

EXC: Let A be an $n \times n$ matrix show that: A is invertible $\Leftrightarrow 0$ is not an eigenvalue of A .

SOL: Recall that λ is an eigenvalue of $A \Leftrightarrow \det(\lambda I - A) = 0$.
 So: 0 is an eigenvalue of $A \Leftrightarrow \det(0 \cdot I - A) = 0$.
 $\Leftrightarrow \det(-A) = 0$. So: 0 is an eigenvalue of $A \Leftrightarrow (-1)^n \det A = 0$.
 $\Leftrightarrow \det A = 0 \Leftrightarrow A$ is NOT invertible. **(Done)**

NO: 2.5!!

§ 2.8

SYSTEMS OF DIFFERENTIAL EQUATIONS

- Q: what is a differential equation?
- Q: what is a FIRST ORDER DIFFERENTIAL equations?

Lemma The solution of the differential equation: $f' = a \cdot f$, where a is a #, is

$f(x) = c \cdot e^{ax}$, for some # c .

SOL: Look at $f(x) = e^{-ax} = g(x)$; $g'(x) = f'(x) e^{-ax} + f(x)(-a) e^{-ax} = e^{-ax} (f'(x) - a f(x)) = 0 \Rightarrow g'(x) = 0 \Rightarrow g(x) = c$ for some # c . So $f(x) = c \cdot e^{ax}$

What if we have more functions?

THE SYSTEM:

$$\begin{cases} f_1' = a_{11}f_1 + a_{12}f_2 + \dots + a_{1n}f_n \\ f_2' = a_{21}f_1 + a_{22}f_2 + \dots + a_{2n}f_n \\ \dots \\ f_n' = a_{n1}f_1 + a_{n2}f_2 + \dots + a_{nn}f_n \end{cases}$$

NOTATION:

$$f = \begin{bmatrix} f_1 \\ f_2 \\ \vdots \\ f_n \end{bmatrix}; \quad f' = \begin{bmatrix} f_1' \\ f_2' \\ \vdots \\ f_n' \end{bmatrix}; \quad A = \begin{bmatrix} a_{11} & a_{12} & \dots & a_{1n} \\ a_{21} & a_{22} & \dots & a_{2n} \\ \dots & \dots & \dots & \dots \\ a_{n1} & a_{n2} & \dots & a_{nn} \end{bmatrix}$$

IT can be written ASO

$$f' = A \cdot f$$

(see lemma!)

Def: The system is called: a system of first order differential equations.

Thm (see lemma) Consider the system: $f' = Af$.

If A is diagonalizable, then every solution of

$f' = Af$ is given by $f(x) = c_1 X_1 e^{\lambda_1 x} + c_2 X_2 e^{\lambda_2 x} + \dots$

$\dots + c_n X_n e^{\lambda_n x}$, where c_1, c_2, \dots, c_n are scalars.

$\lambda_1, \dots, \lambda_n$ are the eigenvalues of A ; X_1, X_2, \dots, X_n are the corresponding eigenvectors.

Do: 12/132

$$\begin{cases} f_1' = 2f_1 + 4f_2 \\ f_2' = 3f_1 + 3f_2 \end{cases}; \quad \begin{cases} f_1(0) = 0 \\ f_2(0) = 1 \end{cases}$$

SOL:

$$f = \begin{pmatrix} f_1 \\ f_2 \end{pmatrix}; \quad f' = \begin{pmatrix} f_1' \\ f_2' \end{pmatrix}; \quad f' = Af; \quad A = \begin{pmatrix} 2 & 4 \\ 3 & 3 \end{pmatrix}$$

$$\begin{aligned} \chi_A(x) &= \det(xI_2 - A) = \det \left(\begin{pmatrix} x & 0 \\ 0 & x \end{pmatrix} - \begin{pmatrix} 2 & 4 \\ 3 & 3 \end{pmatrix} \right) = \det \begin{pmatrix} x-2 & 4 \\ 3 & x-3 \end{pmatrix} \\ &= (x-2)(x-3) - 12 = x^2 - 5x + 6 - 12 = x^2 - 5x - 6 = \\ &= (x-6)(x+1) \Rightarrow \lambda_1 = 6; \quad \lambda_2 = -1. \end{aligned}$$

(OR DISTINCT) eigenvalues $\Rightarrow A$ is diagonalizable!!!

FOR $\lambda_1 = 6$, we solve $(6I_2 - A)X = 0 = \begin{pmatrix} 0 \\ 0 \end{pmatrix}; \begin{pmatrix} 4 & -4 \\ -3 & 3 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix} \Rightarrow$

$$\begin{pmatrix} 1 & -1 & | & 0 \\ 0 & 0 & | & 0 \end{pmatrix} \Rightarrow x_2 = t; \quad x_1 = t, \quad t \neq 0 \Rightarrow X = \begin{pmatrix} t \\ t \end{pmatrix} = t \begin{pmatrix} 1 \\ 1 \end{pmatrix}.$$

choose $X_1 = \begin{pmatrix} 1 \\ 1 \end{pmatrix}$.

FOR $\lambda_2 = -1$, we solve: $(-1I_2 - A)X = 0 = \begin{pmatrix} 0 \\ 0 \end{pmatrix}; \begin{pmatrix} -3 & -4 \\ -3 & -4 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix} \Rightarrow$

$$\begin{pmatrix} -3 & -4 & | & 0 \\ 0 & 0 & | & 0 \end{pmatrix} \Rightarrow x_2 = t; \quad x_1 = \frac{4}{-3}t = -\frac{4}{3}t \Rightarrow X = \begin{pmatrix} -4/3 t \\ t \end{pmatrix} = t \begin{pmatrix} -4/3 \\ 1 \end{pmatrix}$$

choose $X_2 = \begin{pmatrix} -4/3 \\ 1 \end{pmatrix}$.

So $f(x) = c_1 \begin{pmatrix} 1 \\ 1 \end{pmatrix} e^{6x} + c_2 \begin{pmatrix} -4/3 \\ 1 \end{pmatrix} e^{-x}$; To get c_1, c_2

Recall that $\begin{cases} f_1(0) = 0 \\ f_2(0) = 1 \end{cases} \Rightarrow \begin{pmatrix} f_1(0) \\ f_2(0) \end{pmatrix} = \begin{pmatrix} 0 \\ 1 \end{pmatrix} = \begin{pmatrix} 0 \\ 1 \end{pmatrix} = 0$

$$c_1 \begin{pmatrix} 1 \\ 1 \end{pmatrix} e^0 + c_2 \begin{pmatrix} -4/3 \\ 1 \end{pmatrix} e^0 = \begin{pmatrix} 0 \\ 1 \end{pmatrix} \Rightarrow$$

$$c_1 \begin{pmatrix} 1 \\ 1 \end{pmatrix} + c_2 \begin{pmatrix} -4/3 \\ 1 \end{pmatrix} = \begin{pmatrix} 0 \\ 1 \end{pmatrix} \Rightarrow \begin{pmatrix} 1 & -4/3 & | & 0 \\ 1 & 1 & | & 1 \end{pmatrix} \xrightarrow{R_2 - R_1}$$

$$\begin{pmatrix} 1 & -4/3 & | & 0 \\ 0 & 7/3 & | & 1 \end{pmatrix} \Rightarrow c_2 = 3/7 \Rightarrow c_1 = 4/3 \cdot c_2 = \frac{4}{7}$$

So $f(x) = \frac{4}{7} \begin{pmatrix} 1 \\ 1 \end{pmatrix} e^{6x} + \frac{3}{7} \begin{pmatrix} -4/3 \\ 1 \end{pmatrix} e^{-x}$

TRY yourself 1. c. / 132

2.4. Linear Dynamical Systems

Def A dynamical system is a sequence of columns V_0, V_1, V_2, \dots where the initial V_0 is known, and the other are determined by: $V_{k+1} = AV_k$ for $k \geq 0$; (A is a square $m \times m$).

The condition $V_{k+1} = AV_k$ is called a $m \times m$ recurrence.

Since V_0 is known $\Rightarrow V_1 = AV_0$ can be found; $V_2 = AV_1 = A^2V_0$ can be found; $V_3 = AV_2 = A^3V_0, \dots$

Exp: Consider a population of BIRDS. Set $V_k = \begin{bmatrix} a_k \\ j_k \end{bmatrix}$, where a_k and j_k represents the # of adult and juvenile females present k years after the initial values a_0, j_0 were observed.

Assume they satisfy the equations:
$$\begin{cases} a_{k+1} = \alpha a_k + \beta j_k \\ j_{k+1} = m a_k \end{cases}$$

where α and β are ADULT and JUVENILE survival rates; m is the reproduction rate. We assume $\alpha, \beta, m \geq 0$.

So $A = \begin{bmatrix} \alpha & \beta \\ m & 0 \end{bmatrix}$:
$$V_{k+1} = \begin{bmatrix} a_{k+1} \\ j_{k+1} \end{bmatrix} = \underbrace{\begin{bmatrix} \alpha & \beta \\ m & 0 \end{bmatrix}}_A \underbrace{\begin{bmatrix} a_k \\ j_k \end{bmatrix}}_{V_k}$$

Def An eigenvalue λ of an $n \times n$ $m \times m$ A is called a dominant eigenvalue of A if: $|\lambda| > |m|$ for all $m \neq \lambda$ eigenvalues.

THM Consider the dynamical system: $V_{k+1} = AV_k; k \geq 0$ where A , and V_0 are given; Assume that A is diagonalizable $n \times n$ matrix with eigenvalues $\lambda_1, \lambda_2, \dots, \lambda_n$ and corresponding eigenvectors X_1, X_2, \dots, X_n and let $P = [X_1 \ X_2 \ \dots \ X_n]$. Then:

$$V_k = b_1 \lambda_1^k X_1 + b_2 \lambda_2^k X_2 + \dots + b_n \lambda_n^k X_n; k \geq 0$$

where $\begin{bmatrix} b_1 \\ b_2 \\ \vdots \\ b_n \end{bmatrix} = P^{-1}V_0$.

MOREOVERS if A has dominant eigenvalue λ_1 , of multiplicity 1, then $V_k \approx \lambda_1^k b_1 X_1$ for sufficiently large k .

Interpretation: $\lambda_1 > 1 \Rightarrow$ POP becomes very large as $k \nearrow$
 $\lambda_1 = 1 \Rightarrow$ POP stabilizes as $k \nearrow$
 $\lambda_1 < 1 \Rightarrow$ POP becomes very small as $k \nearrow$
(extinction)

1/109 $A = \begin{pmatrix} \frac{1}{2} & \frac{1}{3} \\ 2 & 0 \end{pmatrix}; V_k = \begin{pmatrix} a_k \\ b_k \end{pmatrix} k \geq 0$

SOL:
 (1) $V_0 = \begin{pmatrix} 100 \\ 60 \end{pmatrix}; V_1 = AV_0 = \begin{pmatrix} \frac{1}{2} & \frac{1}{3} \\ 2 & 0 \end{pmatrix} \begin{pmatrix} 100 \\ 60 \end{pmatrix} = \begin{pmatrix} 70 \\ 200 \end{pmatrix}$

$V_2 = \begin{pmatrix} \frac{1}{2} & \frac{1}{3} \\ 2 & 0 \end{pmatrix} \begin{pmatrix} 70 \\ 200 \end{pmatrix} = \begin{pmatrix} 35 + 66.6 \\ 140 \end{pmatrix} \dots \dots \dots$ etc...

(2) $\mathcal{L}_A(x) = \det(xI_2 - A) = \det \begin{pmatrix} x - \frac{1}{2} & -\frac{1}{3} \\ -2 & x \end{pmatrix} =$
 $= x^2 - \frac{1}{2}x - \frac{2}{3} \Rightarrow \lambda_1 = \frac{\frac{1}{2} + \sqrt{\frac{1}{4} + \frac{8}{3}}}{2}$

$\lambda_2 = \frac{\frac{1}{2} - \sqrt{\frac{1}{4} + \frac{8}{3}}}{2}$ 5

$$\Rightarrow \begin{cases} \lambda_1 = \frac{1}{4} \left[1 + \sqrt{\frac{35}{3}} \right] \approx 1.104 \\ \lambda_2 = \frac{1}{4} \left[1 - \sqrt{\frac{35}{3}} \right] \approx -0.604 \end{cases}$$

Since λ_1 is dominant and $> 1 \Rightarrow$ pop. becomes large as $k \nearrow$. (3) it is independent of initial pop.

$$(4) \quad V_k \approx b_1 \cdot \lambda_1^k \cdot X_1$$

To GET X_1 : solve $(\lambda_1 I_2 - A)X_1 = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$

$$\begin{pmatrix} 1.104 & 0 \\ 0 & 1.104 \end{pmatrix} - \begin{pmatrix} 0.500 & 0.333 \\ 2.000 & 0.000 \end{pmatrix} =$$

$$= \begin{pmatrix} 0.604 & -0.333 \\ -2.000 & 1.104 \end{pmatrix}$$

$$\text{So } \begin{pmatrix} 0.604 & -0.333 \\ -2.000 & 1.104 \end{pmatrix} \begin{matrix} \\ \\ \end{matrix} \begin{matrix} 0 \\ 0 \end{matrix} \xrightarrow{\parallel} \begin{pmatrix} 2.000 & -1.104 \\ 0 & 0 \end{pmatrix} \begin{matrix} 0 \\ 0 \end{matrix}$$

$$X_1 = \begin{pmatrix} a \\ b \end{pmatrix} \quad b = t \quad ; \quad a = \frac{1.104}{2} t \quad \text{above } t=2$$

$$\Rightarrow X_1 \approx \begin{pmatrix} 1.104 \\ 2 \end{pmatrix}$$

$$\text{Similarly } X_2 \approx \begin{pmatrix} -0.604 \\ 2 \end{pmatrix}$$

$$\text{So } \begin{bmatrix} b_1 \\ b_2 \end{bmatrix} = P^{-1} V_0 = \begin{bmatrix} 1.104 & -0.604 \\ 2 & 2 \end{bmatrix}^{-1} \begin{bmatrix} 100 \\ 60 \end{bmatrix} =$$

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$$\frac{1}{2.208 + 1.208} \begin{bmatrix} 2 & 0.604 \\ -2 & 1.104 \end{bmatrix} \begin{bmatrix} 100 \\ 60 \end{bmatrix}$$

$$= \frac{1}{3.416} \begin{bmatrix} 200 + 36.24 \\ -200 + 66.24 \end{bmatrix} = \begin{pmatrix} \text{[scribble]} \\ \text{[scribble]} \end{pmatrix} \begin{pmatrix} 69.16 \\ -33.16 \end{pmatrix}$$

$$\text{So } V_k \approx \begin{pmatrix} \text{[scribble]} \\ 69.16 \end{pmatrix} (1.104)^k \begin{pmatrix} 1.104 \\ 2 \end{pmatrix} = \begin{pmatrix} a_k \approx (1.104)^k \text{[scribble]} \\ b_k \approx (1.104)^k \text{[scribble]} \end{pmatrix}$$

* 76.3
138.3

So done...

2/10g a) $A = \begin{pmatrix} \frac{3}{10} & \frac{1}{3} \\ 2 & 0 \end{pmatrix}$; $V_0 = \begin{pmatrix} 100 \\ 50 \end{pmatrix}$; $V_k = A^k V_0$

b) $\lambda_1 = \frac{1}{60} (9 + \sqrt{2481}) \approx 0.981$

$\lambda_2 = \frac{1}{60} (9 - \sqrt{2481}) \approx -0.680$ because:

$x I_2 - A = \begin{pmatrix} x - \frac{3}{10} & -\frac{1}{3} \\ -2 & x \end{pmatrix} \Rightarrow x^2 - \frac{3}{10}x - \frac{2}{3} = 0$

$$\Rightarrow \lambda_1 = \frac{\frac{3}{10} + \sqrt{\frac{9}{100} + \frac{8}{3}}}{2} = \frac{\frac{3}{10} + \sqrt{\frac{24 + 800}{100 \cdot 3}}}{2}$$

$$= \frac{3 + \sqrt{\frac{824}{3}}}{20} = \frac{3 + \sqrt{2481}}{20} = \frac{9 + \sqrt{2481}}{60}$$

c) $x_1 = \begin{pmatrix} \vdots \\ \vdots \end{pmatrix}$; $x_2 = \begin{pmatrix} \vdots \\ \vdots \end{pmatrix}$ \Rightarrow follows:

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$$\begin{bmatrix} 0.981 - 0.300 & -0.333 \\ -2 & 0.981 \end{bmatrix} \begin{bmatrix} a \\ b \end{bmatrix} = \begin{bmatrix} 0.648 & -0.333 \\ -2 & 0.981 \end{bmatrix} \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$\Rightarrow \begin{bmatrix} 0.681 & -0.333 \\ 0 & 0 \end{bmatrix} \cdot \text{If } x_1 = \begin{bmatrix} a \\ b \end{bmatrix} \Rightarrow$$

$$b = t \Rightarrow a = \frac{0.333}{0.681} t \Rightarrow x_1 = \begin{pmatrix} 0.381 \\ 2 \end{pmatrix} \quad t=2$$

In the same way: $x_2 = \begin{pmatrix} -0.680 \\ 2 \end{pmatrix}; P = [x_1 \ x_2]$.

c) $V_k = b_1 \lambda_1^k x_1 + b_2 \lambda_2^k x_2$, where

$$\begin{pmatrix} b_1 \\ b_2 \end{pmatrix} = (P^{-1} V_0) = \begin{bmatrix} 0.981 & -0.680 \\ 2 & 2 \end{bmatrix}^{-1} \begin{bmatrix} 100 \\ 50 \end{bmatrix} =$$

$$\frac{1}{2(0.981) + 2(0.680)} \begin{bmatrix} 2 & 0.680 \\ -2 & 0.981 \end{bmatrix} \begin{bmatrix} 100 \\ 50 \end{bmatrix} =$$

$$= \begin{pmatrix} 70.439 \\ -45.439 \end{pmatrix}$$

Just plug in now in

d) We need V_5 , so by above...

$$V_5 = \begin{pmatrix} 58.288 \\ 141.21 \end{pmatrix}$$

ⓔ $\lambda_1 = 0.981$ is dominant

Ⓞ

$$f) \quad V_k \approx (70.439) (0.981)^k \begin{pmatrix} 0.981 \\ 2 \end{pmatrix}$$

$$g) \quad V_{10} \approx \begin{pmatrix} 57.039 \\ 116.29 \end{pmatrix} \leftarrow n_{10} \\ \leftarrow j_{10}$$

h) They OSIPPER by $\begin{pmatrix} -0.65317 \\ 1.9211 \end{pmatrix}$

i) pop. becomes extinct because the dominant eigenvalue $\lambda_1 < 1$

j) NO, it will be extinct for every initial pop.

k) $\frac{j_k}{n_k + j_k} = 0.671 \Rightarrow 67.1\%$ are juveniles.
