jk} & \{m, n\} = \{i, k\}, i, j, k \neq i \notin \{m, n\}
\end{cases}$$

(b) For $z_{ij} \in V_{ij}$ and $z_{kl} \in V_{kl}$ we have the following commutation formulas:

$$\tau_i(z_{ij})\tau_k(z_{kl}) = \tau_k(z_{kl})\,\tau_i(z_{ij}) \quad i \notin \{j, k, l\} \text{ and } k \notin \{l, i, j\},\tag{2}$$

$$\tau_i(z_{ij})\tau_k(z_{ki}) = \tau_k(z_{ki} + 2z_{ij}z_{ki})\tau_i(z_{ij}) \quad |\{i, j, k\}| = 3,$$
(3)

$$\tau_i(z_{ij})\tau_j(z_{jl}) = \tau_j(z_{jl})\,\tau_i(z_{ij} - 2z_{ij}z_{jl}) \quad |\{i, j, l\}| = 3. \tag{4}$$

Proof. (a) is immediate from (2.4). The formulas in (b) can be checked by using (1) and a case-by-case analysis. An alternative proof for (2) and (3) goes as follows. Since $\tau_c(z) = \exp(L(z,c))$ we have for any invertible endomorphism g of V

$$g\tau_k(z_{kl})g^{-1} = \exp(gL(z_{kl}, e_k)g^{-1}).$$
 (5)

By (2.1')

$$\tau_i(z_{ij})L(z_{kl}, e_k)\tau_i^{-1}(z_{ij}) = L(\tau_i(z_{ij})z_{kl}, \tau_i^{*-1}(z_{ij})e_k)$$

where $\tau_i(z_{ij})z_{kl} = z_{kl} + \delta_{li}2z_{ij}z_{kl}$ by (1) and $\tau_i(z_{ij})^{*-1}e_k = \tau_i(-z_{ij})^*e_k = e_k$ by (2.5). This, together with (5) for $g = \tau_i(z_{ij})$ implies (2) and (3). One can prove (4) in a similar fashion:

$$\tau_j(z_{jl})^{-1}\tau_i(z_{ij})\tau_j(z_{ij}) = \exp L(\tau_j(-z_{jl})z_{ij},\tau_j(z_{jl})^*e_i) = \exp L(z_{ij}-2z_{ij}z_{jl},e_i).$$

4. Transformation groups of Ω defined by \mathcal{E} .

We define

$$\Omega_1 \oplus \Omega_2 \oplus \cdots \oplus \Omega_n = \omega_1 +_2 + \cdots + \omega_n; \omega_i \in \Omega_i, 1 \le i \le n \} \subset \Omega,$$

$$A_{\mathcal{E}} = P(\Omega_1 \oplus \Omega_2 \oplus \cdots \oplus \Omega_n) = \exp L(V_{11} \oplus V_{22} \oplus \cdots \oplus V_{nn}),$$

$$K_{\mathcal{E}} = \{ f \in \operatorname{Aut} V ; fe_i = e_i, 1 \le i \le n \},$$

$$M_{\mathcal{E}} = \{ m \in G(\Omega) ; mV_{ii} \subset V_{ii}, 1 \le i \le n \}.$$

The second equality in the definition of $A_{\mathcal{E}}$ follows from $P(\exp x) = \exp L(2x)$, see [FK; II.3.4], and $\Omega = \exp V$, see the proof of [FK; III.2.1]. Clearly, $K_{\mathcal{E}}$ and $M_{\mathcal{E}}$ are Lie subgroups of $G(\Omega)$.

Theorem 5. (a) $M_{\mathcal{E}} = \{g \in G(\Omega); gV_{ij} = V_{ij} \text{ for all } i, j\} = \{g \in G(\Omega); gL(e_i)g^{-1} = L(e_i) \text{ for } 1 \leq i \leq n\}.$

- (b) $M_{\mathcal{E}}$ operates transitively on $\Omega_1 \oplus \Omega_2 \oplus \cdots \oplus \Omega_n \subset \Omega$. More precisely, $A_{\mathcal{E}} \subset M_{\mathcal{E}}$ and for every $\omega \in \Omega_1 \oplus \Omega_2 \oplus \cdots \oplus \Omega_n$ there exists a unique $a \in A_{\mathcal{E}}$ such that $\omega = a(e)$.
- (c) $K_{\mathcal{E}}$ is a subgroup of $M_{\mathcal{E}}$ satisfying

$$K_{\mathcal{E}} = M_{\mathcal{E}} \cap \text{Aut } V = \{ m \in M; mm^* = \text{Id} \}.$$
 (1)

(d) Any $m \in M_{\mathcal{E}}$ can be uniquely written in the form m = ak where $a \in A_{\mathcal{E}}$ and $k \in K_{\mathcal{E}}$. Thus, we have a decomposition

$$M_{\mathcal{E}} = A_{\mathcal{E}} \cdot K_{\mathcal{E}} \approx (V_{11} \oplus V_{22} \oplus \cdots \oplus V_{nn}) \times K_{\mathcal{E}} \quad (diffeomorphism).$$
 (2)

Proof. We abbreviate $A = A_{\mathcal{E}}, K = K_{\mathcal{E}}$ and $M = M_{\mathcal{E}}$.

(a) Let $m \in M$. Since m is invertible, we have $mV_{ii} = V_{ii}$. For $i \neq j$ and $z_{ij} \in V_{ij}$ we have $z_{ij} = \{e_i \ z_{ij} \ e_j\}$ and hence, by (2.2') and the Peirce multiplication rules,

$$mz_{ij} = m\{e_i \ z_{ij} \ e_j\} = \{me_i \ m^{*-1}z_{ij} \ me_j\} \in \{V_{ii} \ V \ V_{jj}\} \subset V_{ij},$$

whence the first equality in a). The second is then immediate since the Peirce spaces V_{ij} are the joint eigenspaces of the commuting endomorphisms $L(e_i), 1 \le i \le n$.

(b) Let $\omega = \omega_1 \oplus \cdots \oplus \omega_n \in \Omega_1 \oplus \cdots \oplus \Omega_n$. Then, by the Peirce multiplication rules, $P(\omega)V_{ii} = P(\omega_i)V_{ii} \subset V_{ii}$ and hence $A \subset M$. Let $\sqrt{\omega} = \sqrt{\omega_1} \oplus \cdots \sqrt{\omega_n}$ where $\sqrt{\omega_i} \in \Omega_i$ is the unique square root in Ω_i of ω_i . Then $P(\sqrt{\omega}) \in A$ and $P(\sqrt{\omega})e = \omega$. If there exist $a, a' \in A$ with ae = a'e and a = P(x), a' = P(x') for $x, x' \in \Omega_1 \oplus \cdots \oplus \Omega_n$ we get $x^2 = P(x)e = P(y)e = y^2$, thus x = y by the uniqueness of the square root on Ω , and a = a'. Since $g\bar{\Omega} = \bar{\Omega}$ for any $g \in G(\Omega)$, we have $m\Omega_i = m(\bar{\Omega} \cap V_{ii}) \subset \bar{\Omega} \cap V_{ii} = \Omega_i$ for every $m \in M$. Therefore $M(\Omega_1 \oplus \cdots \oplus \Omega_n) \subset \Omega_1 \oplus \cdots \oplus \Omega_n$.

(c) For any $m \in M \cap \operatorname{Aut} V$ we have $m|V_{ii} \in \operatorname{Aut} V_{ii}$ and hence $me_i = e_i$. Conversely, any $f \in K \subset \operatorname{Aut} V \subset G(\Omega)$ has the property $fV_{ii} = fV(e_i, 1) = V(fe_i, 1) = V_{ii}$ and thus lies in $M \cap \operatorname{Aut} V$. The equality $M_{\mathcal{E}} \cap \operatorname{Aut} V = \{m \in M; mm^* = Id\}$ then follows from (2.3).

(d) For $m \in M$ there exists a unique $a \in A$ such that me = ae, i.e., $k = a^{-1}m \in Aut \ V \cap M = K$ in view of (2.3) and c). (2) follows from the fact that exp is a diffeomorphism.

Remarks 6. 1) Let Str(V) be the structure group of V. Since $Str(V) = Str(V)^*$, it is the group of real points of a reductive algebraic group, and $G(\Omega) \subset Str(V)$ is a finite covering of the (topological) identity component $Str(V)^0$. More generally, $Str(V)_{\mathcal{E}} := \{g \in Str(V); mV_{ij} = V_{ij} \text{ for all } i, j\}$ is invariant under * and hence the group of real points of a reductive algebraic group. Since $Str(V)_{\mathcal{E}}^0 \subset M_{\mathcal{E}} \subset Str(V)_{\mathcal{E}}$ it follows that $M_{\mathcal{E}}$ is a real reductive group in the sense of [W; 2.1]. The decomposition (2) is the Cartan decomposition of $M_{\mathcal{E}}$ in the sense of [W; 2.1.8]. In particular, $K_{\mathcal{E}}$ is a maximal compact subgroup of $M_{\mathcal{E}}$.

2) If $\mathcal{E} = \{e\}$ then (2) specializes to the well-known Cartan decomposition $G(\Omega) = P(\Omega) \cdot \operatorname{Aut} V$ ([BK; XI Satz 4.5]). The corresponding decomposition of the Lie algebra $\operatorname{Lie}G(\Omega) = \mathfrak{g}(V)$ is the Cartan decomposition $\mathfrak{g}(V) = L(V) \oplus \operatorname{Der} V$. If \mathcal{E} is a Jordan frame, i.e., every e_i is primitive: $V_{ii} = \mathbb{R}e_i$, $A_{\mathcal{E}}$ is an abelian group and coincides with the group A of [FK; VI.3, p. 112]. In this case $\mathfrak{a} = L(V_{11} \oplus V_{22} \oplus \cdots \oplus V_{nn})$ is a maximal abelian subspace of $L(V) \subset \mathfrak{g}(V)$ so that $M_{\mathcal{E}}$ coincides with the group M of [W; 2.2.4].

5. Transformation groups of Ω defined by \mathcal{E} and a partial order.

We let \leq be a partial order on $I = \{1, \ldots, n\}$ which is weaker than the canonical order: $i \leq j \Rightarrow i \leq j$. We put $i \prec j \Leftrightarrow i \leq j$, $i \neq j$ and define

$$\begin{split} e_{\langle i \rangle} &= \sum_{k \prec i} \, e_k \,, & \tau_{\langle i \rangle} &= \tau_{e_{\langle i \rangle}} \,, \\ V_{\langle i]} &= \oplus_{k \prec i} \, V_{ki} = V(e_{\langle i \rangle}, \frac{1}{2}) \cap V(e_i, \frac{1}{2}) \,, & V^{(i \prec)} &= \oplus_{i \prec j} \, V_{ij} \,, \\ V_{ij \prec} &= \left(\oplus_{j \prec l} \, V_{il} \right) \oplus \left(\oplus_{i < k \leq l} \, V_{kl} \right), (1 \leq i \leq j \leq n), & V_{ij \preceq} &= V_{ij} \oplus V_{ij \prec}. \end{split}$$

Thus, $V^{(i\prec)}=V^{(i)}$ in case \leq coincides with the canonical order. We will consider the following subgroups of $G(\Omega)$:

$$N_{\mathcal{E},\prec} = \{ u \in G(\Omega); (u - \operatorname{Id}) V_{ij} \subset V_{ij\prec} \text{ for all } i \leq j \},$$

$$T_{\mathcal{E},\preceq} = \{ t \in G(\Omega); t V_{ij} \subset V_{ij\preceq} \text{ for all } i \leq j \}.$$

Theorem 7. (a) The group $N_{\mathcal{E},\prec}$ is a unipotent simply-connected Lie subgroup of $T_{\mathcal{E},\preceq}$ and has the descriptions

$$N_{\mathcal{E}, \prec} = \{ \tau_1(z_1) \cdots \tau_{n-1}(z_{n-1}) \, ; \, z_i \in V^{(i \prec)}, 1 \le i < n \}$$
 (1)

$$= \{ \tau_{(n)}(z_n) \cdots \tau_{(2)}(z_2) ; z_i \in V_{(i)}, 1 < i \le n \}.$$
 (2)

The Lie algebra of $N_{\mathcal{E}, \prec}$ is

$$\mathfrak{n}_{\mathcal{E},\prec} = \bigoplus_{i=1}^{n-1} \{ L(z_i, e_i) ; z_i \in V^{(i\prec)} \} = \bigoplus_{i\prec j} L(V_{ij}, e_i).$$

(b) The group $M_{\mathcal{E}} \subset T_{\mathcal{E},\preceq}$ normalizes $N_{\mathcal{E},\prec}$, and $T_{\mathcal{E},\preceq}$ is a semidirect product: $T_{\mathcal{E},\preceq} = M_{\mathcal{E}} \cdot N_{\mathcal{E},\prec}$.

(c) $K_{\mathcal{E}} = T_{\mathcal{E}} \cap \text{Aut } V = \{g \in T_{\mathcal{E}}; ge = e\} = \{g \in T_{\mathcal{E}}; gg^* = \text{Id}\}.$

Proof. For easier notation we abbreviate $K=K_{\mathcal{E}}$, $M=M_{\mathcal{E}}$, $N=N_{\mathcal{E},\prec}$ and $T=T_{\mathcal{E},\prec}$.

(a) Any $u \in N$ is of the form $u = \operatorname{Id} + n$ with n nilpotent, i.e., u is unipotent. Transitivity of \prec implies that $\mathfrak{n} = \{n \in \operatorname{End} V; nV_{ij} \subset V_{ij \prec} \text{ for all } i \leq j\}$ is a nilpotent subalgebra of $\operatorname{End} V$. Therefore, $u^{-1} = \operatorname{Id} + \sum_{i \geq 1} (-n)^i$ shows that N is closed under taking inverses. Similarly, N is also closed under products and therefore a subgroup of $G(\Omega)$. It is a closed subgroup of $G(\Omega)$ and therefore a Lie subgroup of $G(\Omega)$. It follows from (1) that N is simply-connected (This is not so surprising since, by [B; §9.5, Cor. 2 of Prop. 18], any unipotent group is simply-connected.) We are therefore left with proving (1) and (2).

Proof of (1): For any $i \prec j$ we have $\tau_i(z_{ij}) \in N$ by Lemma 4.a. Since $\tau_i(\sum_{j\succ i}z_{ij}) = \prod_{j\succ i}\tau_i(z_{ij})$, we also have $\{\tau_1(z_1)\cdots\tau_{n-1}(z_{n-1}); z_i\in V^{(i\prec)}\}\subset N$. Conversely, let $u\in N$. By definition, there exist unique $z_1\in V^{(1\prec)}$ and $v_0\in V(e_1,0)$ such that $ue_1=e_1+z_1+v_0$. Observe that $u^*x_{11}=x_{11}$ for all $x_{11}\in V_{11}$ since $(u-\mathrm{Id})V\subset V_{11}^{\perp}$. Hence, by (2.4) and the Peirce multiplication rules,

$$ux_{11} = uP(e_1)x_{11} = P(ue_1)u^{*-1}x_{11} = P(e_1 + z_1 + v_0)x_{11}$$

= $x_{11} \oplus \{e_1 x_{11} z_1\} \oplus P(z_1)x_{11} = x_{11} \oplus 2x_{11}z_1 \oplus P(z_1)x_{11}.$

In view of (2.4) this shows $ux_{11} = \tau_1(z_1)x_{11}$. Let $\tilde{u} = \tau_1(z_1)^{-1}u \in N$ and put $c = e - e_1$. Since $V' := V(c, 1) = V(e_1, 0) = \bigoplus_{2 \le k \le l \le n} V_{kl}$ it follows that \tilde{u} leaves V' invariant. Because $\tilde{u}\Omega = \Omega$ and $\Omega_c = \Omega \cap V(c, 1)$ we see that $\tilde{u}|V'$ lies in the corresponding subgroup N' of $G(\Omega_c)$ defined with respect to $\mathcal{E} \cap V(c, 1) = (e_2, \ldots, e_n)$ and the restriction of \preceq to $\{2, \ldots, n\}$. By induction, $\tilde{u}|V' = \tau_2(z_2) \cdots \tau_{n-1}(z_{n-1})|V'$ for suitable $z_i \in V^{(i \prec)}$ (= Id if n = 2). Then

$$\widehat{u} := (\tau_2(z_2) \cdots \tau_{n-1}(z_{n-1}))^{-1} \widetilde{u} = \tau_{n-1}(-z_{n-1}) \cdots \tau_2(-z_2) \widetilde{u} \in N$$

has the property $\widehat{u}x_{ii} = x_{ii}$ for all $1 \leq i \leq n$. Thus, $\widehat{u} = M \cap N = \{\text{Id}\}$. Proof of (2): We have for $k \prec i$

$$\tau_{\langle i\rangle}(z_{ki}) = \exp L(z_{ki}, e_{\langle i\rangle}) = \exp L(z_{ki}, e_k) = \tau_k(z_{ki}), \tag{4}$$

and hence for $z_i \in V_{\langle i|}$

$$\tau_{\langle i \rangle}(z_i) = \prod_{k \prec i} \tau_{\langle i \rangle}(z_{ki}) = \prod_{k \prec i} \tau_k(z_{ki}).$$

This shows that

$$N' := \{ \tau_{(n)}(z_n) \cdots \tau_{(2)}(z_2) ; z_i \in V_{(i)}, 1 < i \le n \} \subset N.$$

By (4), N' contains the canonical generators of N. Hence N' = N if N' is a subgroup of N. To prove this, it suffices to show that for j < l and $i \prec j, k \prec l$ we have $\tau_{\langle j \rangle}(z_{ij})\,\tau_{\langle l \rangle}(z_{kl}) \in N'$. Since $|\{i,j,l\}| = 3$ and $\tau_{\langle j \rangle}(z_{ij})\,\tau_{\langle l \rangle}(z_{kl}) = \tau_i(z_{ij})\,\tau_k(z_{kl})$ there are two cases to be considered: if k = i or $k \notin \{i,j,l\}$ then, by Lemma 4.b, $\tau_i(z_{ij})\,\tau_k(z_{kl}) = \tau_k(z_{kl})\tau_i(z_{ij}) = \tau_{\langle l \rangle}(z_{kl})\tau_{\langle j \rangle}(z_{ij}) \in N'$, while for k = j we have, by Lemma 4.b and (4)

$$\tau_i(z_{ij})\tau_j(z_{jl}) = \tau_j(z_{jl})\tau_i(z_{ij} - 2z_{ij}z_{jl}) = \tau_{\langle l\rangle}(z_{jl})\tau_{\langle l\rangle}(-2z_{ij}z_{jl})\tau_{\langle j\rangle}(z_{ij})$$
$$= \tau_{\langle l\rangle}(z_{jl} - 2z_{ij}z_{jl})\tau_{\langle j\rangle}(z_{ij}) \in N'.$$

This finishes the proof of (2).

Since $\tau_i(z_i) = \exp L(z_i, e_i)$ we have $\mathfrak{n}' := \sum_{i=1}^n L(V^{(i \prec)}, e_i) \subset \mathfrak{n} := \operatorname{Lie} N_{\mathcal{E}, \prec}$ by (1). That the sum is direct follows from $L(z_i, e_i)e_j = \delta_{ij}z_i$. To conclude $\mathfrak{n}' = \mathfrak{n}$ it is sufficient to prove that \mathfrak{n}' is a subalgebra. Indeed, the Lie subgroup N' of N corresponding to \mathfrak{n}' contains $\tau_i(V^{(i \prec)})$, hence N' = N by (1) and therefore $\mathfrak{n}' = \mathfrak{n}$. That \mathfrak{n}' is a subalgebra of \mathfrak{n} follows from the following calculations. Let $z_i \in V^{(i)}, w_i \in V^{(j)}$. If i = j then, by (2.2),

$$[L(z_i, e_i), L(w_i, e_i)] = L(\{z_i e_i w_i\}, e_i) - L(w_i, \{e_i z_i e_i\}) = 0$$

since $\{e_i z_i e_i\} = 0$, $\{z_i e_i w_i\} \in V(e_i, 0)$ and $L(V(e_i, 0), V(e_i, 1)) = 0$. If i < j then $w_i \in V(e_i, 0)$ and so $\{z_i e_i w_i\} = 0$. Hence, (2.2) shows

$$[L(z_i, e_i), L(w_i, e_i)] = -L(w_i, \{e_i z_i e_i\}).$$

Here $\{e_i z_i e_j\} = z_{ij} \in V_{ij}$ and so $\{e_i e_i z_{ij}\} = z_{ij}$. A second application of (2.2) then yields

$$-L(w_i, z_{ij}) = [L(e_i, e_i), L(w_i, z_{ij})] = -[L(w_i, z_{ij}), L(e_i, e_i)] = -L(\{w_i, z_{ij}, e_i\}, e_i)$$

where $\{w_j z_{ij} e_i\} = \sum_{j \prec k} \{w_{jk} z_{ij} e_i\}$. Each term $\{w_{jk} z_{ij} e_i\} \in V_{ik}$ with $i \prec j \prec k$ since $z_{ij} = 0$ unless $i \prec j$. This proves $[L(z_i, e_i), L(w_j, e_j)] \in L(V^{(i \prec)}, e_i)$. (b) It follows from Theorem 5.a that $M \subset T$. Moreover, M normalizes N since for $m \in M$ and $u \in N$ we have

$$(mum^{-1} - Id)V_{ij} = m(u - Id)m^{-1}V_{ij} = m(u - Id)V_{ij} \subset mV_{ij} = V_{ij}$$

Because $M \cap N = \{\text{Id}\}$ it is clear that $MN = \{mn; m \in M, n \in N\} \subset T$ is a semidirect product. To prove the other inclusion, let $t \in T$. We will construct inductively an $n \in N$ such that $nt \in M$. Assuming that $tV_{jj} = V_{jj}$ for $1 \le j < i$ we will find $n_i \in N$ such that $n_i tV_{jj} = V_{jj}$ for $1 \le j \le i$. Let $te_i = x_{ii} + x_{i \prec} + b$ where b is an element of

$$B = \bigoplus_{i < k \le l \le n} V_{kl} = V(e_{i+1} + \dots + e_n, 1) \subset V(e_i, 0).$$

We claim that $x_{ii} \in \Omega_i$. Indeed, $te = te_1 + \cdots + te_i + \cdots + te_n = x_{11} + \cdots + x_{ii} + x_{i \prec} + \tilde{b}$ for suitable $x_{jj} \in V_{jj}$ and $\tilde{b} \in B$, and therefore $x_{ii} = P(e_i)te \in P(e_i)\Omega = \Omega_i$ by [MN; 3.2]. For any $z \in V^{(i \prec)}$ we have $\tau_i(z)te_i = x_{ii} \oplus 2zx_{ii} + x_{i \prec} \oplus b'$ for a

suitable $b' \in B$. Since $x_{ii} \in \Omega_i$ is invertible in V_{ii} , we can find $z' \in V^{(i \prec)}$ such that $2z'x_{ii} + x_{i \prec} = 0$. Thus, replacing t by $\tau_i(z')t$, we can assume $te_i = x_{ii} + b'$ and, by (2.4), still have $tV_{jj} \subset V_{jj}$ for j < i. Let

$$C = (\bigoplus_{i < l \le n} V_{il}) \oplus (\bigoplus_{i < k \le l} V_{kl}) = (\bigoplus_{i < l \le n} V_{il}) \oplus B.$$

Since $t^{-1}C \subset C$ we have $t^{*-1}V_{ii} \subset D := C^{\perp} = V_{ii} \oplus (\bigoplus_{1 \leq k < i, k \leq l} V_{kl})$, the orthogonal complement of C with respect to the trace form. Because of $P(B)D = 0 = \{V_{ii} D B\}$ it now follows for arbitrary $v_{ii} \in V_{ii}$

$$tv_{ii} = tP(e_i)v_{ii} = P(te_i)t^{*-1}v_{ii} \in P(x_{ii} + b')D$$

= $P(x_{ii})D + P(b')D + \{x_{ii} D b'\} = P(x_{ii})D = V_{ii},$

which completes the induction process.

(c) With respect to a suitable orthonormal basis of V, any $g \in T$ is represented by an upper triangular block matrix whose block structure is determined by the Peirce spaces V_{ij} . If such a g is also orthogonal, the matrix is in fact a diagonal block matrix. It follows that $ge_i \in V_{ii}$ is an idempotent of the same rank as e_i and hence $ge_i = e_i$. Thus $T \cap \text{Aut } V \subset K$, and the other inclusion is obvious. The remaining equalities then follow from (2.3).

Remarks 8. 1) Since $N_{\mathcal{E},\prec}$ is unipotent it does not contain any non-trivial compact subgroup, and thus $K_{\mathcal{E}}$ is also a maximal compact subgroup of $T_{\mathcal{E},\preceq}$, see Remark 6(1).

2) The map

$$V^{(1\prec)} \times \cdots \times V^{(n-1\prec)} \to N_{\mathcal{E}} : (z_1, \ldots, z_{n-1}) \mapsto \tau_1(z_1) \cdots \tau_{n-1}(z_{n-1})$$

is in fact a diffeomorphism. Indeed, that the map is a bijection follows from (1) and Proposition 3. As a product of exponentials, it is obviously differentiable. That its inverse is differentiable too, can be shown inductively, following the method of the proof of (1). Of course, since N is nilpotent this is also a special case of a general result on canonical coordinates of solvable Lie groups ([B; §9.6, Prop. 20]).

3) If \leq is the minimal order, i.e., $i \leq j \Leftrightarrow i = j$, we have $N_{\mathcal{E},\prec} = \{\mathrm{Id}\}$ and $T_{\mathcal{E},\preceq} = M_{\mathcal{E}}$. For example, this is the case if $\mathcal{E} = \{e\}$. On the other extreme, if \mathcal{E} is a Jordan frame and \leq is the canonical order, the group $N_{\mathcal{E},\prec}$ coincides with the so-called strict triangular subgroup N of [FK; VI.3]. By (3) it is also the group N of [W; 2.1.8]. In this case, $A_{\mathcal{E}} \cdot N_{\mathcal{E},\prec}$ is a subgroup of $T_{\mathcal{E},\prec}$, the so-called triangular subgroup T of [FK; VI.3].

6. The AP cone ([MN]).

An AP cone $\Omega(\mathcal{K}) \subset \Omega$ is defined in terms of an orthogonal system (c_1, \ldots, c_s) of primitive idempotents $c_i \in V$ and a unital ring \mathcal{K} , i.e., a set of subsets of $\{1, \ldots, s\}$ which is closed under union and intersection: $K, L \in \mathcal{K} \Rightarrow K \cup L \in \mathcal{K}$

and $K \cap L \in \mathcal{K}$, and which moreover has the property that $\emptyset \in \mathcal{K}$ and $\{1,\ldots,s\} \in \mathcal{K}$. To describe $\Omega(\mathcal{K})$ we need the following notations. For any $K \subset \{1,\ldots,s\}$ and $x \in V$ we put $c_K = \sum_{k \in K} c_k$ and $x_K = P(c_K)x$, the $V(c_K,1)$ -component of x. If $x \in \Omega$ and $K \neq \emptyset$ then $x_K \in P(c_K)\Omega$, and one knows that this is the symmetric cone of the Euclidean Jordan algebra $V(c_K,1)$. In particular, x_K is invertible in $V(c_K,1)$. We denote by x_K^{-1} the inverse of x_K in $V(c_K,1)$ and view x_K^{-1} as an element of V. We note that in general $x_K^{-1} \neq P(c_K)(x^{-1})$. For $K = \emptyset$ we put $c_\emptyset = 0$ and $x_K^{-1} = 0^{-1} = 0$. The AP cone $\Omega(\mathcal{K})$ is then defined as the set of all $x \in \Omega$ satisfying

$$x_{K \cup L}^{-1} + x_{K \cap L}^{-1} = x_K^{-1} + x_L^{-1}$$

for all $K, L \in \mathcal{K}$. Equivalent characterizations of $\Omega(\mathcal{K})$ are given in [MN; Thm. 2.4].

The link with the results obtained so far in this paper is property (1) below. To explain it, we recall that $\emptyset \neq K \in \mathcal{K}$ is join-irreducible if K is not a union of proper subsets of K belonging to K. Thus, if we put $\langle K \rangle := \cup \{K' \in \mathcal{K}; K' \subsetneq K\}$ and $[K] := K \setminus \langle K \rangle$ then K is join-irreducible if and only if $[K] \neq \emptyset$. We denote by $\mathcal{J}(\mathcal{K})$ the set of all join-irreducible sets in \mathcal{K} . One knows [AP; 2.1] that any $K \in \mathcal{K}$ is partitioned by $\{[L]; L \in \mathcal{J}(\mathcal{K}) \text{ and } L \subset K\}$. Moreover, by [AP; 2.7], one can always find a never-decreasing listing of $\mathcal{J}(\mathcal{K})$, i.e., an enumeration $\mathcal{J}(\mathcal{K}) = (K_1, \ldots, K_n)$ with the property $i < j \Rightarrow K_j \not\subset K_i$. We fix such a listing and define a partial order \preceq on $\{1, \ldots, n\}$ by $i \preceq j \Leftrightarrow [K_i] \subset K_j$. For $1 \leq j \leq s$ we put $e_j = \sum_{i \preceq j} c_i$ and obtain in this way an orthogonal system $\mathcal{E} = (e_1, \ldots, e_n)$. After renumbering, we may assume that \preceq is weaker than the canonical order, so that we are in the setting of $\mathbf{6}$. Then, by [MN; 2.14], the map

$$F_{\mathcal{K}}: V^{(1\prec)} \times \cdots \times V^{(n-1\prec)} \times \Omega_1 \times \cdots \times \Omega_n \to \Omega(\mathcal{K})$$

given by

$$F_{\mathcal{K}}(z_1,\cdots,z_{n-1},y_1,\cdots,y_n)=\tau_1(z_1)\cdots\tau_{n-1}(z_{n-1})(y_1\oplus\cdots\oplus y_n)$$

is a bijection. Thus,

$$\Omega(\mathcal{K}) = N_{\mathcal{E}, \prec}(\Omega_1 \oplus \cdots \oplus \Omega_n)$$
 (1)

We transport the obvious manifold structure of $V^{(1\prec)} \times \cdots \times V^{(n-1\prec)} \times \Omega_1 \times \cdots \times \Omega_n$ to $\Omega(\mathcal{K})$ via $F_{\mathcal{K}}$. By Proposition 3, $\Omega(\mathcal{K})$ is then a simply-connected closed submanifold of Ω (with the induced topology). Also, Proposition 3 implies,

$$\Omega(\mathcal{K}) = \Omega \Leftrightarrow \preceq \text{ is the canonical order.}$$
 (2)

$$\Omega(\mathcal{K}) = \Omega_1 \oplus \cdots \oplus \Omega_n \Leftrightarrow \preceq \text{ is the minimal order.}$$
 (3)

Theorem 9. $T_{\mathcal{E},\preceq}$ is a transitive Lie transformation group of $\Omega(\mathcal{K})$. For this operation, the isotropy group of $e \in \Omega(\mathcal{K})$ is $K_{\mathcal{E}}$, and we have an isomorphism of manifolds

$$\Omega(\mathcal{K}) \approx T_{\mathcal{E}, \prec}/K_{\mathcal{E}}.$$

Proof. For easier notation we abbreviate $K = K_{\mathcal{E}}$, $M = M_{\mathcal{E}}$, $N = N_{\mathcal{E}, \prec}$ and $T = T_{\mathcal{E}, \preceq}$. By Theorem 5.b, we know that M operates transitively on $\Omega_1 \oplus \cdots \oplus \Omega_n$. Thus, by (7.1), $\Omega(\mathcal{K}) = NMe$. But this implies that both M and N leave $\Omega(\mathcal{K})$ invariant: $N\Omega(\mathcal{K}) = NNMe = \Omega(\mathcal{K})$ and, since M normalizes N, $M\Omega(\mathcal{K}) = MNMe = NMMe = \Omega(\mathcal{K})$. Therefore, T operates transitively on $\Omega(\mathcal{K})$. By Theorem 6.c), the isotropy group of e in T is $K_{\mathcal{E}}$, and hence the isomorphism follows from ([B; §1.7 Prop. 14]).

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