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§ 2.5 COMPLEX NUMBERS

Can we solve $x^2 + 1 = 0$? **IN** real #s (\mathbb{R}): NO!

Def Let i be a # (nonreal) s.t. $i^2 = -1$

A complex # is a # of the form: $z = \boxed{a+bi}$,
where a, b are real #s.

EXP: $3-i$; $4 + \frac{2}{9}i$, $\sqrt{2} + \sqrt{3}i$

NOTATION ①

def Given $z = a+bi$, a is called The Real part of z ,
 b is called the Imaginary part of z .

NOTE: Every real # is a complex #:

$$a \text{ in } \mathbb{R} \rightarrow a = a + 0 \cdot i$$

Def: 2 complex #s are equal if and only if they
have the same real and imaginary parts:

$$2+3i \neq -2+3i$$

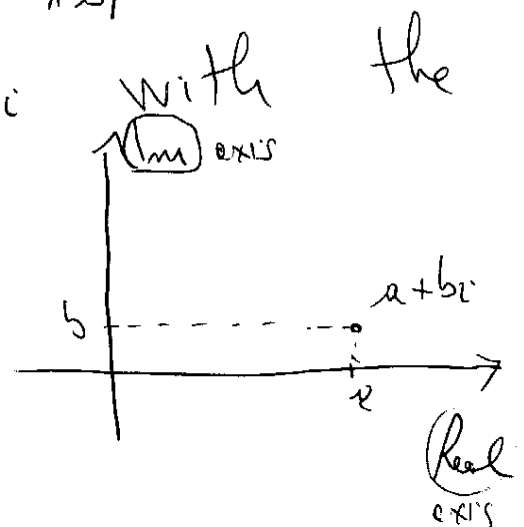
GEOMETRICAL DISPLAY (of complex #s)

We identify the complex # $z = a+bi$

point $P(a, b)$:

→ DRAW $\boxed{-1-i}$

Def The plane is called the
COMPLEX PLANE



OPERATIONS: • $z = a+bi$; $w = c+di$

Addition (+) $z+w = (a+c) + (b+d)i$

Multiplication (\cdot) $zw = (ac-bd) + (ad+bc)i$ (Use $i^2 = -1$)

EXP: $(3-7i) + (-1+9i) = 2 + 2i$
 $(3-7i)(-1+9i) = (-3+63) + (27+7)i = 60 + 34i$

Def • If $z = a+bi$ is a complex #, the conjugate of z , denoted \bar{z} , is given by $\bar{z} = a-bi$.

EXP: $\overline{-3-2i} = -3+2i$; $\overline{4} = 4$

PROPERTIES:
$$\begin{cases} \overline{z \pm w} = \bar{z} \pm \bar{w} \\ \overline{z\bar{w}} = \bar{z}w \\ \overline{\bar{z}} = z \\ z \text{ is real} \iff z = \bar{z} \end{cases} \quad \leftarrow \text{TRY IT!}$$

Def: If $z = a+bi$ is a complex # (in \mathbb{C}) then the absolute value of z , denoted $|z|$, is the positive or zero real #: $\sqrt{a^2+b^2}$.

NOTE: $|z|^2 = z \cdot \bar{z} = \sqrt{a^2+b^2}$

PROPERTIES:
$$\begin{cases} |z| \geq 0 \\ |z| = 0 \iff z = 0 \\ |zw| = |z| \cdot |w| \end{cases}$$

DIVISION (\div) if $z \neq 0$, then $\frac{1}{z} = z^{-1} = \frac{\bar{z}}{|z|^2}$

EXP: Find $\frac{4-3i}{3+5i}$

SOL:
$$\frac{4-3i}{3+5i} = \frac{4-3i}{3+5i} \cdot \frac{3-5i}{3-5i} = \frac{(12-15) + (-20-9)i}{34}$$

$$= -\frac{3}{34} + \left(-\frac{29}{34}\right)i.$$

QUADRATICS / ROOTS SOLVE $ax^2+bx+c=0$; $a \neq 0$

SOL:
$$x_{1,2} = \frac{-b \pm \sqrt{b^2 - 4ac}}{2a}$$

1^o) $b^2 - 4ac > 0 \rightarrow$ 2 distinct roots

2^o) $b^2 - 4ac = 0 \rightarrow$ one (repeated) root

3^o) $b^2 - 4ac < 0 \rightarrow$ 2 conjugated complex #s as roots

EXP: SOLVE: $x^2 + x + 100 = 0$

SOL:
$$x_{1,2} = \frac{-1 \pm \sqrt{1-400}}{2} \Rightarrow \begin{cases} x_1 = \frac{-1 - \sqrt{-399}}{2} \\ x_2 = \frac{-1 + \sqrt{-399}}{2} \end{cases}$$

$$\Rightarrow \begin{cases} x_1 = -1/2 - \frac{i\sqrt{399}}{2} \\ x_2 = -1/2 + \frac{i\sqrt{399}}{2} \end{cases}$$

IN CASE 3^o) the quadratic is called irreducible.

EXP: If $z = 7-i$, find an irreducible quadratic with z as a root.

SOL: $(x - (7-i))(x - (7+i)) = \dots$ since $(7+i)$ is also a root!!

FUNDAMENTAL Theorem of ALGEBRA

(T) Every complex polynomial $f(x)$ of degree $n \geq 1$ has the form: $f(x) = u \cdot (x - \lambda_1)(x - \lambda_2) \dots (x - \lambda_n)$ for some complex #s: $\lambda_1, \lambda_2, \dots, \lambda_n \rightarrow$ the roots of $f(x)$; $u \neq 0$ is the coeff of x^n in $f(x)$.

EXC: 5 a) 11g

3-e) 11g $(a+bi)(1+i) = a-bi - 3-2i \Rightarrow z = \dots$

7/11g (T/F) a) T ; b) F $z=i$ c) (T) ; d) $z = \frac{1}{2} + i\frac{\sqrt{3}}{2}$
 $w=1$

e) $|1+0 \cdot i| = |0+1 \cdot i|$, but $1 \neq i$: (F)

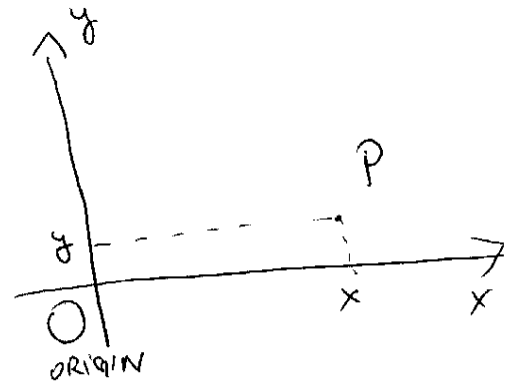
f) $a-bi = -a-bi \Rightarrow a=0$ (T)

CH:3 VECTOR GEOMETRY

§3.1 Geometric vectors

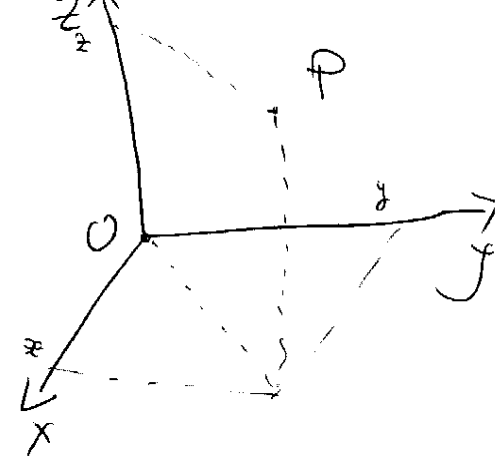
a) The plane $\left\{ \begin{array}{l} \text{origin} \\ 2 \text{ perpendicular axes} \\ \text{scale} \end{array} \right.$

Each point P determines a unique pair (x,y) of #s, called the coordinates; We write $P(x,y)$



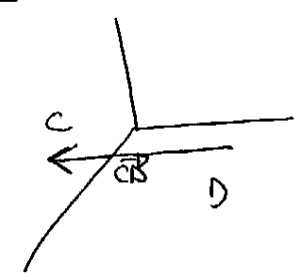
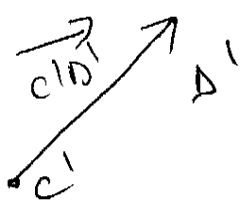
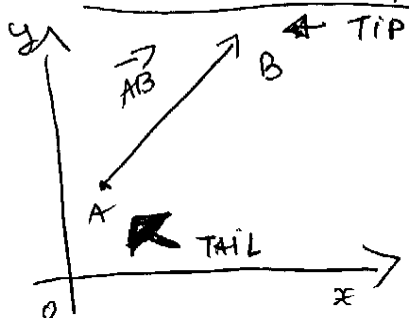
- b) The Space
- origin
 - 3 mutually \perp axes
 - scale

Each point P determines a unique triple (x, y, z) of #s, the coordinates of P ; we write $P(x, y, z)$.



VECTORS \equiv arising from Geometry

Def if A, B are 2 points (in plane/space), the directed segment from A to B is called the vector from A to B , denoted \vec{AB} .

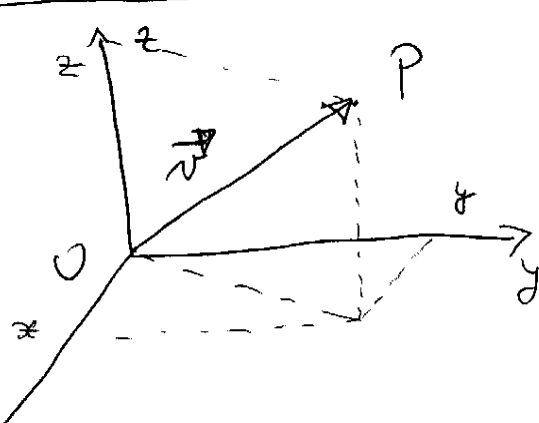


Def: 2 vectors are equal if they have the same length and the same direction

EXP: So $\vec{AB} = \vec{CD'}$ is denoted $\|\vec{AB}\|$.

Def The length of \vec{AB} is denoted $\|\vec{AB}\|$.

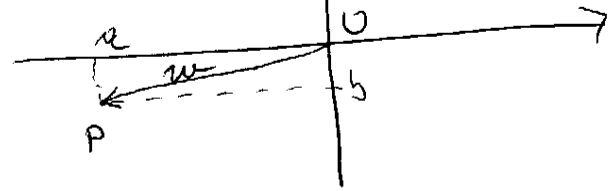
Def A vector \vec{v} is in STANDARD POSITION if its TAIL is in the origin.



P is determined by x, y, z ; we may write: $\vec{v} = \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \vec{OP}$

- IT IS called matrix form -

In plane: $\vec{OP} = \vec{w} = \begin{bmatrix} a \\ b \end{bmatrix}$.



OPERATIONS:

(+) Addition $\vec{v} + \vec{w} = \begin{pmatrix} x \\ y \\ z \end{pmatrix} + \begin{pmatrix} x' \\ y' \\ z' \end{pmatrix} = \begin{pmatrix} x+x' \\ y+y' \\ z+z' \end{pmatrix}$

• (scalar multiplication) $k\vec{v} = k \begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} kx \\ ky \\ kz \end{pmatrix}$

• The zero vector: $\vec{0} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$

• The negative $-\vec{v} = - \begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} -x \\ -y \\ -z \end{pmatrix}$

PROPERTIES:

$$\begin{cases} \vec{u} + \vec{v} = \vec{v} + \vec{u} \\ (\vec{u} + \vec{v}) + \vec{w} = \vec{u} + (\vec{v} + \vec{w}) \\ \vec{0} + \vec{v} = \vec{v} \\ \vec{v} + (-\vec{v}) = \vec{0} \end{cases} \quad (a, b = \neq 0)$$

$$\begin{aligned} (a+b)\vec{v} &= a\vec{v} + b\vec{v} \\ a(\vec{u} + \vec{v}) &= a\vec{u} + a\vec{v} \\ (ab)\vec{u} &= a(b\vec{u}) \\ 1 \cdot \vec{v} &= \vec{v} \end{aligned}$$

(T) Let $\vec{v} = \begin{pmatrix} x \\ y \\ z \end{pmatrix}$; $\vec{w} = \begin{pmatrix} x_1 \\ y_1 \\ z_1 \end{pmatrix}$ be vectors.

(1) $\vec{v} = \vec{w}$ iff $x = x_1, y = y_1, z = z_1$

(2) $\|\vec{v}\| = \sqrt{x^2 + y^2 + z^2}$

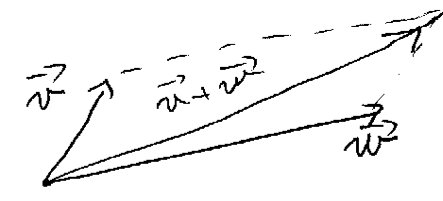
(3) $\vec{v} = \vec{0} \iff \|\vec{v}\| = 0$

(4) $\|a\vec{v}\| = |a| \cdot \|\vec{v}\|$; a scalar ($\neq 1$)

NOTE: If \vec{v} is a vector, $-\vec{v}$ has the same length but opposite direction.

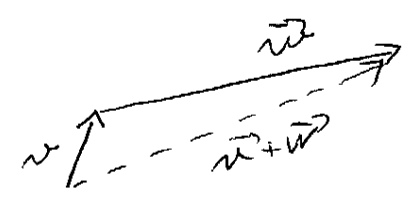
Vector Addition

• Parallelogram LAW

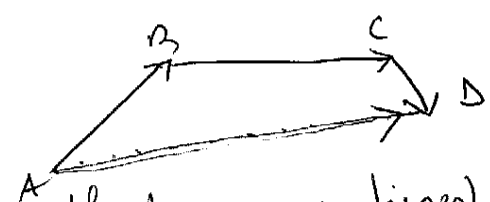


OR

• TIP-TO-TAIL Method:



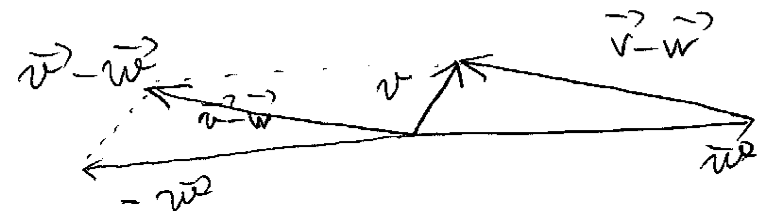
IMPORTANT NOTE:



$$\vec{AB} + \vec{BC} + \vec{CD} = \vec{AD}$$

(use the law/method many times)

Difference:



THM

Let $P_1(x_1, y_1, z_1)$; $P_2(x_2, y_2, z_2)$ be 2 points. Then:

(1) $\vec{P_1P_2} = \begin{bmatrix} x_2 - x_1 \\ y_2 - y_1 \\ z_2 - z_1 \end{bmatrix}$; (2) $d(P_1, P_2) = \sqrt{(x_2 - x_1)^2 + (y_2 - y_1)^2 + (z_2 - z_1)^2}$
(PyT's thm.)

(In plane: (1) $\vec{P_1P_2} = \begin{bmatrix} x_2 - x_1 \\ y_2 - y_1 \end{bmatrix}$; $d(P_1, P_2) = \sqrt{(x_2 - x_1)^2 + (y_2 - y_1)^2}$
where $P_1(x_1, y_1)$; $P_2(x_2, y_2)$

Def:

Two non-zero vectors are parallel if they have the same or opposite direction

THM

Let \vec{v}, \vec{w} be 2 nonzero vectors.

IFSAE:

(1) \vec{v}, \vec{w} are parallel; (2) one of \vec{v}, \vec{w} is a

sc. multiple of the other.

Do:

11/141

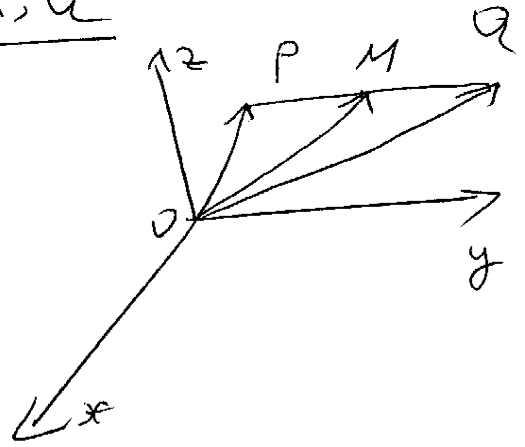
§ MID POINT between 2 points P, Q

$$\vec{OM} = \frac{1}{2} (\vec{OP} + \vec{OQ})$$

half of the diagonal

Do:

10/141 c) (NOT)

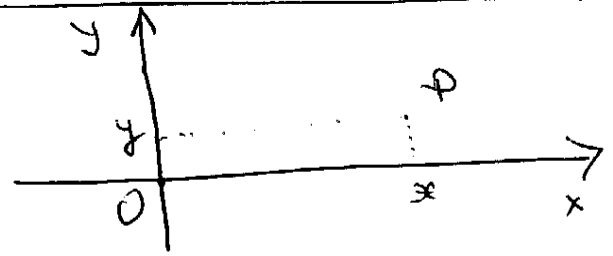


CH3 VECTOR GEOMETRY

§3.1 Geometric Vectors

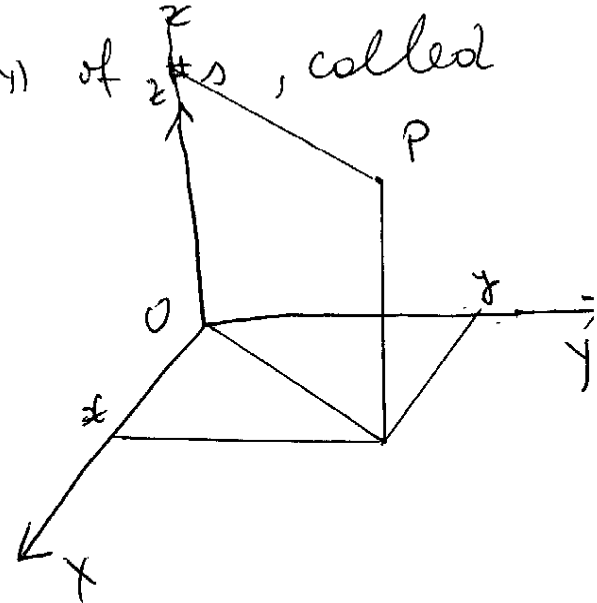
a) THE PLANE $\left\{ \begin{array}{l} \text{ORIGIN} \\ 2 \text{ perpendicular axes} \\ \text{scale} \end{array} \right.$

Each point P determines a pair (x,y) of #'s, called the coordinates; we write P(x,y).



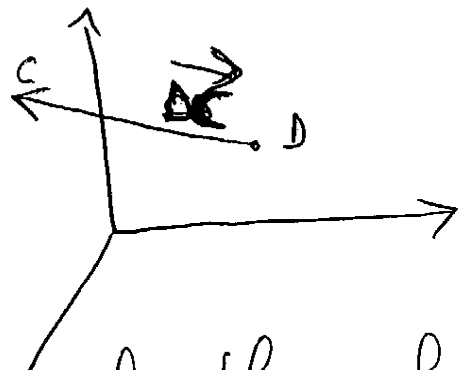
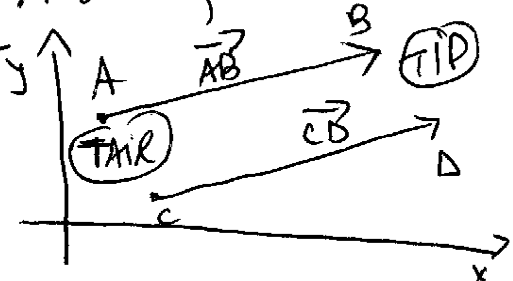
b) THE SPACE $\left\{ \begin{array}{l} \text{ORIGIN} \\ 3 \text{ mutually } \perp \text{ axes} \\ \text{scale} \end{array} \right.$

Each point P determines a triple (x,y,z) of #'s, the coordinates of P. We write P(x,y,z)



Vectors (arising from geometry)

Def if A, B are 2 points (plane/space), the directed segment from A to B is called the vector from A to B, denoted \vec{AB} .



Def(=) 2 vectors are equal if they have the same length and direction.

Exp: $\vec{AB} = c \vec{D}$

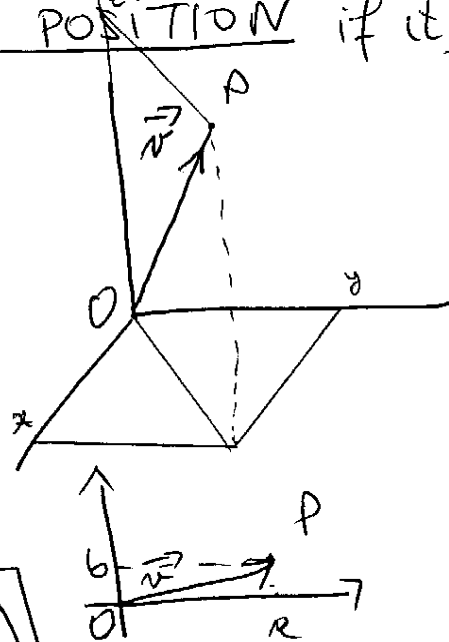
Def (||-||) The length of \vec{AB} is denoted by $\|\vec{AB}\|$.

Def^o: A vector \vec{v} is in STANDARD POSITION if its TAIL is in the origin:

$$\vec{v} = \vec{OP}$$

P is determined by x, y, z ; we may write $\vec{v} = \vec{OP} = \begin{bmatrix} x \\ y \\ z \end{bmatrix}$ (mx. notation)

(In plane $\vec{v} = \vec{OP} = \begin{bmatrix} a \\ b \end{bmatrix}$, where



OPERATIONS

$$+ : \vec{v} + \vec{w} = \begin{pmatrix} x \\ y \\ z \end{pmatrix} + \begin{pmatrix} x' \\ y' \\ z' \end{pmatrix} = \begin{pmatrix} x+x' \\ y+y' \\ z+z' \end{pmatrix}$$

$$\cdot : k\vec{v} = k \begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} kx \\ ky \\ kz \end{pmatrix}$$

$$\vec{0} : \vec{0} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix} \rightarrow \text{the zero vector}$$

$$\text{negative } \vec{v} : -\vec{v} = \begin{pmatrix} -x \\ -y \\ -z \end{pmatrix}$$

PROPERTIES:

$$\vec{v} + \vec{w} = \vec{w} + \vec{v}; \quad (\vec{v} + \vec{w}) + \vec{u} = \vec{v} + (\vec{w} + \vec{u});$$

$$\vec{0} + \vec{v} = \vec{v}; \quad \vec{v} + (-\vec{v}) = \vec{0}; \quad (a+b)\vec{v} = a\vec{v} + b\vec{v};$$

$$a(\vec{v} + \vec{w}) = a\vec{v} + a\vec{w}; \quad (ab)\vec{v} = a(b\vec{v}); \quad 1\vec{v} = \vec{v}$$

(T) Let $\vec{v} = \begin{pmatrix} x \\ y \\ z \end{pmatrix}$, $\vec{w} = \begin{pmatrix} x' \\ y' \\ z' \end{pmatrix}$. THEN^o

$$(1) \vec{v} = \vec{w} \Leftrightarrow x = x'; y = y'; z = z'$$

$$(2) \|\vec{v}\| = \sqrt{x^2 + y^2 + z^2}$$

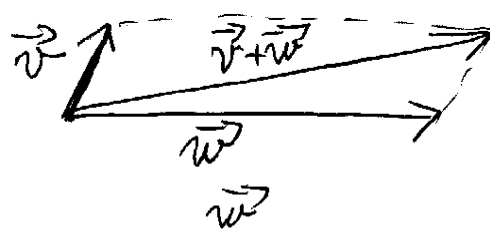
$$(3) \vec{v} = \vec{0} \Leftrightarrow \|\vec{v}\| = 0$$

$$(4) \|a\vec{v}\| = |a| \cdot \|\vec{v}\|; a \neq 0$$

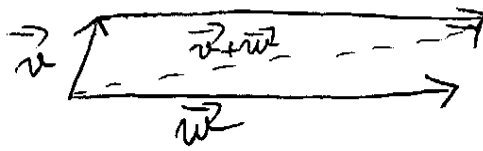
NOTE: Given \vec{v} (a vector), $-\vec{v}$ has the same length, but opposite direction

VECTOR ADDITION

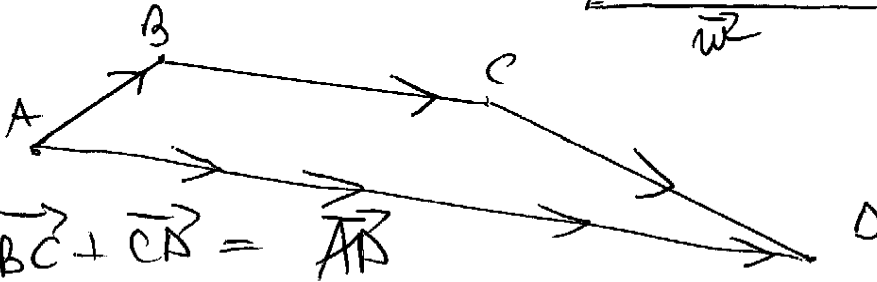
PARALLELOGRAM LAW



TIP-to-TAIL method:

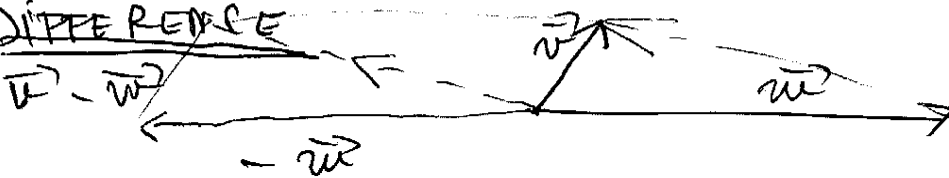


MORE:



$$\vec{AB} + \vec{BC} + \vec{CD} = \vec{AD}$$

DIFFERENCE



TH Let $P_1(x_1, y_1, z_1)$, $P_2(x_2, y_2, z_2)$ be 2 points. THEN:

(1) $\vec{P_1P_2} = \begin{bmatrix} x_2 - x_1 \\ y_2 - y_1 \\ z_2 - z_1 \end{bmatrix}$; (2) $d(P_1, P_2) = \sqrt{(x_2 - x_1)^2 + (y_2 - y_1)^2 + (z_2 - z_1)^2}$

In plane: $\vec{P_1P_2} = \begin{bmatrix} x_2 - x_1 \\ y_2 - y_1 \end{bmatrix}$; $d(P_1, P_2) = \sqrt{(x_2 - x_1)^2 + (y_2 - y_1)^2}$
 for $P_1(x_1, y_1)$, $P_2(x_2, y_2)$.

DEF: II TWO NON-ZERO vectors are parallel if they have the same or opposite direction

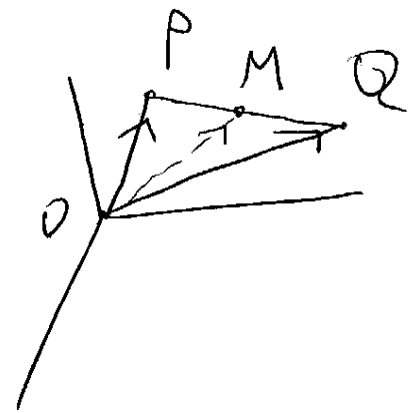
THM II Let \vec{v}, \vec{w} be 2 vectors (non zero)
TFAE:

- (1) \vec{v}, \vec{w} are parallel
- (2) one of \vec{v}, \vec{w} is a scalar multiple of the other.

DO: 11/141

MIDPOINT between 2 points P, Q

$$\vec{OM} = \frac{1}{2}(\vec{OP} + \vec{OQ})$$



DO: 10/141 c) NOT

§ 3.2

DOT PRODUCT and PROJECTIONS

Def: • if $\vec{v} = \begin{pmatrix} x \\ y \\ z \end{pmatrix}$, $\vec{w} = \begin{pmatrix} x' \\ y' \\ z' \end{pmatrix}$ then $\vec{v} \cdot \vec{w} =$

$$= xx' + yy' + zz'$$

$$\bullet \text{ If } \vec{v} = \begin{pmatrix} x \\ y \end{pmatrix}, \vec{w} = \begin{pmatrix} x' \\ y' \end{pmatrix} \Rightarrow \vec{v} \cdot \vec{w} = xx' + yy'$$

EXP: $\begin{pmatrix} -1 \\ 2 \end{pmatrix} \cdot \begin{pmatrix} 3 \\ -1 \\ 0 \end{pmatrix} = 3 + 1 + 0 = 4$

PROPERTIES: (1) $\vec{v} \cdot \vec{w} = \vec{w} \cdot \vec{v}$; (2) $\vec{v} \cdot \vec{w}$ is \mathbb{R} ; (3) $\vec{v} \cdot \vec{0} = 0$

(4) $\vec{v} \cdot \vec{v} = \|\vec{v}\|^2$ (5) $(r\vec{v}) \cdot \vec{w} = r(\vec{v} \cdot \vec{w}) = \vec{v} \cdot (r\vec{w})$

(6) $\vec{v} \cdot (\vec{u} \pm \vec{w}) = \vec{v} \cdot \vec{u} \pm \vec{v} \cdot \vec{w}$

Angles (Def) The angle θ ($0 \leq \theta \leq \pi$) between 2 nonzero vectors \vec{u}, \vec{v} is satisfying:

$$\vec{u} \cdot \vec{v} = \|\vec{u}\| \cdot \|\vec{v}\| \cos \theta$$

EXP 4f/148 $\cos \theta = -\frac{1}{2} \Rightarrow \theta = \frac{2\pi}{3}$

4b/148 $\cos \theta = 0 \Rightarrow \theta = \frac{\pi}{2}$

Def:

$$\begin{cases} \vec{v} \cdot \vec{w} > 0 \Leftrightarrow \theta \text{ is acute} & (0 \leq \theta < \frac{\pi}{2}) \\ \vec{v} \cdot \vec{w} = 0 \Leftrightarrow \theta \text{ is right angle} & (\theta = \frac{\pi}{2}) \\ \vec{v} \cdot \vec{w} < 0 \Leftrightarrow \theta \text{ is obtuse} & (\frac{\pi}{2} < \theta \leq \pi) \end{cases}$$

when $\vec{v} \cdot \vec{w} = 0$ we say \vec{v}, \vec{w} are orthogonal (\perp)

DO: 7/148 $\vec{AB} = \begin{pmatrix} -1 \\ 4 \end{pmatrix}$; $\vec{CB} = \begin{pmatrix} 0 \\ 2 \\ -2 \end{pmatrix} \rightarrow \vec{AB} \cdot \vec{CB} = 0$
 $\rightarrow \vec{AB} \perp \vec{CB} \rightarrow$ Done

PROJECTIONS: Let $\vec{v}, \vec{d} \neq \vec{0}$ be vectors.

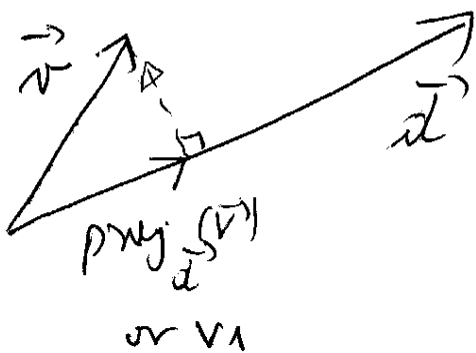
(1) The projection of \vec{v} onto \vec{d} is given by

$$\text{proj}_{\vec{d}}(\vec{v}) = \frac{\vec{v} \cdot \vec{d}}{\|\vec{d}\|^2} \cdot \vec{d}$$

(2) $\vec{v} - \text{proj}_{\vec{d}}(\vec{v}) \perp \vec{d}$

(3) \vec{v} can be written uniquely in the form:
 $\vec{v} = \vec{u}_1 + \vec{u}_2$ such that $\vec{u}_1 \parallel \vec{d}$
 $\vec{u}_2 \perp \vec{d}$

(In fact $\vec{u}_1 = \text{proj}_{\vec{d}}(\vec{v})$, $\vec{u}_2 = \vec{v} - \text{proj}_{\vec{d}}(\vec{v})$.)



DO: 10/148

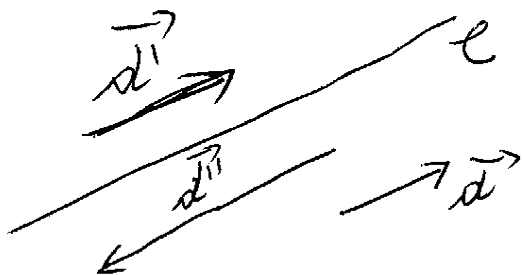
TO TRY:

10b/14g : c, f
19, 20

§ 3.3 LINES and PLANES

§ LINES

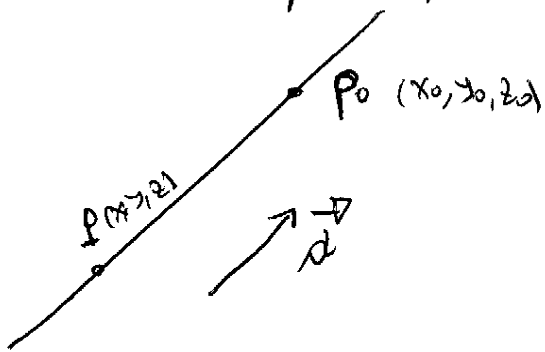
Def A direction vector of a line is a non-zero vector \vec{d} that is parallel to the line



DEF: • VECTOR EQ. of a line that has \vec{d} as a direction vector and is passing through \vec{p}_0 .

$$\vec{p} = \vec{p}_0 + t\vec{d}, \quad \text{t scalar}$$

$$\begin{cases} \vec{p} = \vec{OP} \\ \vec{p}_0 = \vec{OP}_0 \end{cases}$$



$$\vec{d} = \begin{bmatrix} a \\ b \\ c \end{bmatrix}$$

OR:
$$\begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} x_0 \\ y_0 \\ z_0 \end{pmatrix} + t \begin{pmatrix} a \\ b \\ c \end{pmatrix}$$

• SCALAR EQ. of a line (just multiply/identify)

$$\begin{cases} x = x_0 + ta \\ y = y_0 + tb \\ z = z_0 + tc \end{cases}$$

Read Δ Home :

152-153

all that examples